

Learning 3D Functionality Representations

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Speakers



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Learning 3D Functionality Representations

- What is this course about?
 - Cover recent developments that incorporate **functionality** considerations into **shape analysis** in **computer graphics**
 - For the analysis of **3D objects** and **scenes**
 - Discuss work **in learning 3D representations for functionality** and its connections to **deep learning, computer vision, and robotics**
 - Course targeted at **researchers** and **students**

Learning 3D Functionality Representations

- Differences to our SIGGRAPH Asia 2016 course on *Directions in Shape Analysis towards Functionality*:
 - We provide an **organizational framework** to classify prior work
 - We connect functionality to recent works **on learned 3D representations**, especially to connect it to deep learning, computer vision, and robotics



**SIGGRAPH
ASIA 2020
VIRTUAL**

Outline

- Introduction
 - Concept of functionality
 - Motivation: semantics versus functionality in shape analysis
 - Example applications

- Overview of the remaining sections of the course



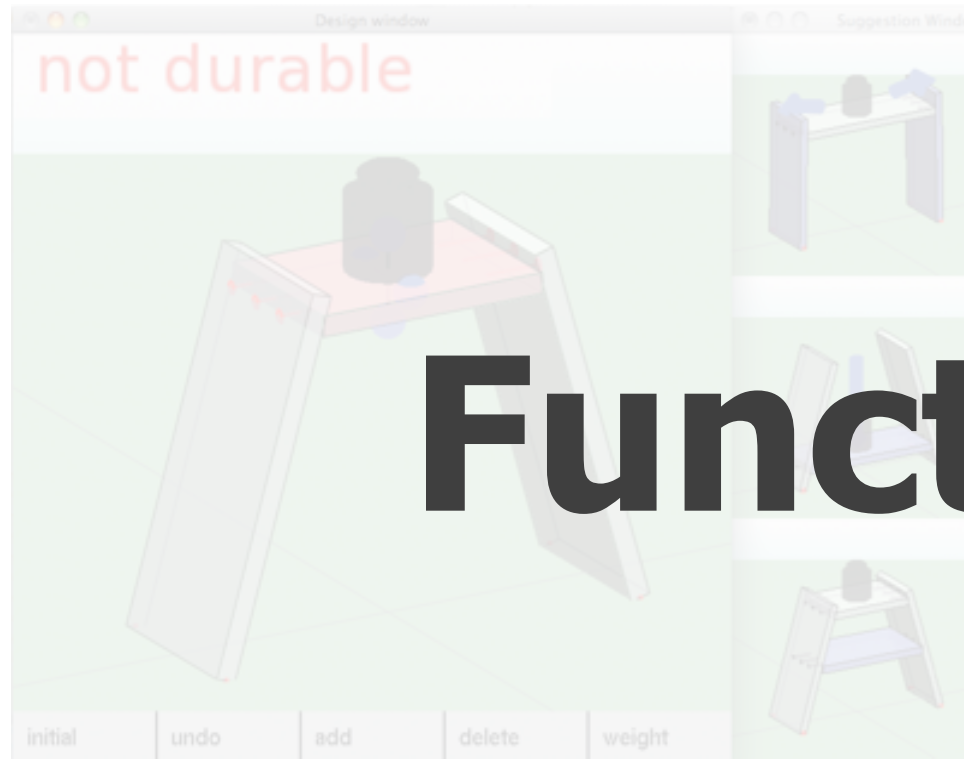
Course material

- The course material is available at our course Web page:

<https://learn3dfunc.github.io/>

Introduction





Furniture Design
[UIM12]



Motion simulation
[HLK*17]

Functionality

What is functionality?

- “The particular use for which an object is designed”

-- [Merriam-Webster dictionary]



What is functionality?

- “The application of an object in a specific context for the accomplishment of a particular purpose” [BB95]



Object recognition vs. functionality recognition



What is this? → **Chair**

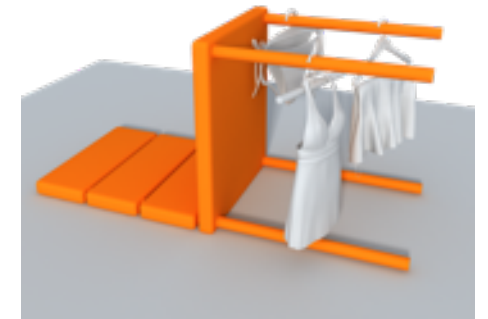
What can we do with this?



Chair



Handcart



Drying Rack



Object recognition vs. functionality recognition

- “The essential definition of object classes is functional”



Handcart



Table

Several approaches related to **shape understanding**

- Structure-aware shape processing
- Symmetry detection
- Data-driven shape analysis
- Generative models

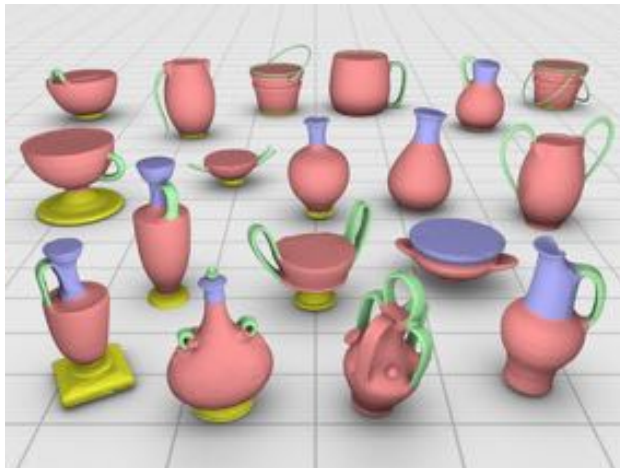
Methods covered in **previous** courses, tutorials, and STARs:

- Symmetry in 3D geometry: Extraction and applications [[MPWC12](#)]
- Structure-aware shape processing [[MWZ*13](#)]
- Data-driven shape analysis and processing [[XKHK17](#)]
- Modeling and remodeling 3D worlds [[YYAZ17](#)]
- Learning generative models of 3D structures [[CXRZ19](#)]

Shape analysis and semantics

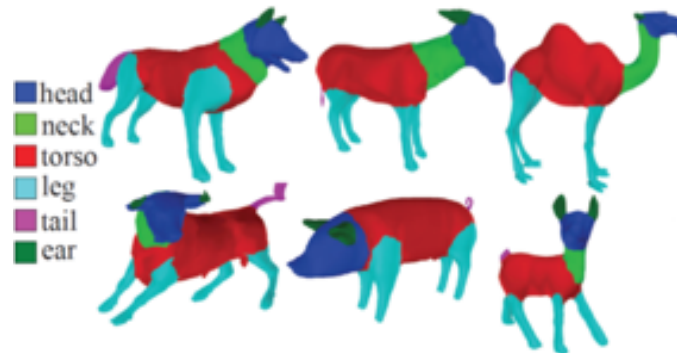
Three general **problems** related to **functionality** analysis:

Unsupervised segmentation



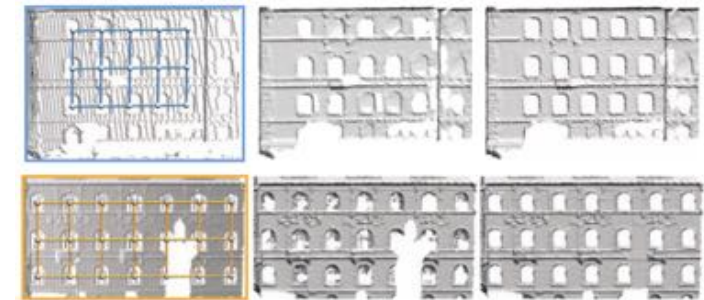
[SvKK*11]

Supervised segmentation



[KHS10]

Symmetry detection

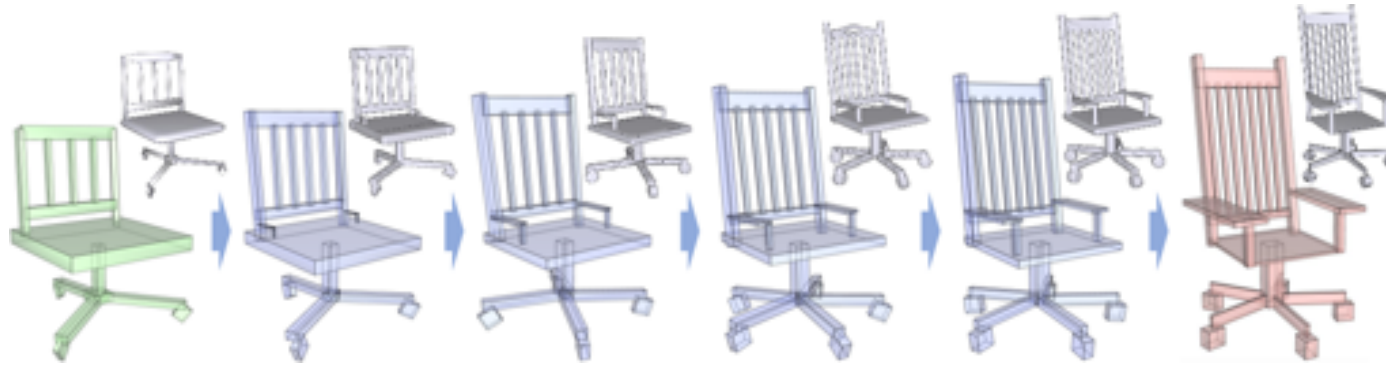


[PMW*08]

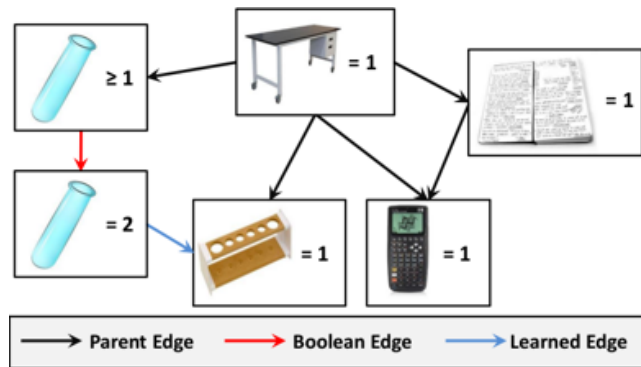
- Co-segmentation, symmetry analysis, and classification provide **part labels** and/or **correspondences** among shape **parts**
- Corresponding parts *likely* possess the same **functionality**
- There is some **relation** between **labels** and certain types of **functionality**, e.g., *chair seat* versus *sitting*
- Can constitute a **preliminary analysis** of functionality

- Difficult to infer the true **functional similarity**
- Analysis based only on **geometry** and **structural** similarity
- The **functionality** is not directly **named** or **categorized**

Learning generative models of 3D structures



[LXC*17]

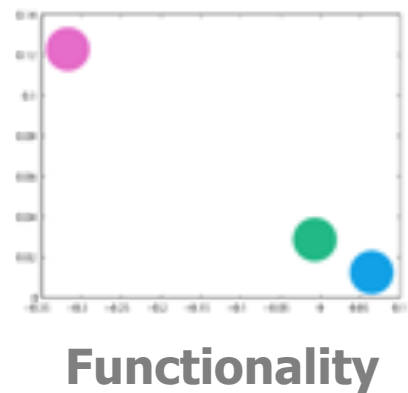
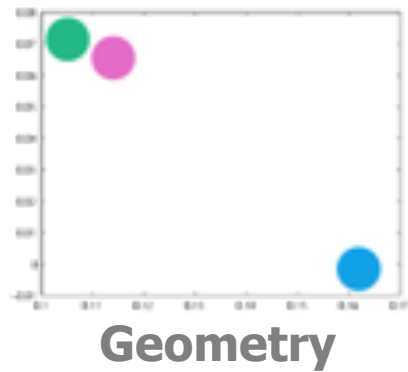


[FRS*12]

- Synthesis performed based on **geometric** and/or **structural** similarity of the shapes
- Synthesized shapes **resemble** exemplars in the training data
- Functionality preservation is **not** enforced nor guaranteed

Functionality vs. geometry

- Difference between “geometric appearance” and “functionality”



Challenges in functionality analysis

- Hard to handle large structural variations



Handcart



Table

Challenges in functionality analysis

- Hard to handle large **structural variations**
- Hard to establish the **connection** between **structure** and **functionality**



Modern chair by Valerie Everett



Halo modern chair by Michael Sodeau

- **Shape analysis can benefit from functionality**
 - Incorporate a model of shape functionality to analyze and process 3D objects and scenes
- **Why?**
 - Several applications motivate this goal...

Functionality-aware applications

- **Object and scene retrieval**
- Scene synthesis
- Modeling and editing
- ...



Object-in-scene retrieval
[HZvK*15]



Scene retrieval [SCH*14]

Functionality-aware applications

- Object and scene retrieval
- **Scene synthesis**
- Modeling and editing
- ...



Human interaction synthesis
[SCH*16]



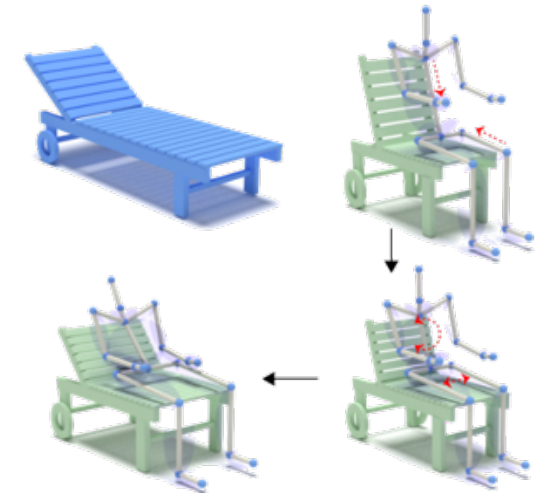
3D scene synthesis
[FSL*15]

Functionality-aware applications

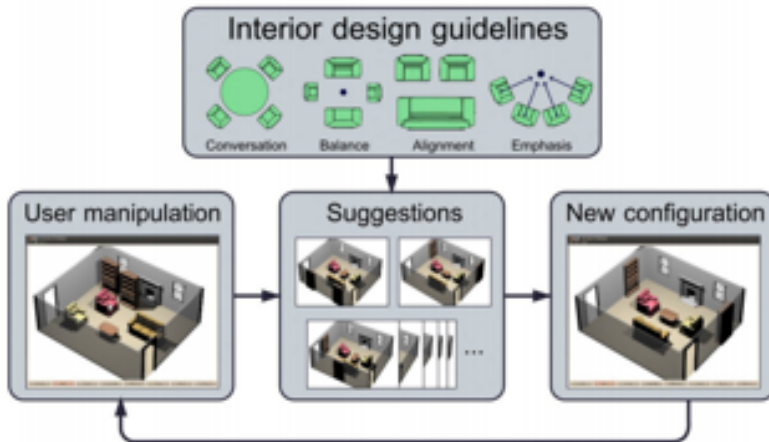
- Object and scene retrieval
- Scene synthesis
- **Modeling and editing**
- ...



Object hybrid
[HvKW*16]

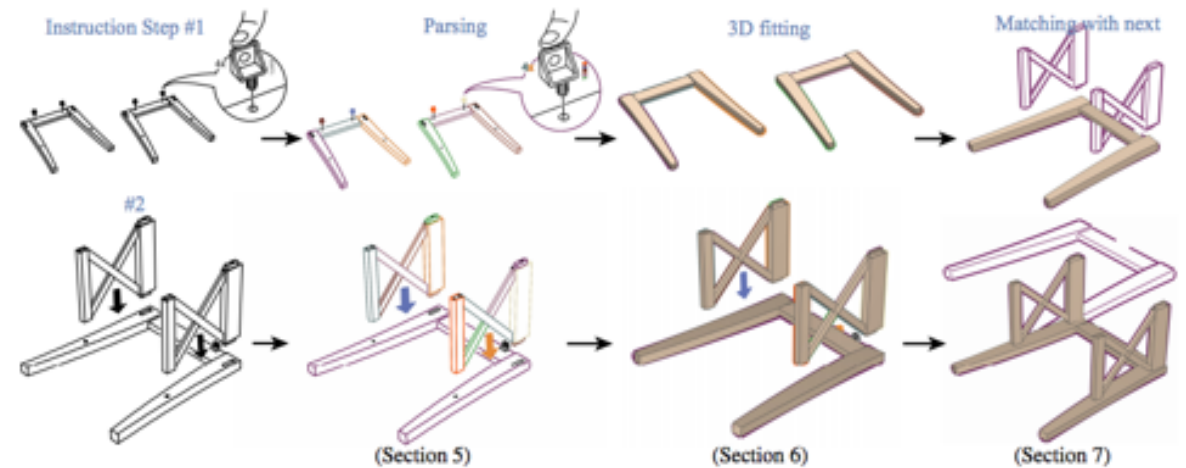


Object modeling
[ZLDM16]

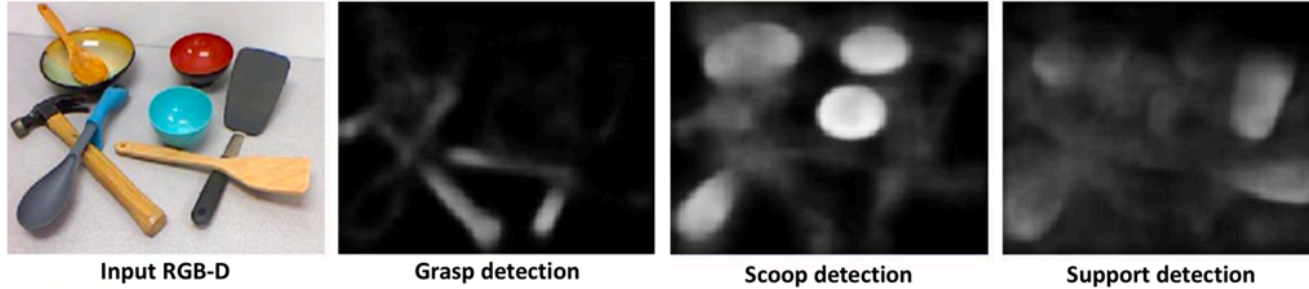


Scene editing
[MSL*11]

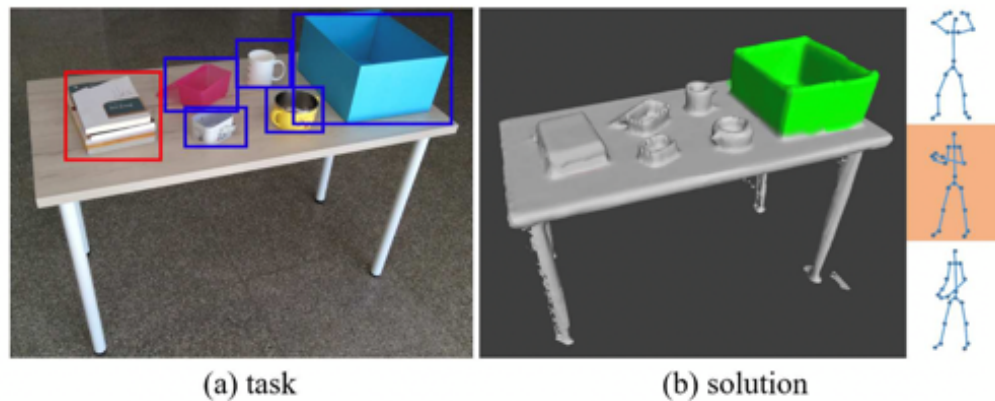
- Computer graphics is highly related to the virtual **prototyping** and mass **customization** revolution
- In **prototyping** and **customization**, an understanding of functionality is essential!
- A **fundamental problem**
- Still much to be done...



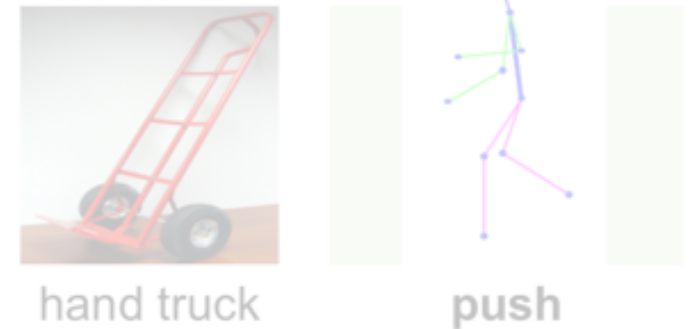
Functionality analysis in computer vision and robotics



Tool Affordance Detection [[MTFA15](#)]



Transferring Objects [[WLY17](#)]



Knowledge Base [[ZFFF14](#)]

What is this course about?

- The goal of this course
 - To provide a comprehensive survey of **functionality analysis** in **computer graphics** and related areas such as **computer vision**
- Audience
 - **Researchers** in graphics/vision
- Criteria
 - General **definition** of functionality

Research questions

- How to **represent** functionality?
- How to derive a functionality **model** from such representations?
- How to incorporate functionality models into **shape analysis** and **modeling**?
- How to **learn** such models?
- How to do all of this **efficiently**?
- ...

Research questions

- In this course, we will provide a sampler of different **solutions** to these **questions** as given by existing work
- For various **problem domains** and targeting **diverse applications**



Outline

- Our definition of functionality (Oliver)
- Classification of prior works (Ruizhen + Manolis)
- Functionality-aware applications + future directions (Manolis)

Definition of functionality and classification criteria



Definition of functionality

- **Functionality: use or purpose** of an object
- “Function is the action for which a person or thing is specially fitted or used, or for which a thing exists (purpose)” [[Merriam-Webster](#)]
- “Functionality is the application of an object in a specific context for the accomplishment of a particular purpose” [[BB95](#)]

Our definition of functionality

Goals:

- **Constructive definition** of functionality
- Serve as a **classification guide** for existing work
- Define the functionality of an **entity**

Our definition of functionality

We follow our definition proposed in the following paper:

- Ruizhen Hu, Manolis Savva, and Oliver van Kaick, **"Functionality Representations and Applications for Shape Analysis"**, *Computer Graphics Forum (Eurographics State-of-the-art report)*, vol. 37, n. 4, pp. 603-624, 2018.

Our definition of functionality

Functionality = Geometry + Interaction



Our definition of functionality

Functionality = **Geometry** + Interaction



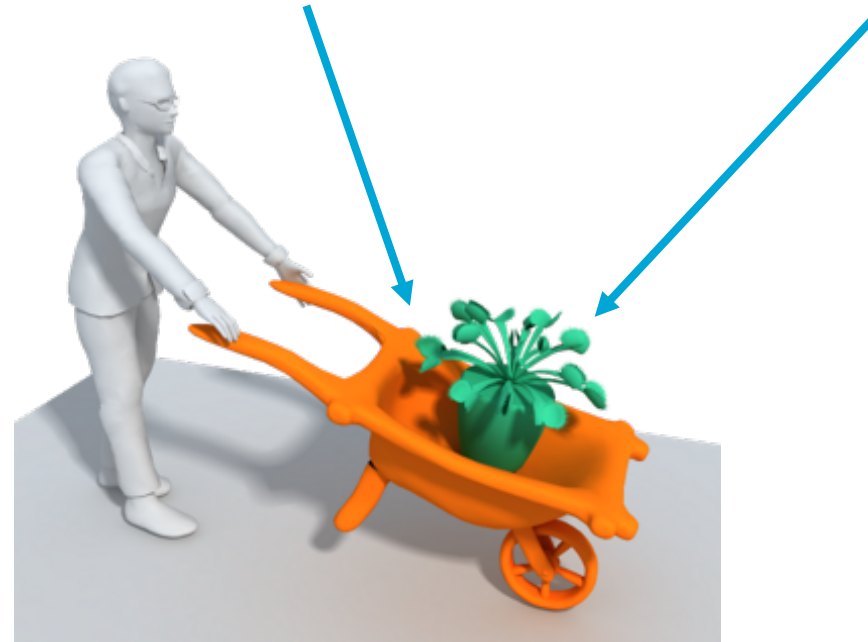
“Form follows function” [[Sul96](#)]

Our definition of functionality

Functionality = Geometry + **Interaction**

Atomic interaction:

<**Functional entity**, relation, **interacting entity**>

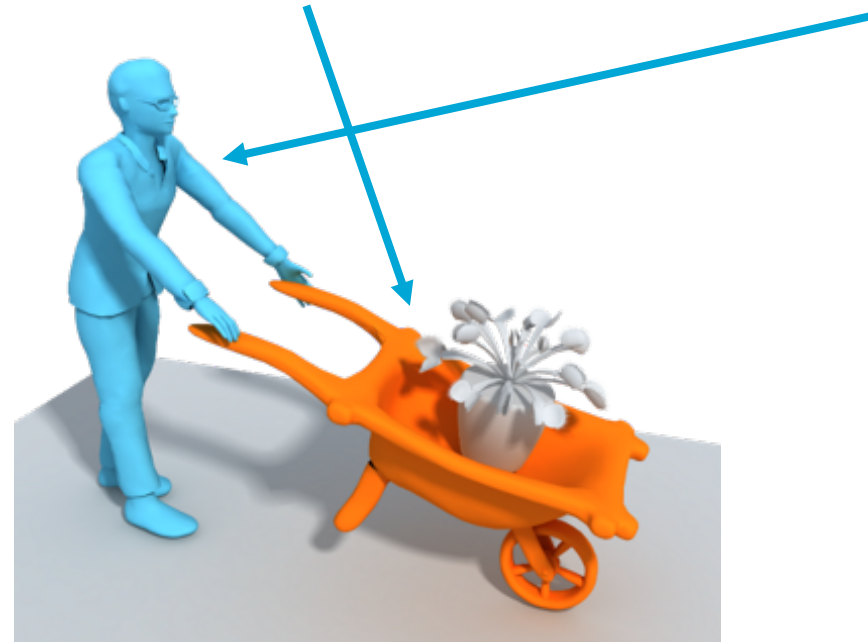


Our definition of functionality

Functionality = Geometry + **Interaction**

Atomic interaction:

<**Functional entity**, relation, **interacting entity**>



Components of atomic interactions

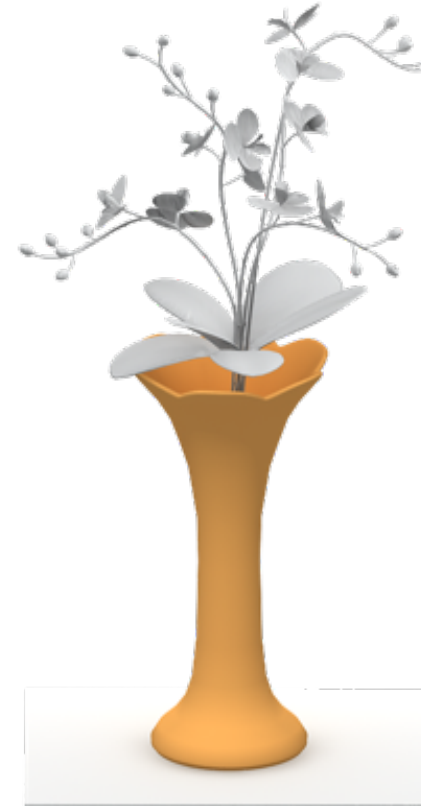
- Type of **entity**
- Level of **entity**
- Type of **relation**
- Representation of the **relation**

Type of entity

- Static entity
- Dynamic entity
- Human(-oid) agent

Type of entity

- **Static entity**
- Dynamic entity
- Human(-oid) agent



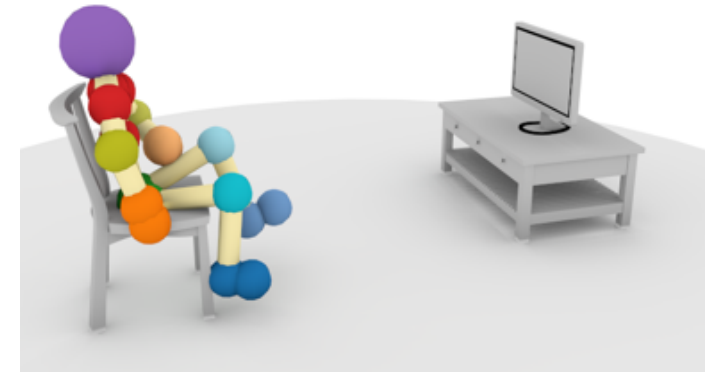
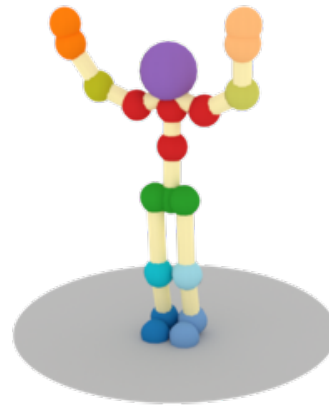
Type of entity

- Static entity
- **Dynamic entity**
- Human(-oid) agent



Type of entity

- Static entity
- Dynamic entity
- **Human(-oid) agent**



Level of entity



Scene



Multi-object

Type of relation

- Atemporal
- Time-varying

Type of relation

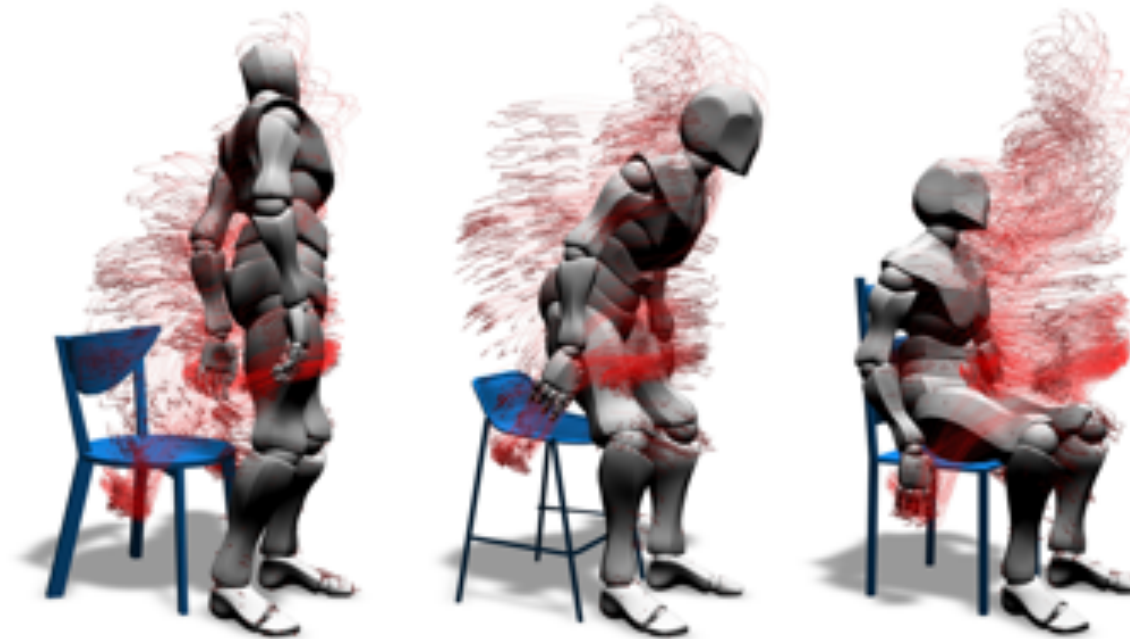
- **Atemporal**
- Time-varying



- ICON descriptor [[HZvK*15](#)]

Type of relation

- Atemporal
- **Time-varying**



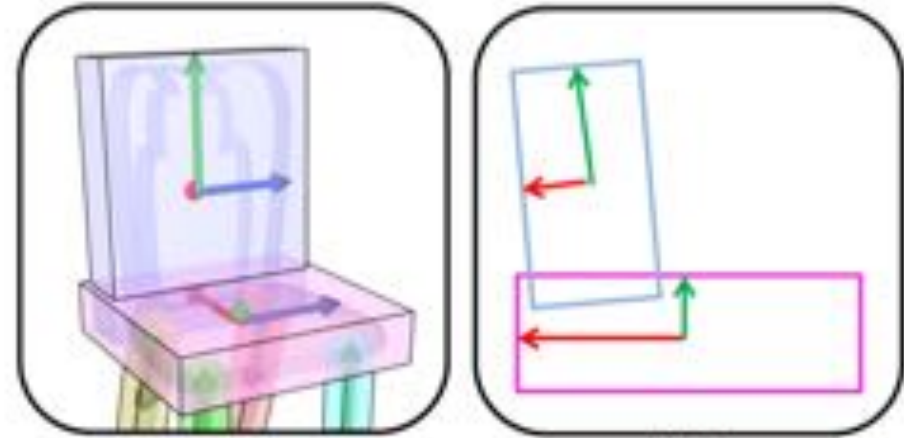
- Interaction landscapes [PKH*17]

Representation of the relation

- Spatial arrangement
- Boundary representation
- Dense volume feature
- Gestalt and symmetry grouping
- Mechanical relations
- Humanoid actions

Representation of the relation

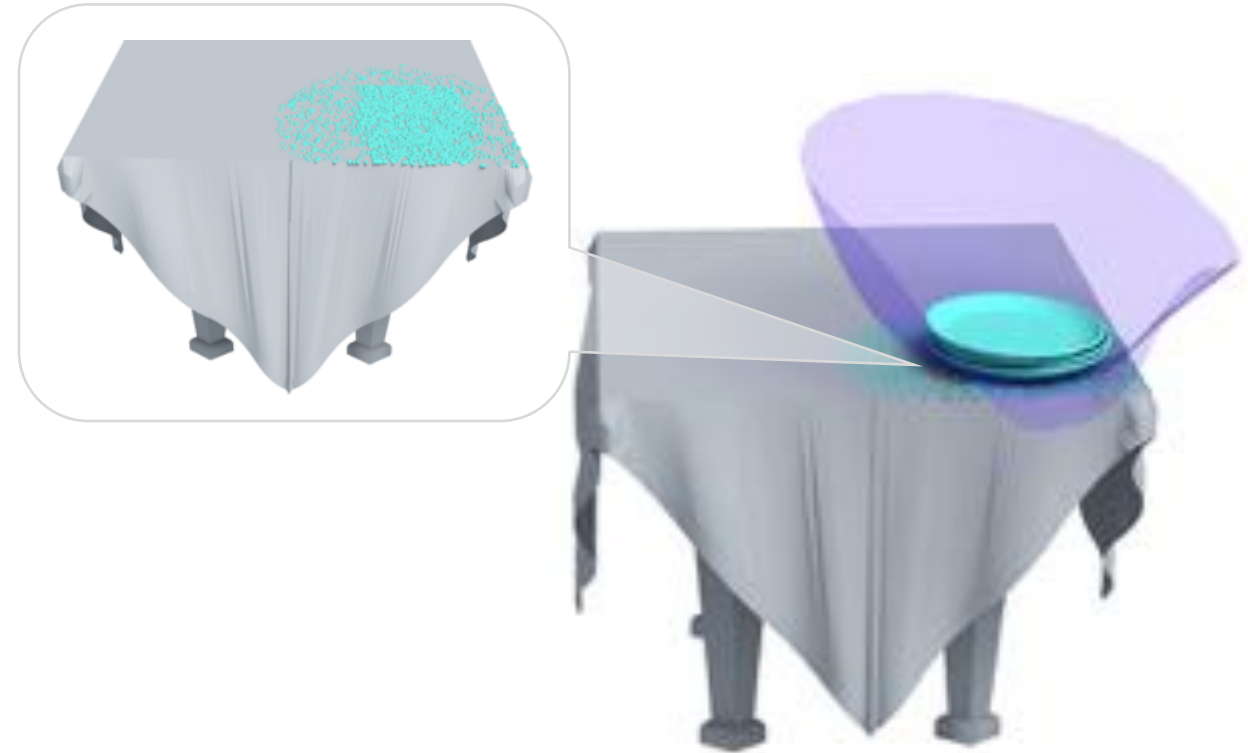
- **Spatial arrangement**
- Boundary representation
- Dense volume feature
- Gestalt and symmetry grouping
- Mechanical relations
- Humanoid actions



- Relative position
- Co-occurrence
- Gravitational support
- Attachment
- Enclosure
- RAID descriptor [GMW16]

Representation of the relation

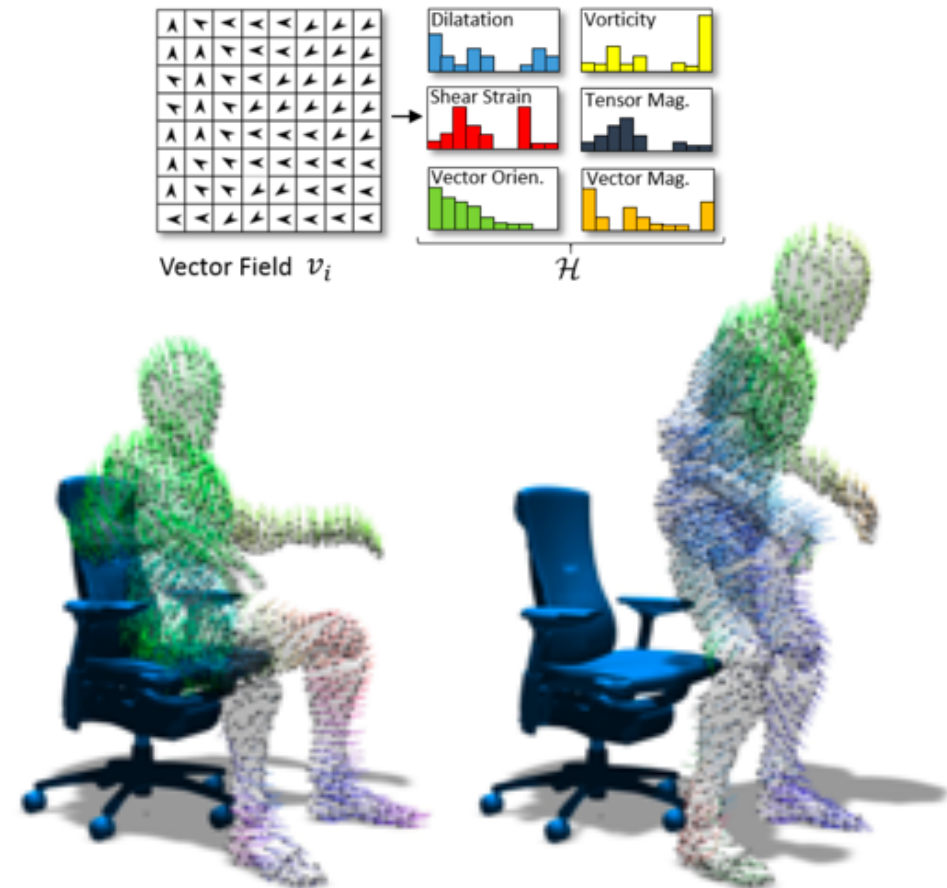
- Spatial arrangement
- **Boundary representation**
- Dense volume feature
- Gestalt and symmetry grouping
- Mechanical relations
- Humanoid actions



- Intersection bisector surface (IBS) [ZWK14]
- Interaction regions (IR) [HZvK*15]

Representation of the relation

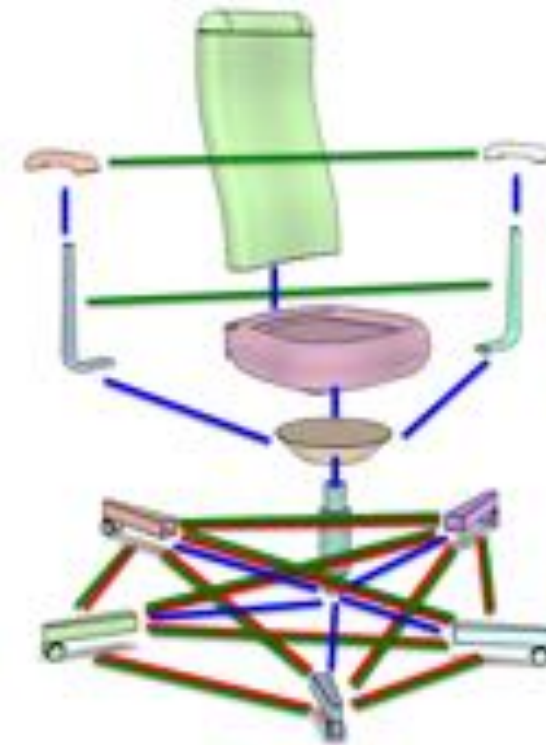
- Spatial arrangement
- Boundary representation
- **Dense volume feature**
- Gestalt and symmetry grouping
- Mechanical relations
- Humanoid actions



- Interaction landscapes [PKH*17]

Representation of the relation

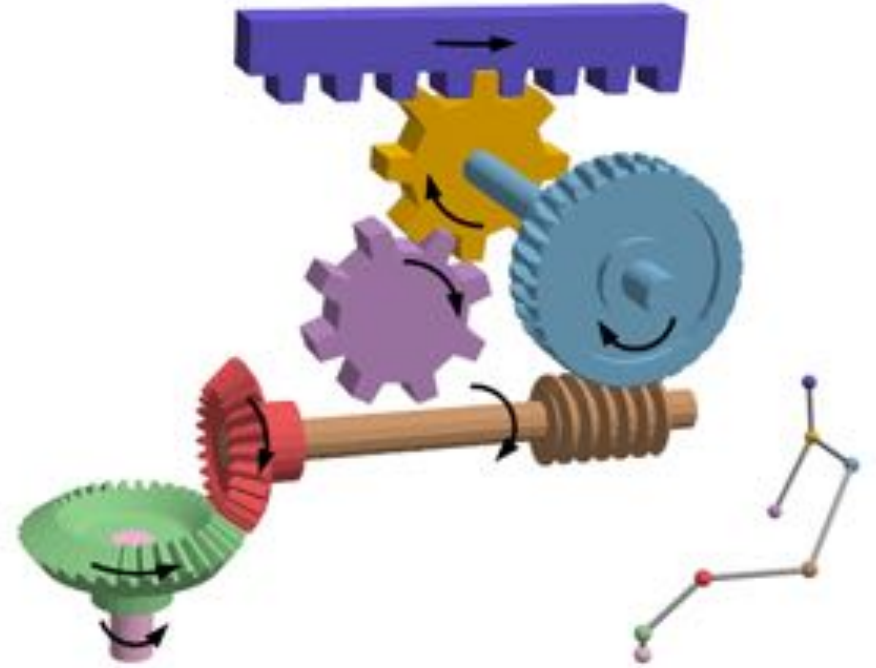
- Spatial arrangement
- Boundary representation
- Dense volume feature
- **Gestalt and symmetry grouping**
- Mechanical relations
- Humanoid actions



- Symmetry hierarchy [WXL*11]

Representation of the relation

- Spatial arrangement
- Boundary representation
- Dense volume feature
- Gestalt and symmetry grouping
- **Mechanical relations**
- Humanoid actions



- Force drivers, joints, and gears
[LOMI11, KLY*14, MYY*10, XLX*16]

Representation of the relation

- Spatial arrangement
- Boundary representation
- Dense volume feature
- Gestalt and symmetry grouping
- Mechanical relations
- **Humanoid actions**



- Gazing, grasping, holding, pushing, pulling, and sitting [SCH*14, FSL*15, SCH*16, MLZ*16]

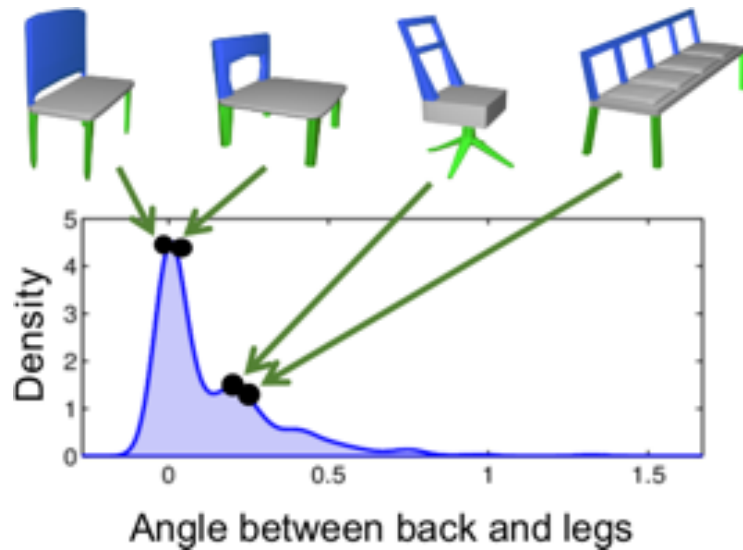


Representations of functionality

Functionality = Geometry + Interaction

Representations of functionality

Functionality = Geometry + Interaction ~~X~~
Geometry-only (G) methods

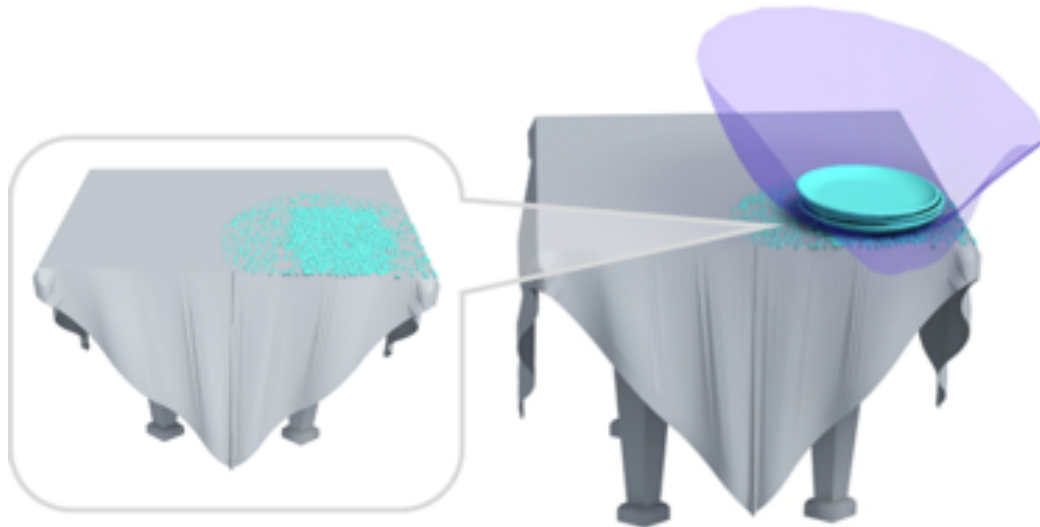


Meta-representation
of shape families
[FavK*14]

Representations of functionality

Functionality = Geometry + Interaction ✓

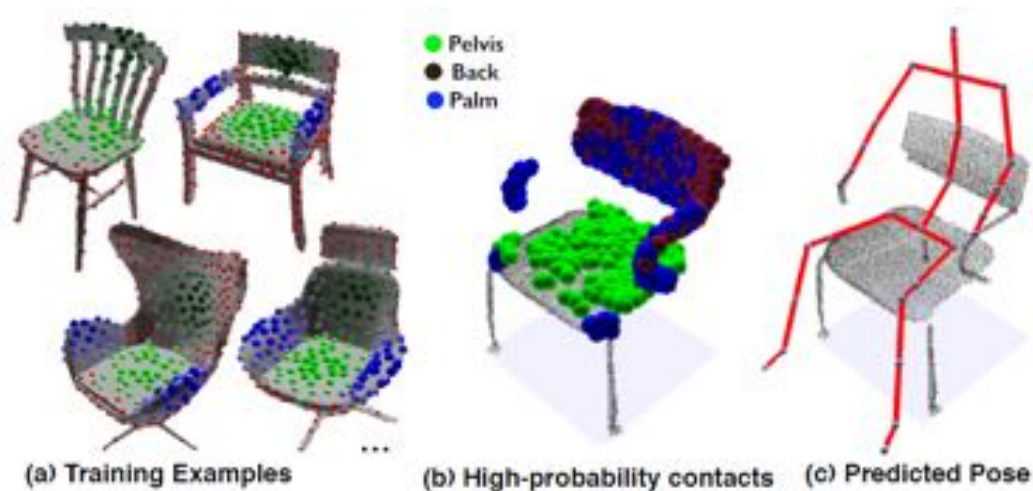
Geometry + interaction (GI) methods



Interaction context
(ICON) descriptor
[HZvK*15]

Representations of functionality

Functionality = Geometry + Interaction ✓
Geometry + agent (GA) methods



Shape2pose: Human-centric shape analysis [KCGF14]

Additional classification criteria

- **Model type:** discriminative or generative
- **Approach:** supervised, unsupervised, or handcrafted
- **Input data representation:** RGB-D image, point cloud, mesh

Classification criteria

Works	Functional entity	Representation of geometry or interactions			Additional classification criteria		
		Component / interacting entity	Dynamicity	Relations	Input	Approach	Model type
Geometry-only (G)							
Xu et al. [XSF02]	scene	object-geo	stat	SA	mesh	handcrafted	generative
Merrell et al. [MSL [*] 11]	scene	object-geo	stat	SA	mesh	handcrafted	generative
Yu et al. [YYT [*] 11]	scene	object-geo	stat	SA	mesh	supervised	generative
Fisher et al. [FSH11]	scene	object-geo	stat	SA	mesh	handcrafted	discriminative
Fisher et al. [FRS [*] 12]	multi-object	object-geo	stat	SA	mesh	supervised	generative
Zhao et al. [ZWK14]	multi-object	object-geo	stat	BR	pcl	handcrafted	discriminative
Zhao et al. [ZHG [*] 16]	multi-object	object-geo	stat	BR	mesh	supervised	generative
Zheng et al. [ZCOM13]	object	part-geo	stat	SG	mesh	handcrafted	generative
Mitra et al. [MY [*] 10]	object	part-geo	stat	SG	mesh	handcrafted	discriminative
Xu et al. [XLX [*] 16]	object	part-geo	stat	SG	rgbd	handcrafted	discriminative
Fish et al. [FAvK [*] 14]	object	part-geo	stat	SA	mesh	supervised	generative
Yumer et al. [YK14]	object	part-geo	stat	SA	mesh	supervised	generative
Pechuk et al. [PSR08]	part	part-geo	stat	SA	rgbd	supervised	discriminative
Gelfand et al. [GG04]	part	-	-	-	mesh	handcrafted	discriminative
Andries et al. [ADSV20]	object	-	stat	-	-	supervised	generative
Krs et al. [KMG [*] 20]	object	part-geo	stat	-	-	unsupervised	generative

Classification criteria

Works	Functional entity	Representation of geometry or interactions			Additional classification criteria		
		Component / interacting entity	Dynamicity	Relations	Input	Approach	Model type
Geometry+interaction (GI)							
Hu et al. [HZvK [*] 15]	object	stat-inter	stat	BR	pcl	handcrafted	discriminative
Hu et al. [HyKW [*] 16]	object	stat-inter	stat	BR	pcl	supervised	discriminative
Pirk et al. [PKH [*] 17]	object	dyn-inter	dyn	VF	mesh	handcrafted	discriminative
Myers et al. [MTFA15]	part	stat-inter	stat	SA	rgbd	supervised	discriminative
Kim et al. [KS14]	part	stat-inter	stat	SA	rgbd	supervised	discriminative
Laga et al. [LMS13]	part	stat-inter	stat	SA+SG	mesh	supervised	discriminative
Hu et al. [HLK [*] 17]	part	stat-inter	dyn	SA+BR	pcl	supervised	discriminative
Xiang et al. [XQM [*] 20]	part	stat-inter	dyn	SA	mesh	supervised	discriminative
Hu et al. [HYZ [*] 18]	object	stat-inter	stat	SA+BR	vol	supervised	generative
Yi et al. [YHL [*] 18]	part	stat-inter	dyn	SA	pcl	supervised	discriminative
Wang et al. [WZS [*] 19]	part	stat-inter	dyn	SA	pcl	supervised	discriminative
Yan et al. [YHY [*] 19]	part	stat-inter	dyn	SA	pcl	supervised	discriminative
Li et al. [LWY [*] 20]	part	stat-inter	dyn	SA	pcl	supervised	discriminative
Kokic et al. [KSHK17]	part	stat-inter	dyn	SA	pcl	supervised	generative
Li et al. [LSK20]	part	stat-inter	dyn	SA	pcl	supervised	generative

Classification criteria

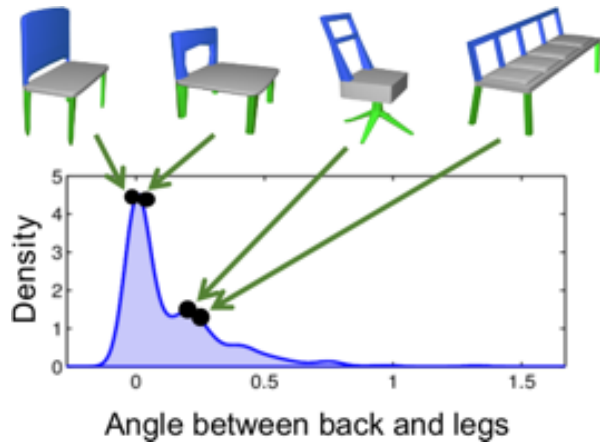
Works	Functional entity	Representation of geometry or interactions			Additional classification criteria		
		Component / interacting entity	Dynamicity	Relations	Input	Approach	Model type
Geometry+agent (GA)							
Grabner et al. [GGVG11]	scene	agent-inter	stat	HA	mesh	supervised	generative
Savva et al. [SCH ⁺ 14]	scene	agent-inter	stat	SA+HA	mesh	supervised	discriminative
Zhu et al. [ZJZ ⁺ 16]	scene	agent-inter	stat	SA	mesh	supervised	generative
Jiang et al. [JKS13]	multi-object	agent-inter	stat	SA	rgbd	supervised	discriminative
Wang et al. [WLY17]	multi-object	agent-inter	stat	SA+HA	mesh	supervised	discriminative
Fisher et al. [FSL ⁺ 15]	multi-object	agent-inter	stat	SA+HA	mesh	supervised	generative
Savva et al. [SCH ⁺ 16]	multi-object	agent-inter	stat	SA+HA	mesh	supervised	generative
Ma et al. [MLZ ⁺ 16]	multi-object	agent-inter	dyn	SA+HA	mesh	unsupervised	generative
Zheng et al. [ZLDM16]	object	agent-inter	stat	SA	mesh	handcrafted	generative
Kim et al. [KCGF14]	object	agent-inter	stat	SA	mesh	supervised	generative
Bar-Aviv & Rivlin [BAR06]	object	agent-inter	stat	SA+HA	mesh	handcrafted	discriminative
Zhu et al. [ZZCZ15]	object	agent-inter	dyn	SA+HA	rgbd	supervised	discriminative
Zhao et al. [ZCK17]	object	agent-inter	dyn	SA+HA	mesh	handcrafted	discriminative
Lee et al. [LCL06]	object	agent-inter	dyn	SA	mesh	supervised	generative
Li et al. [LLK ⁺ 19]	scene	agent-inter	stat	SA+HA	rgbd	supervised	generative
Zhang et al. [ZHN ⁺ 20]	scene	agent-inter	stat	SA+HA	rgbd	supervised	generative
Mao et al. [MZX ⁺ 19]	object	agent-inter	stat	SA	mesh	supervised	generative
Fu et al. [FFY ⁺ 20]	scene	agent-inter	stat	SA+HA	mesh	supervised	discriminative
Monsrpart et al. [MGC ⁺ 19]	scene	agent-inter	stat	SA	rgbd	supervised	generative
Raiz et al. [RMC19]	scene	agent-inter	stat	SA+BR	mesh	supervised	generative
Starke et al. [SZKS19]	object	agent-inter	dyn	SA	vol	supervised	generative

Summary for definition

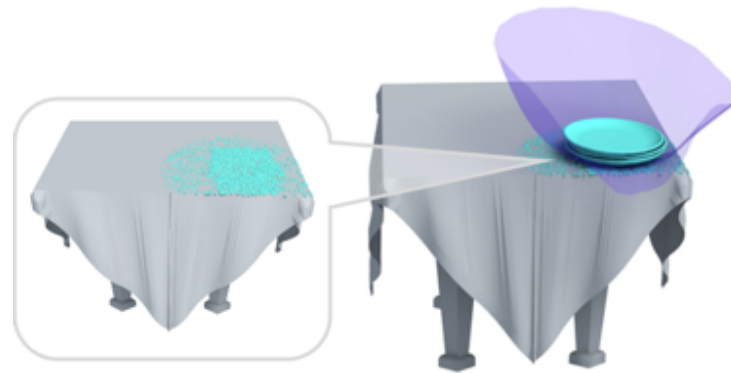
- Use **definition of functionality** and **additional criteria** to classify and discuss **previous work**
- Definition provides **three groups of functionality methods**
- **Classification** also useful when discussing **unexplored areas of research and future work**

Next: discussion of methods

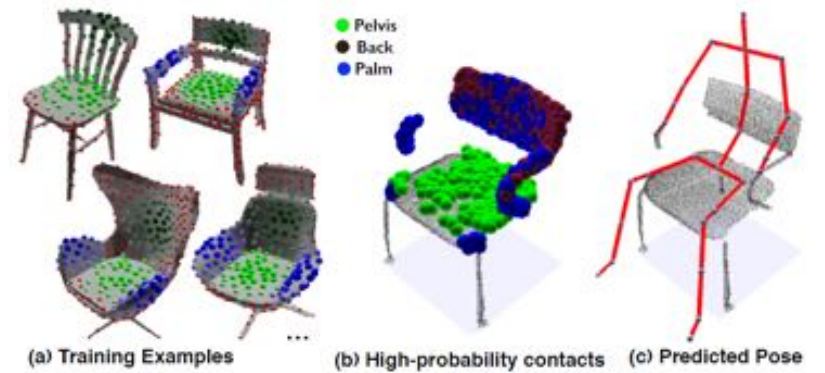
Functionality = Geometry + Interaction



G methods

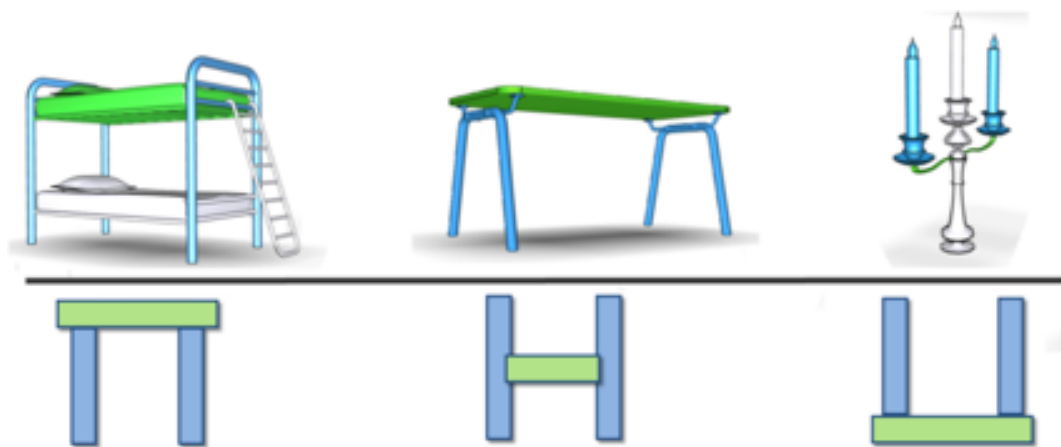


GI methods



GA methods

Geometry-only (G) methods

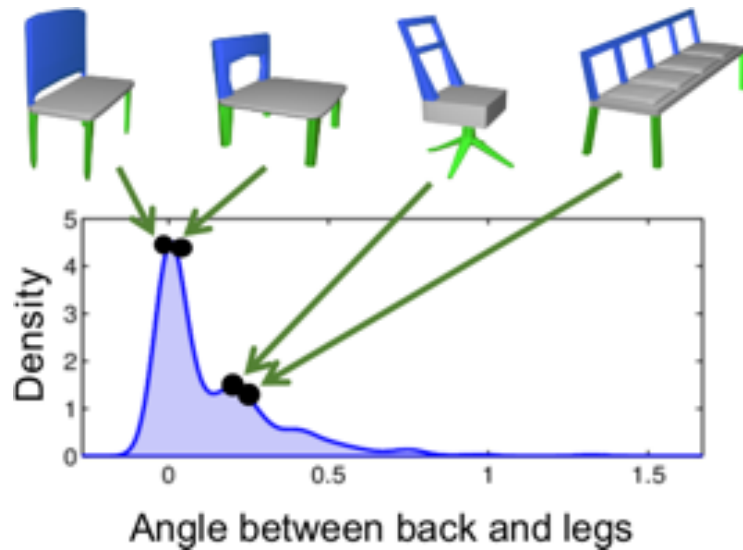


Geometry-only methods

Functionality = Geometry + Interaction



Geometry-only (G) methods



Meta-representation
of shape families
[FavK*14]

Geometry-only methods

- Derive **functionality** only from **geometry** and **structure**
- Geometry and structure of **parts, objects, or scenes**
- **Interactions** with other entities are **not considered**
- Relations considered in the analysis are **static**

Geometry-only methods

Discussion follows **level of the entity**:

- Scene-level functionality
- Object-level functionality
- Part-level functionality

Geometry-only methods

Discussion follows **level of the entity**:

- **Scene-level functionality**
- Object-level functionality
- Part-level functionality

Scene-level functionality

- Describe the **functionality of a scene**
- Specific **object arrangements** enable certain functionalities
- Consider **relations between objects** in the scene
- **Spatial arrangements** or **boundary representations**

Scene-level functionality



Constrained placement
[XSF02]



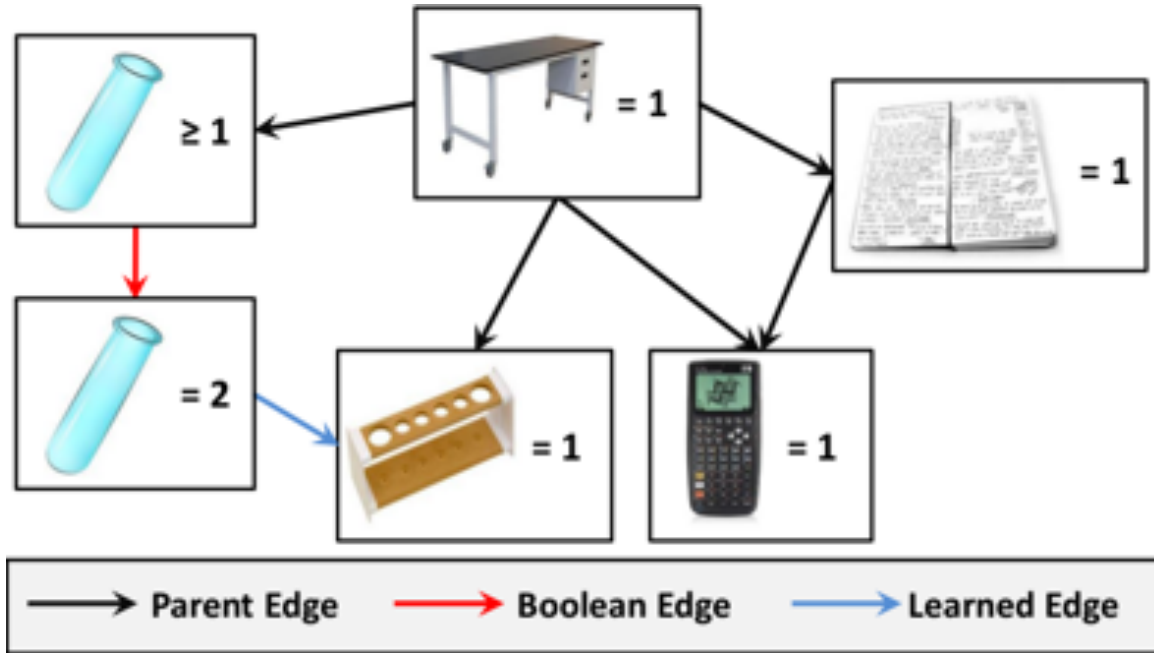
Interior design guidelines
[MSL*11]



“Make it home”
[YYT*11]

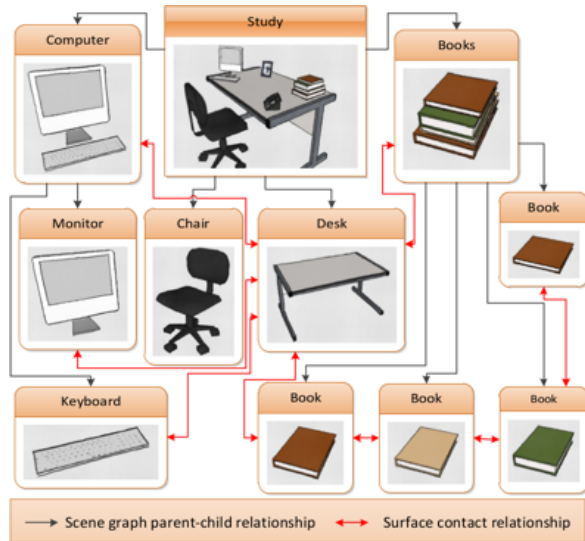
- Automatically **place objects** to **generate a scene**
- Using **placement constraints and rules, pseudo-physics, interior design guidelines, and ergonomic factors**

Scene-level functionality

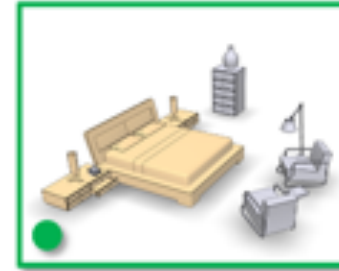
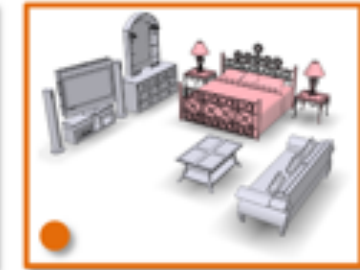


- “Example-based synthesis of 3D object arrangements” [FRS*12]
- **Synthesize scenes** with a **learned object co-occurrence model**

Scene-level functionality



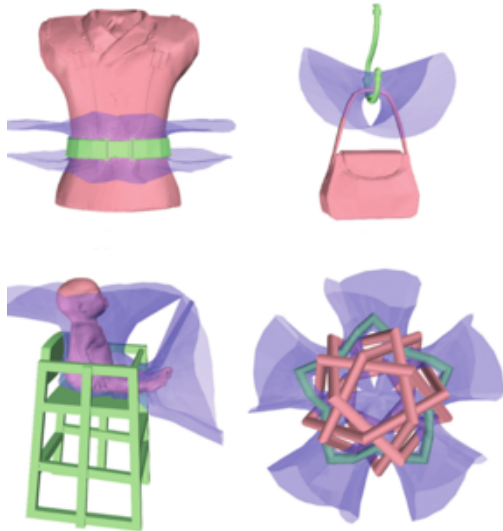
Graph kernels
[FSH11]



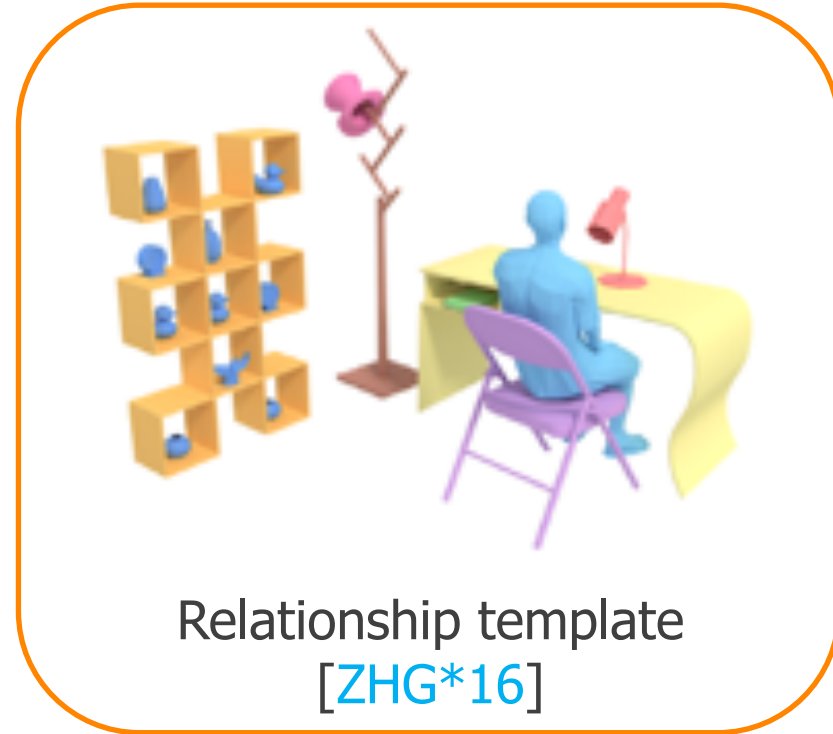
Focal points
[XMZ*14]

- Content-based **comparison** for **scene retrieval**
- Considering **co-occurrence of objects**

Scene-level functionality



Interaction Bisector Surface
[ZWK14]



Relationship template
[ZHG*16]

- Represent the **spatial boundary** between objects
- Applicable to **scene comparison** and **template-based synthesis**

Relationship templates

[ZHG*16]

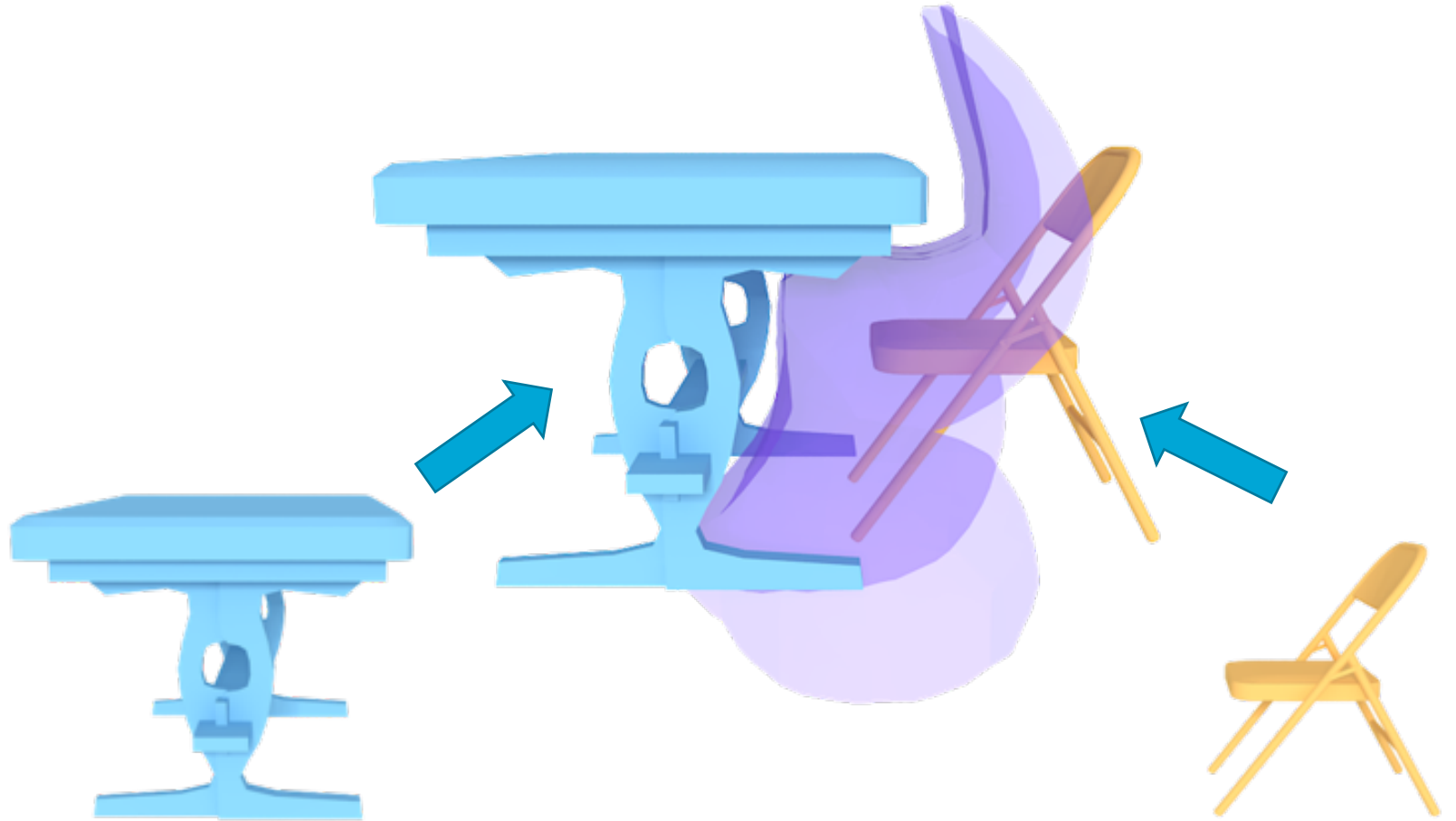
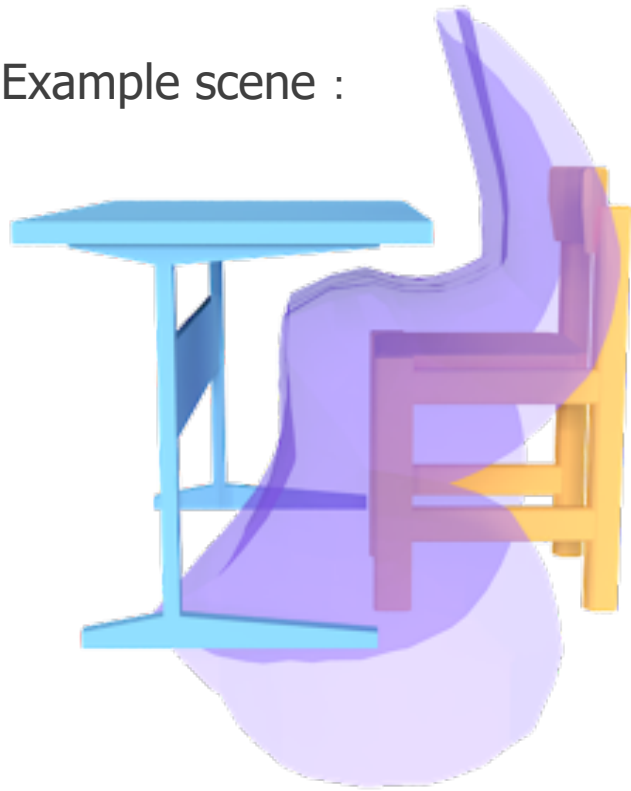


How to make variations of complex relationship?

Relationship templates

[ZHG*16]

Example scene :

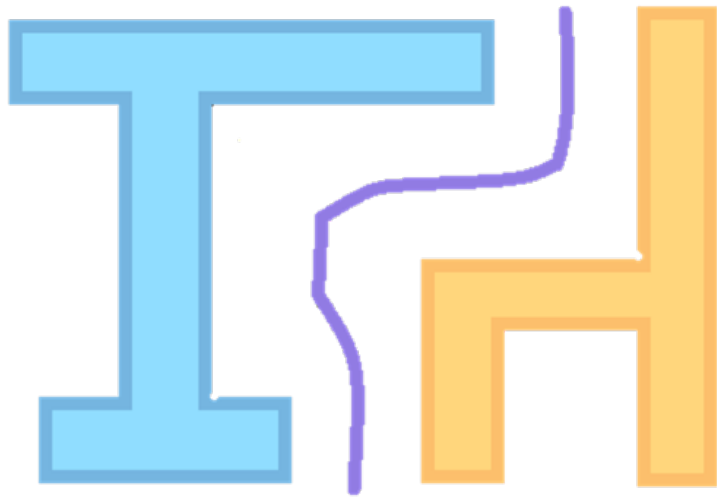


Novel object 1

Novel object 2

Relationship templates

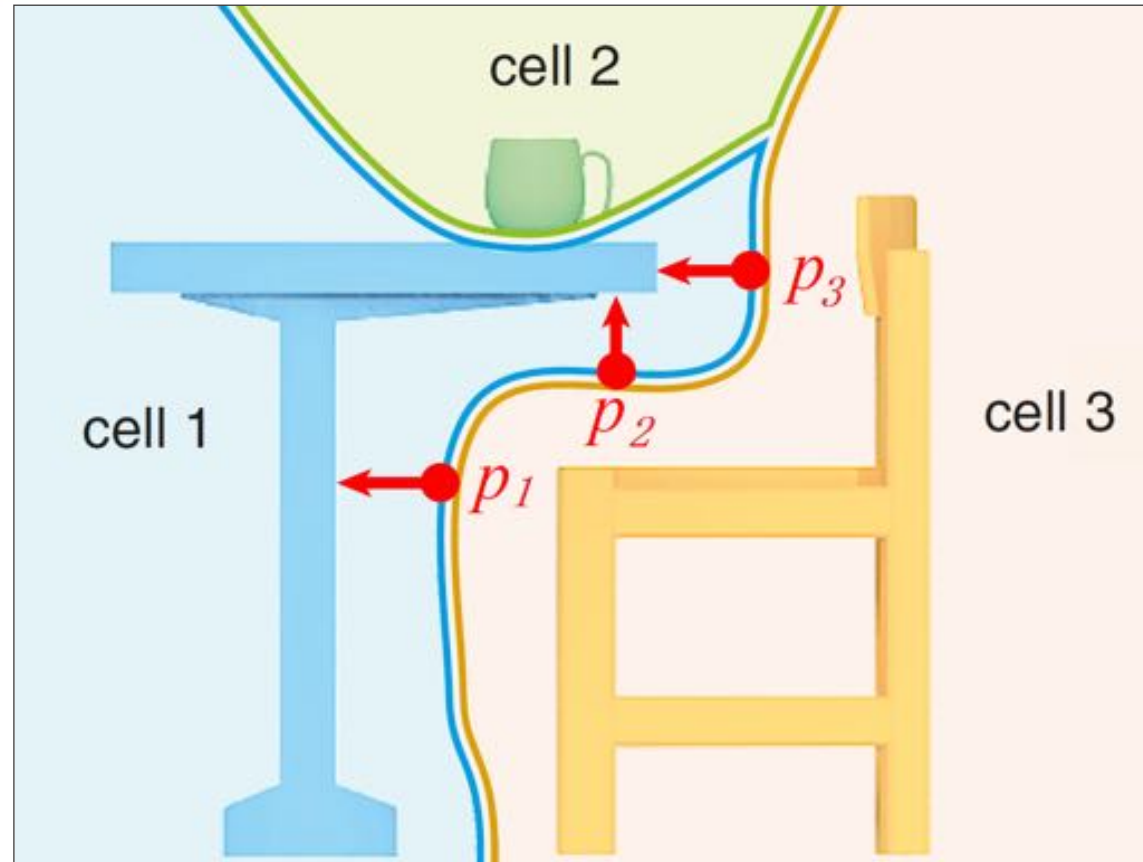
[ZHG*16]



Template construction: IBS

Relationship templates

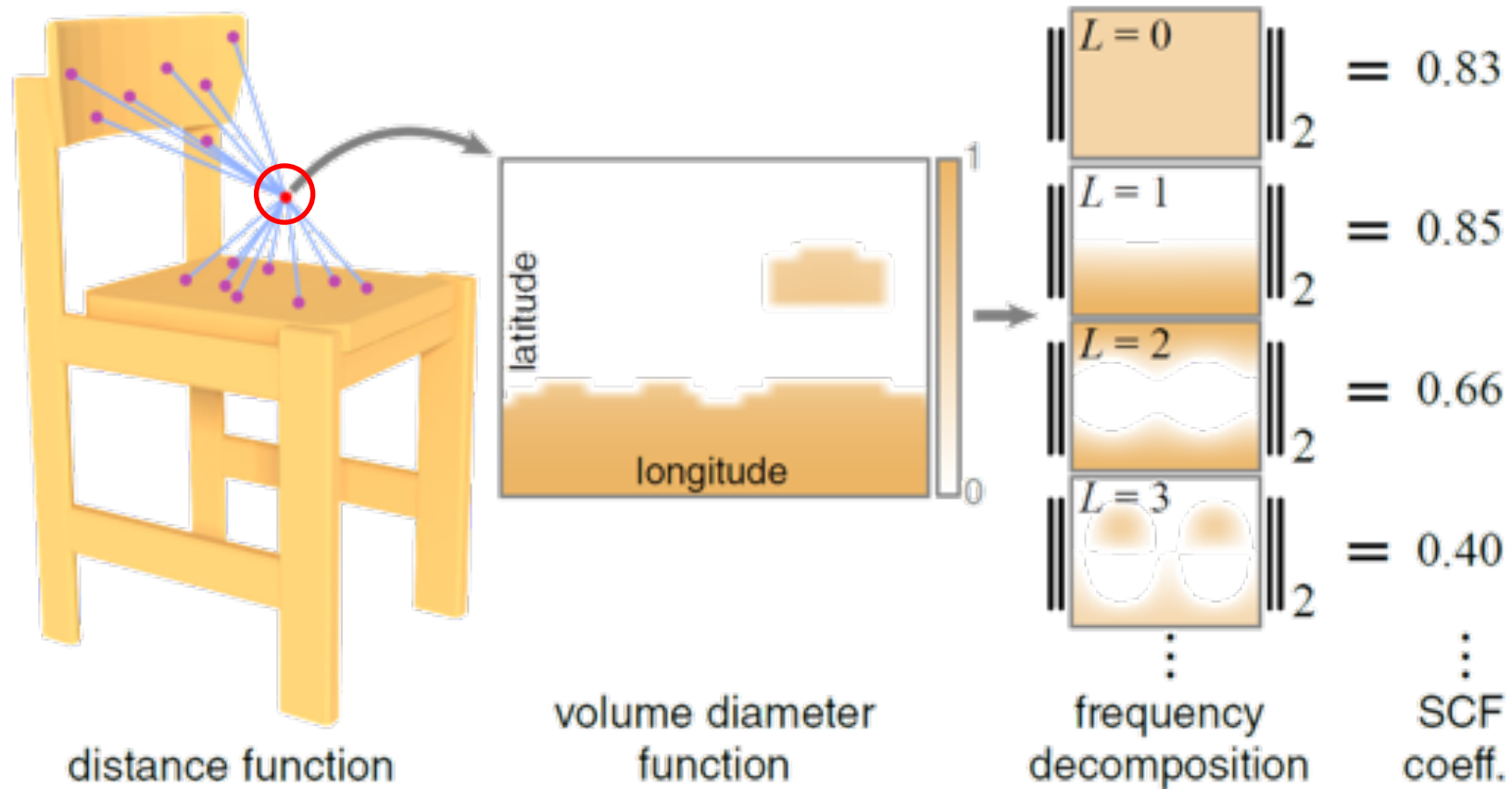
[ZHG*16]



Template construction: cells and features

Relationship templates

[ZHG*16]

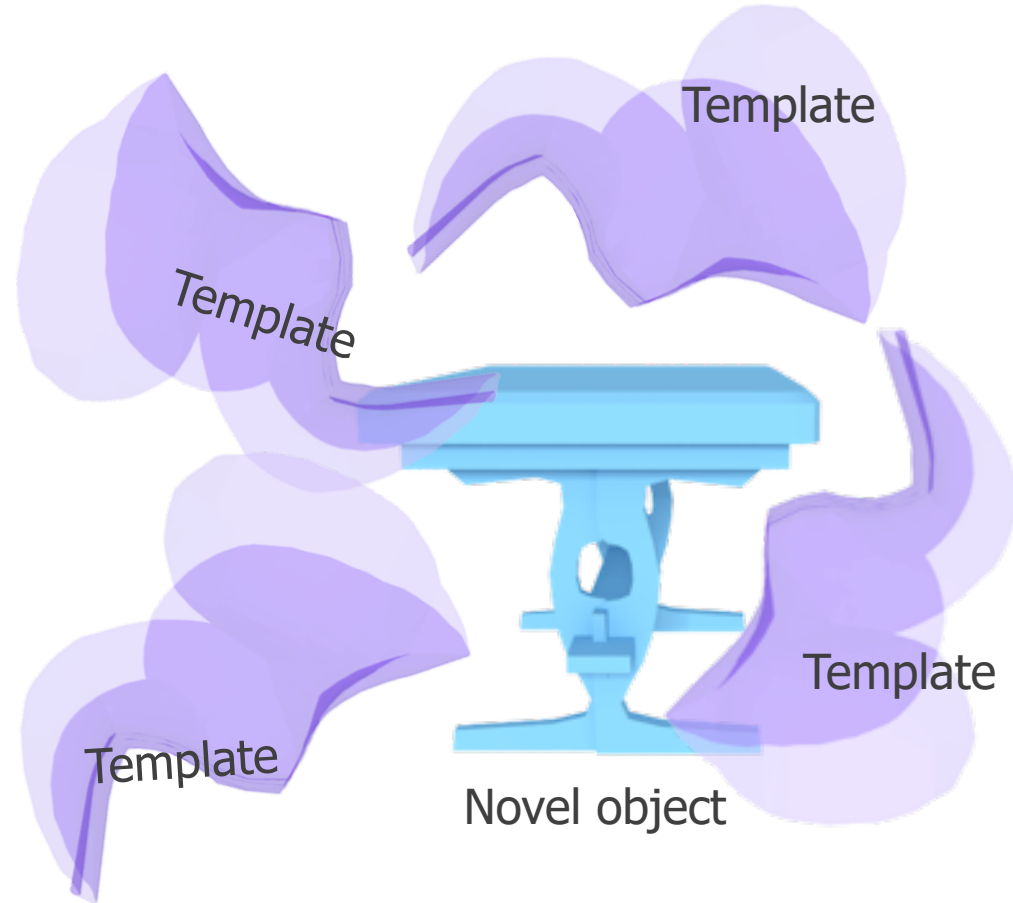


Shape Coverage Feature (SCF)

Relationship templates

[ZHG*16]

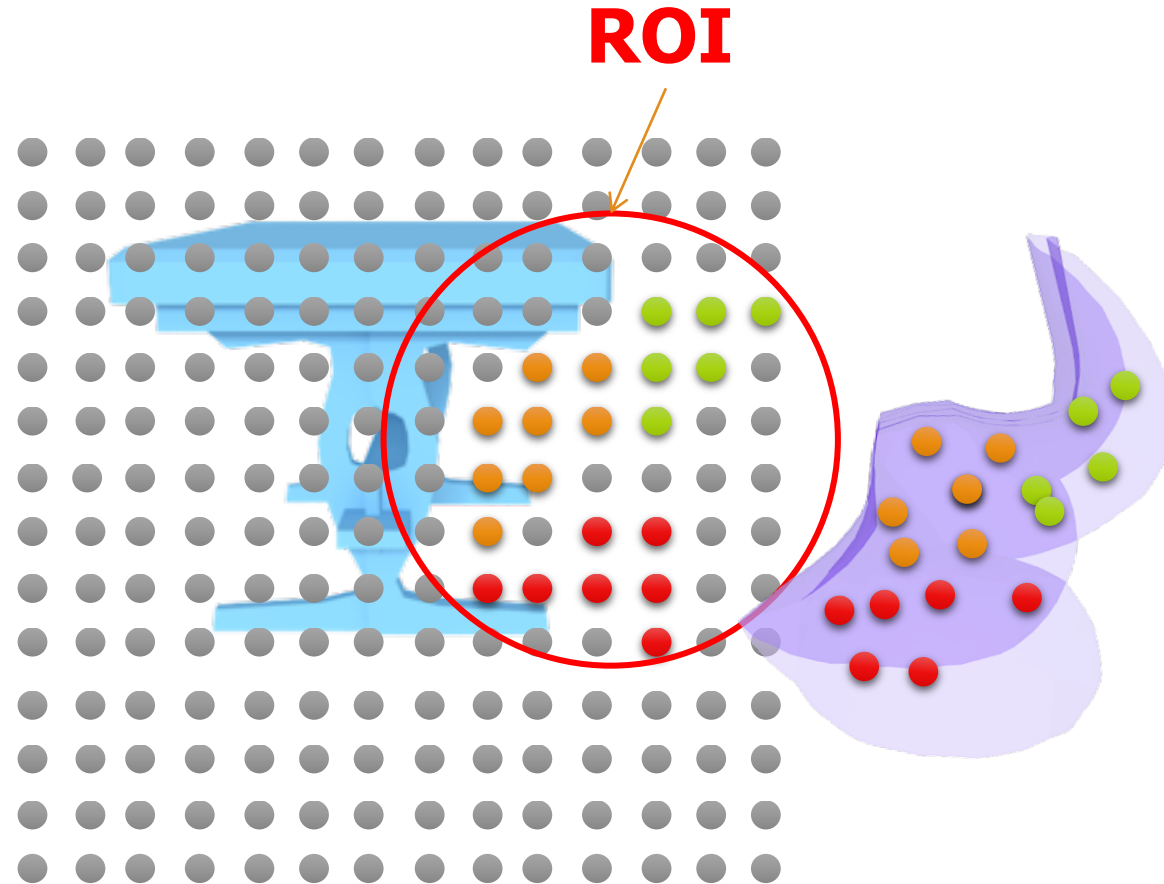
Example scene :



Novel Object Fitting

Relationship templates

[ZHG*16]



Novel Object Fitting: initial matching

Relationship templates

[ZHG*16]

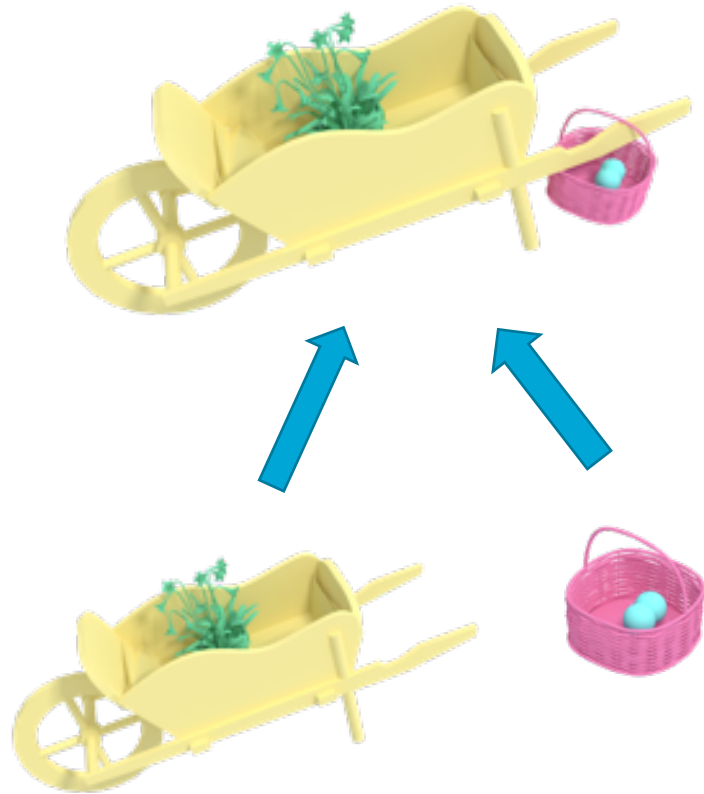


Novel Object Fitting: refinement

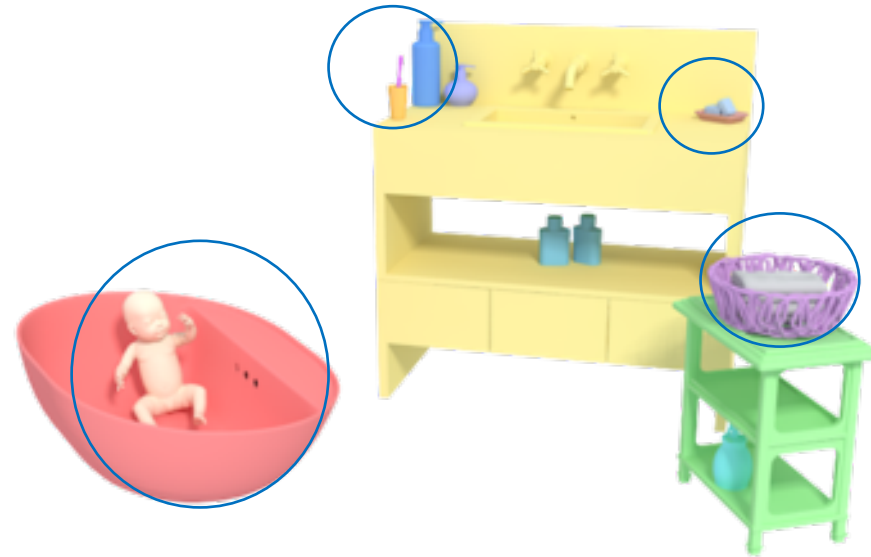
Relationship templates

[ZHG*16]

Scene hierarchy



Combine with other scene synthesis system



M. Fisher, D. Ritchie, M. Savva, T. Funkhouser, and P. Hanrahan, “**Example-based Synthesis of 3D Object Arrangements**” *SIGGRAPH ASIA2012*

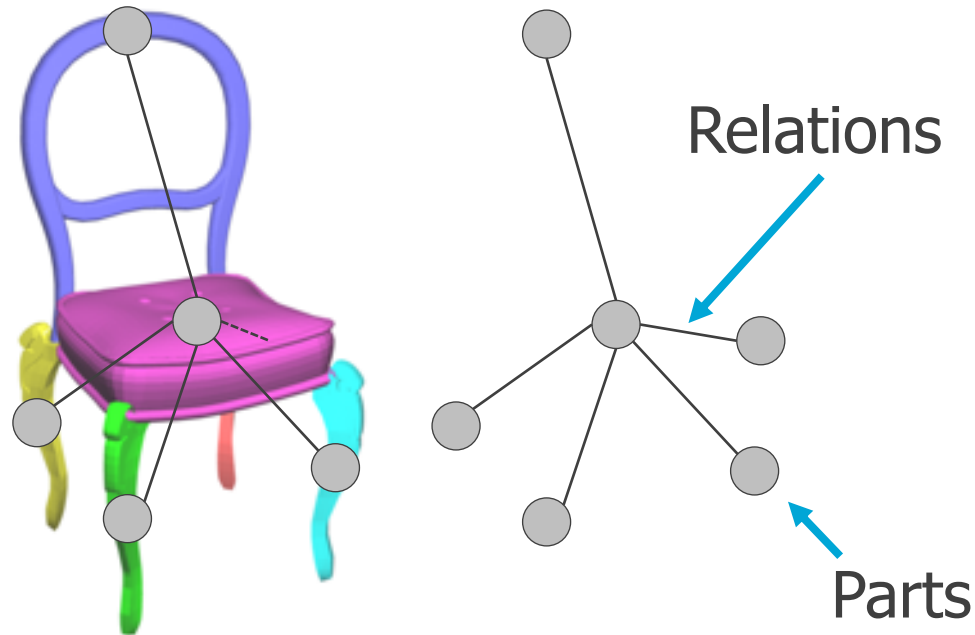
Geometry-only methods

Discussion follows **level of the entity**:

- Scene-level functionality
- **Object-level functionality**
- Part-level functionality

Object-level functionality

- Examine the **geometry** and **structure** of the object
- Structure: represent a shape as a **graph of parts**
- Edges represent **relations** between connected parts

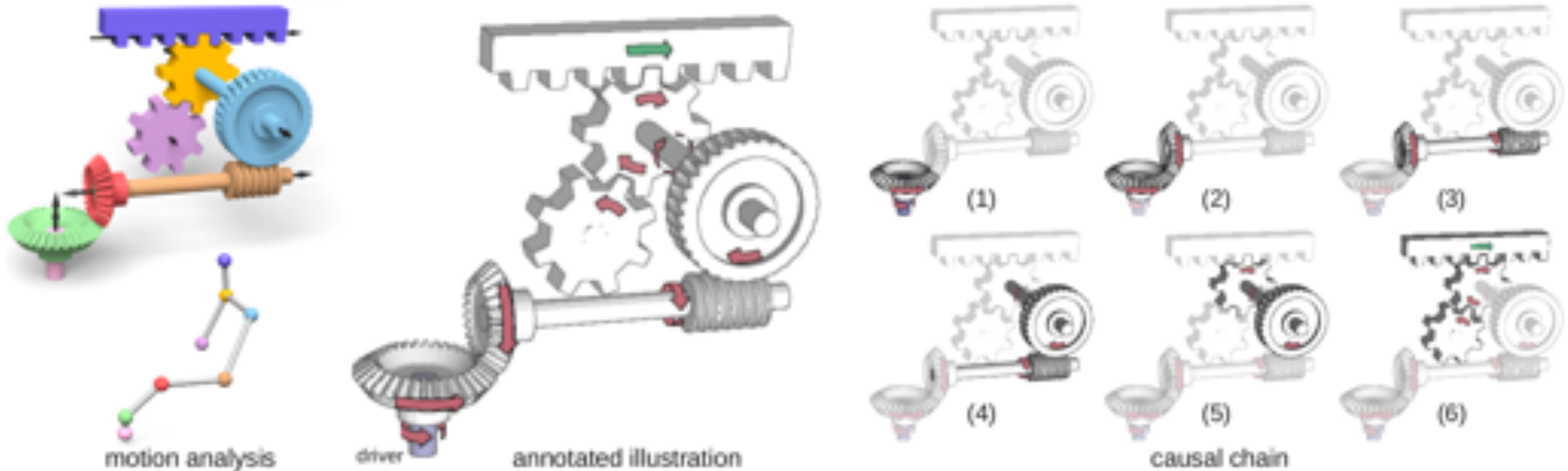


Object-level functionality



- Symmetric functional arrangements (**sFARRs**) [[ZCOM13](#)]
- **Handcrafted rules** to detect **special groupings of parts**
- **Exchange sFARRs** between shapes to **generate plausible shapes**

Object-level functionality



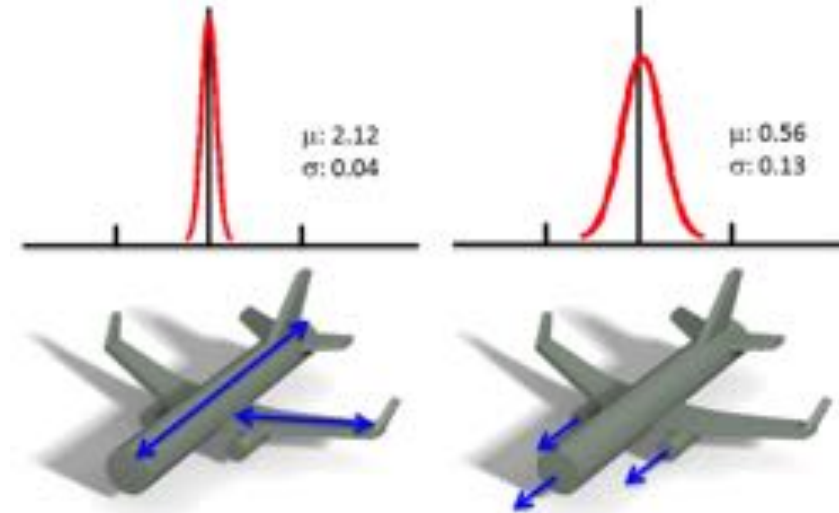
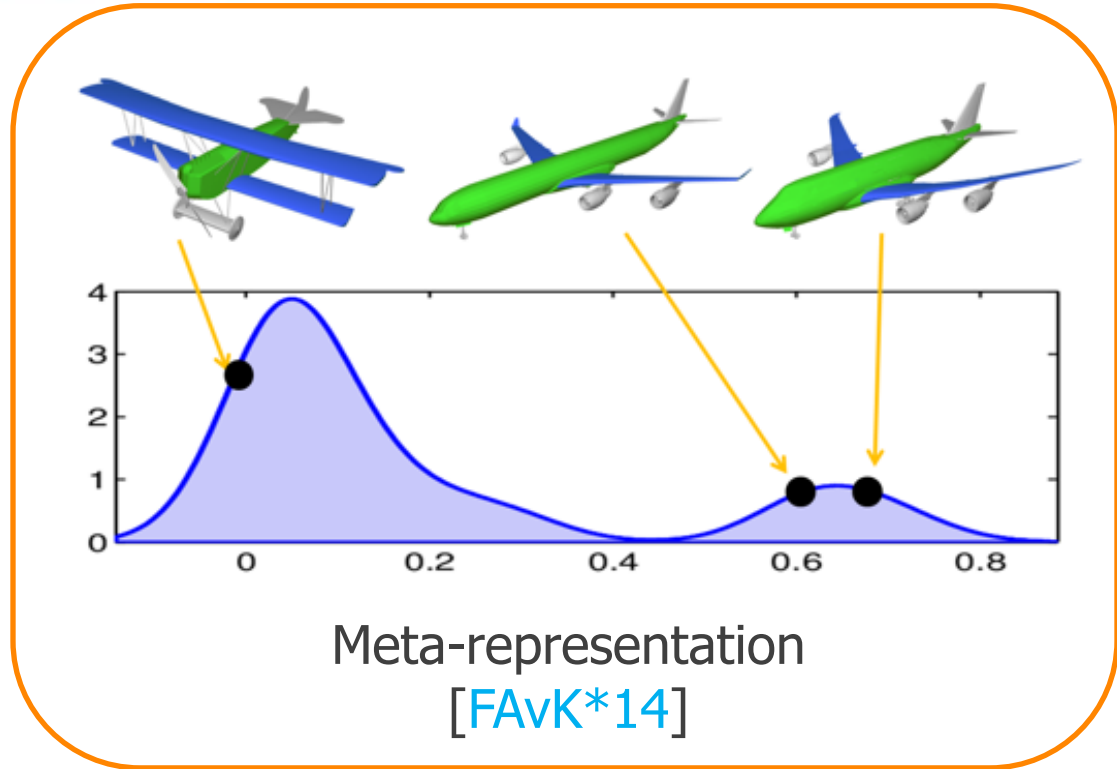
- Illustrate the **functioning** of **mechanical assemblies** [MYY*10]
- Assemblies composed of mechanical components such as **gears**
- Infer **motion** with **handcrafted rules** based on **symmetry relations**

Object-level functionality



- Recover **functioning of mechanical assemblies** from **images** [XLX*16]
- Analysis of the **geometry of linked parts** in **multiple views**

Object-level functionality



- **Learn a part configuration model** from a set of shapes of same family
- Evaluate **validity** of a shape based on how well it **fits the model**

Meta-representation of shapes [FAvK*14]



Are these shapes "valid"?

Meta-representation of shapes [FAvK*14]



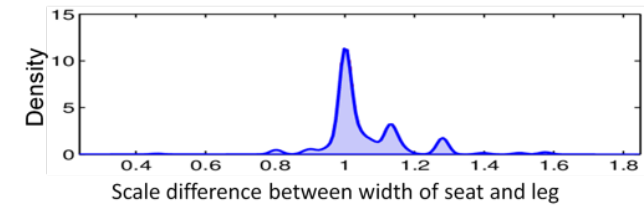
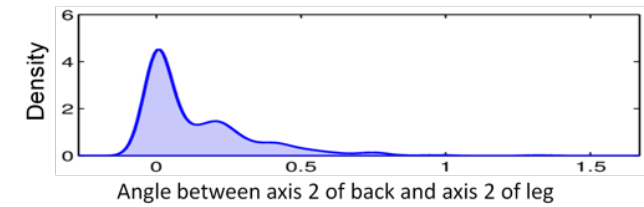
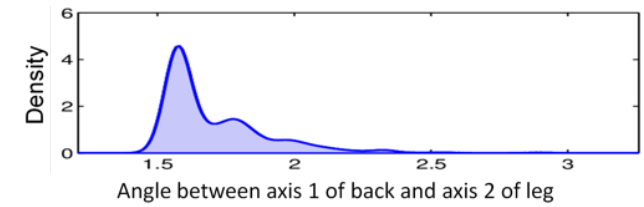
Learn validity from a collection

Meta-representation of shapes [FAvK*14]

Input



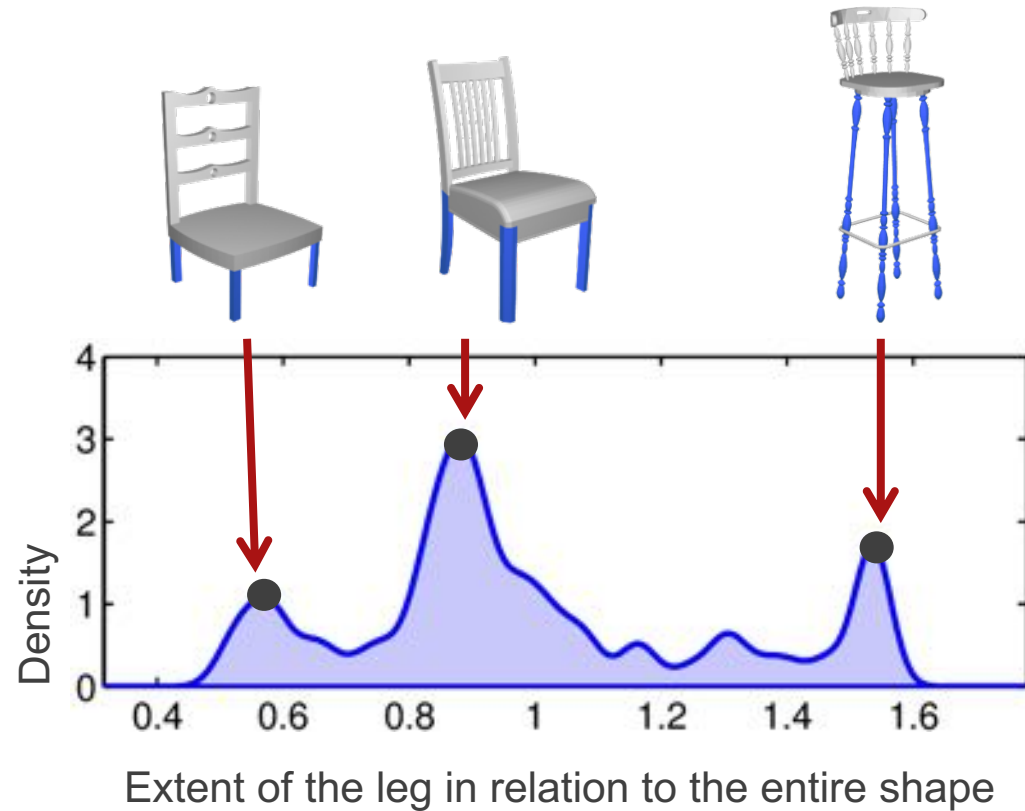
Meta-representation



■
■
■

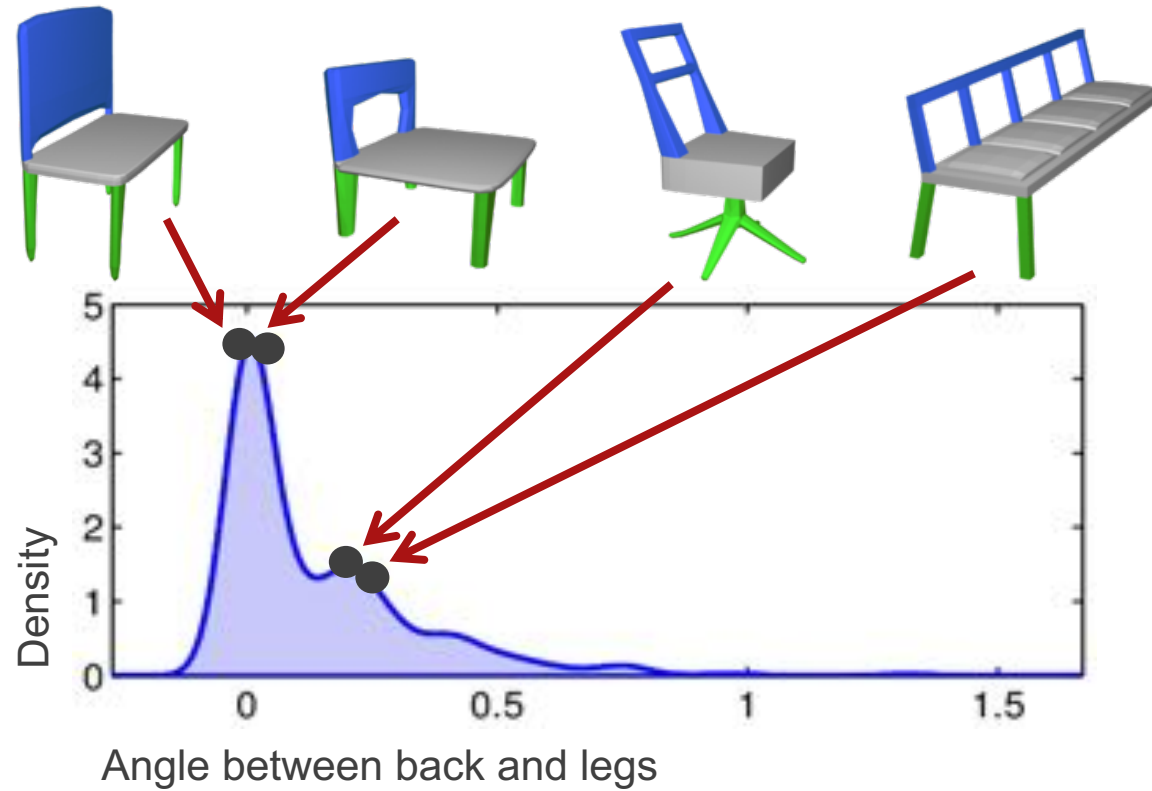
How to characterize “validity”?

Meta-representation of shapes [FAvK*14]



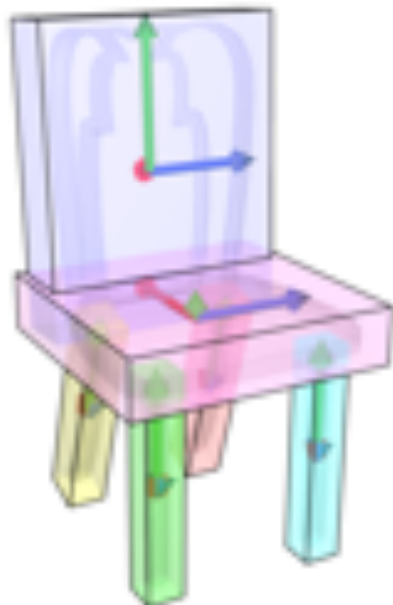
Relations for single parts

Meta-representation of shapes [FAvK*14]




Relations for pairs of parts

Meta-representation of shapes [FAvK*14]



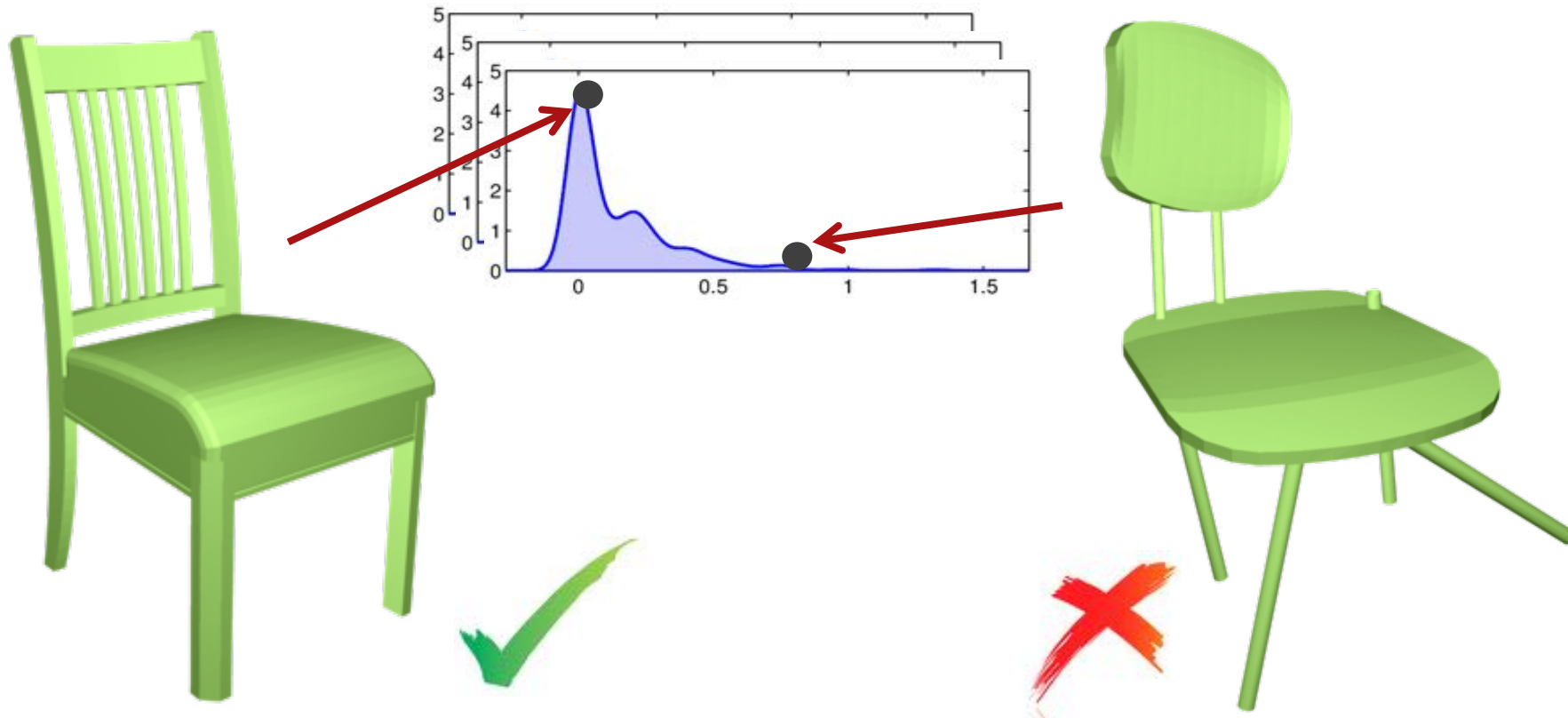
	Back	Seat	Leg
Back	unary	binary	binary
Seat		unary	binary
Leg			unary

Extent
Unary: 

Binary: 
Scale
Rotation
Contact

Relations per shape

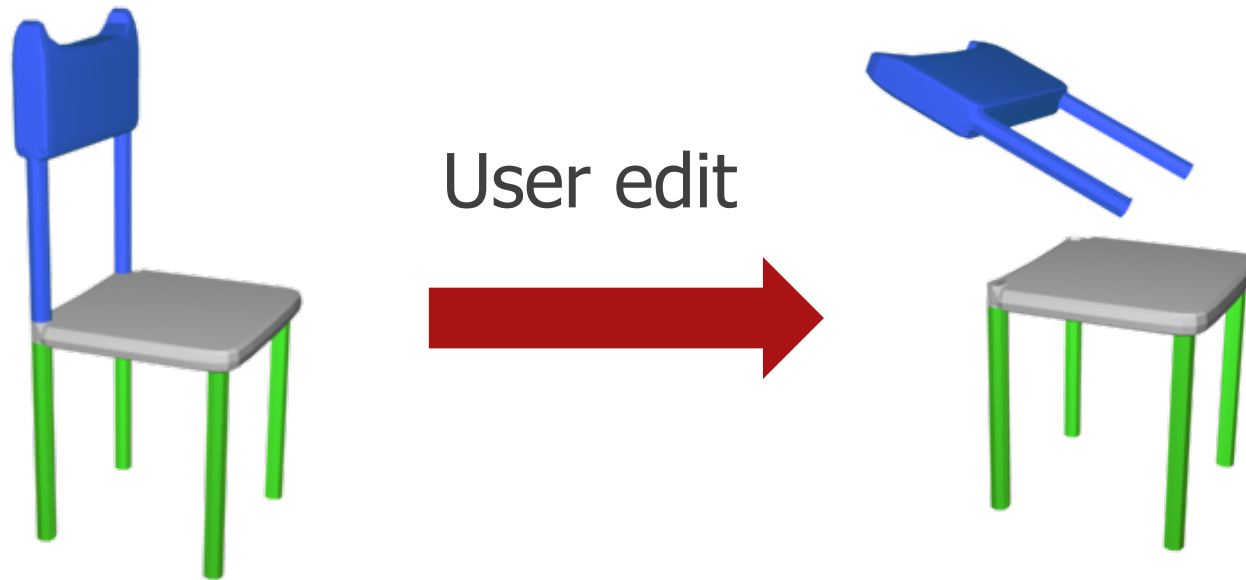
Meta-representation of shapes [FAvK*14]



Characterize validity with the relations

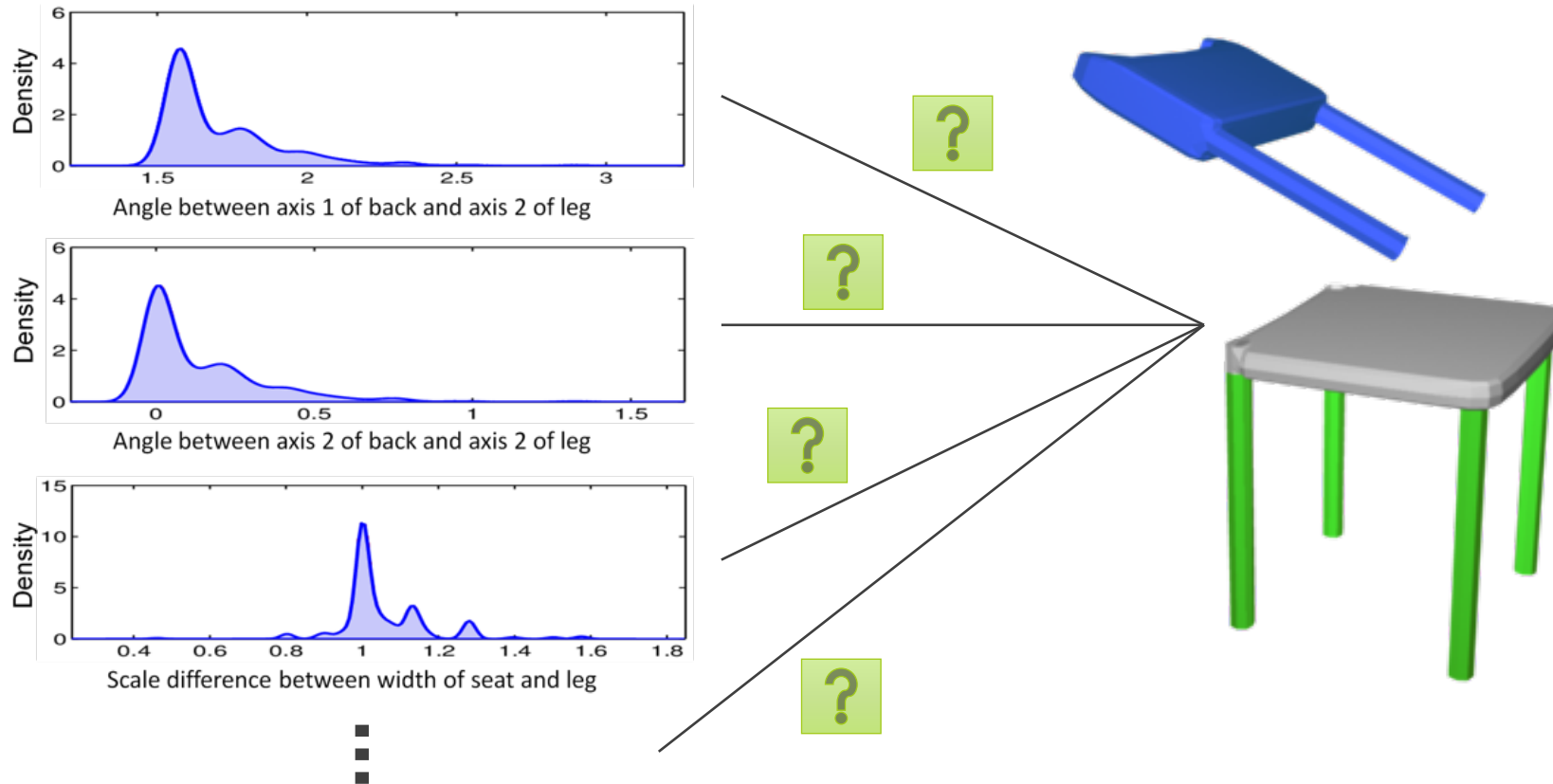
- Validity is useful in several applications:
 - Exploration
 - Guided modeling
 - Coupled editing

Meta-representation of shapes [FAvK*14]



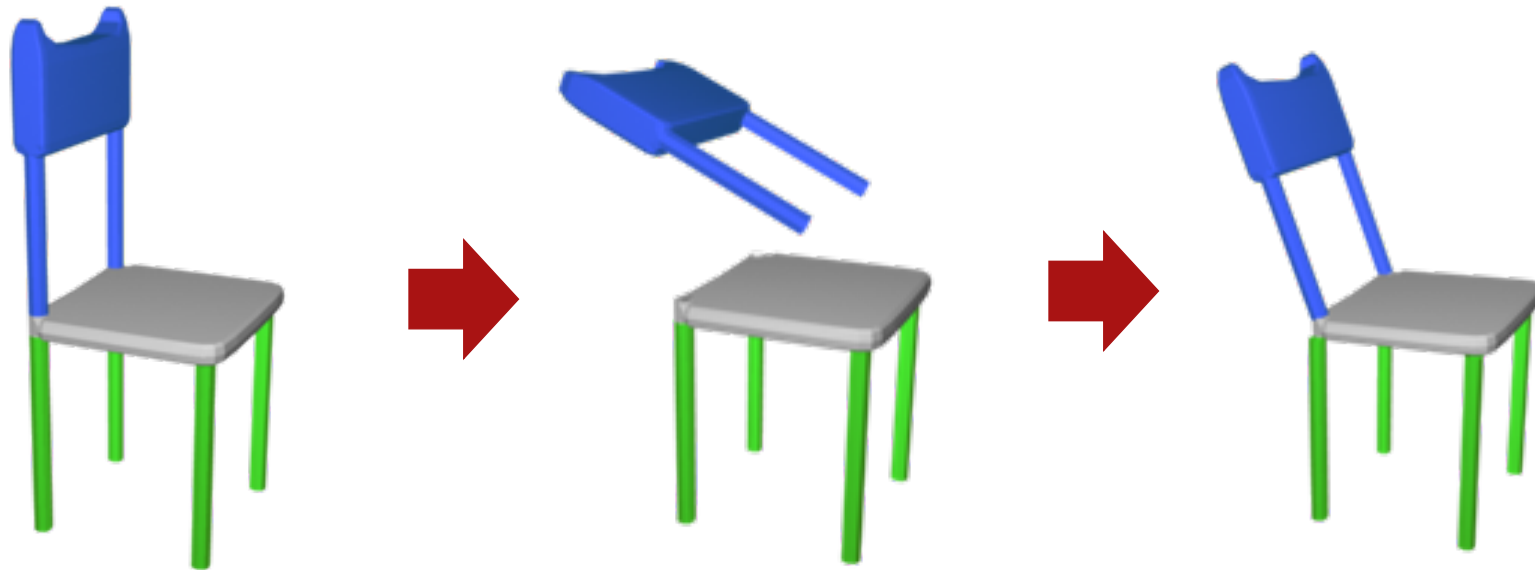
General editing approach

Meta-representation of shapes [FAvK*14]



General editing approach

Meta-representation of shapes [FAvK*14]



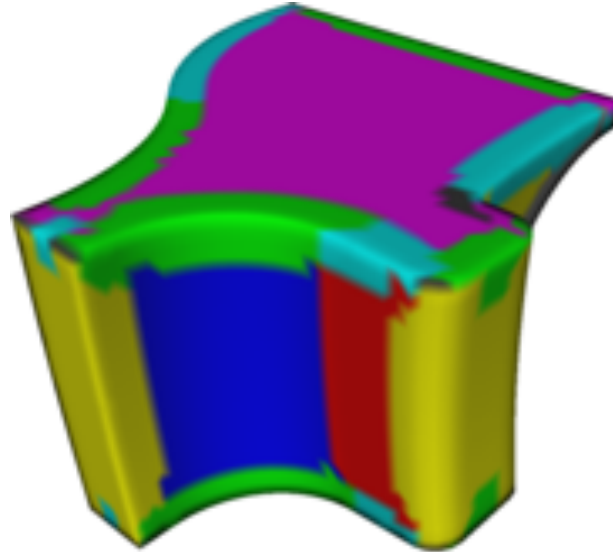
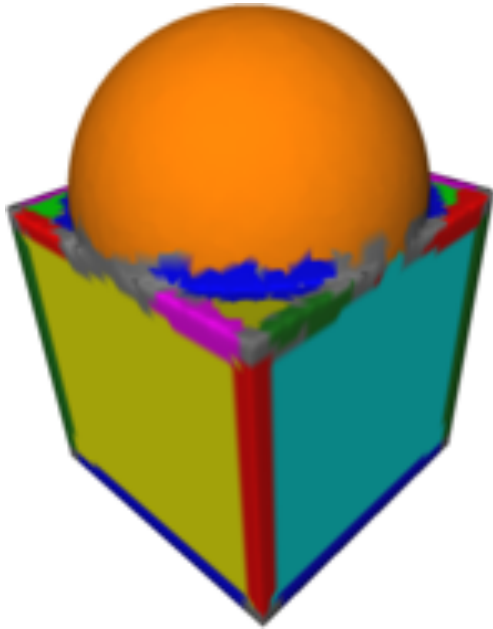
General editing approach

Geometry-only methods

Discussion follows **level of the entity**:

- Scene-level functionality
- Object-level functionality
- **Part-level functionality**

Part-level functionality



- “Shape segmentation using local slippage analysis” [GG04]
- Discover **slippable motions** of a shape
- Reveal **regions of shapes** that are **kinematic surfaces** with same motion

Discussion

- Functionality models derived from **geometry** and **structure**
- Models **often** capture **functional properties** of a shape
- **But not all** discovered **properties** relate to **functionality**
- **Handcrafted models** often include only few **manually-defined functionality types**

Geometry + Interaction

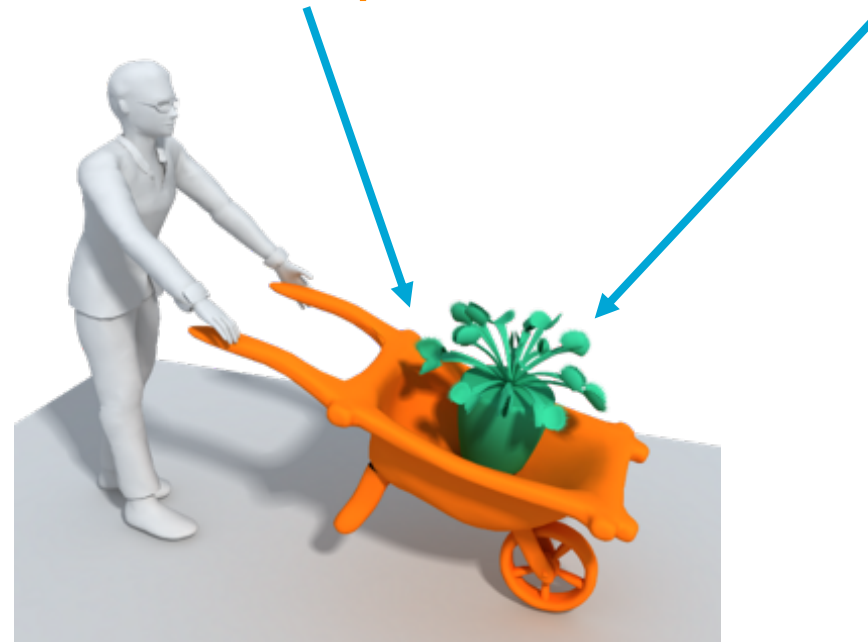


Our definition of functionality

Functionality = Geometry + Interaction

Atomic interaction:

<Functional entity, relation, interacting entity>



Key observation

- The functionality of an entity is well reflected by **the way how the entity is used when performing its functionality**



Challenges

- Capture multiple, different interactions



Challenges

- Insensitivity to object geometry and count



Challenges

- Group interactions in a meaningful manner



Structural organization

Geometry + interaction methods

Works	Representation of geometry or interactions				Additional classification criteria		
	Functional entity	Component / interacting entity	Dynamicity	Relations	Input	Approach	Model type
Geometry+interaction (GI)							
Hu et al. [HZK ⁺ 15]	object	stat-inter	stat	BR	pcl	handcrafted	discriminative
Hu et al. [HYKW ⁺ 16]	object	stat-inter	stat	BR	pcl	supervised	discriminative
Pirk et al. [PKH ⁺ 17]	object	dyn-inter	dyn	VF	mesh	handcrafted	discriminative
Myers et al. [MTFA15]	part	stat-inter	stat	SA	rgbd	supervised	discriminative
Kim et al. [KS14]	part	stat-inter	stat	SA	rgbd	supervised	discriminative
Laga et al. [LMS13]	part	stat-inter	stat	SA+SG	mesh	supervised	discriminative
Hu et al. [HLK ⁺ 17]	part	stat-inter	dyn	SA+BR	pcl	supervised	discriminative
Xiang et al. [XQM ⁺ 20]	part	stat-inter	dyn	SA	mesh	supervised	discriminative
Hu et al. [HYZ ⁺ 18]	object	stat-inter	stat	SA+BR	vol	supervised	generative
Yi et al. [YHL ⁺ 18]	part	stat-inter	dyn	SA	pcl	supervised	discriminative
Wang et al. [WZS ⁺ 19]	part	stat-inter	dyn	SA	pcl	supervised	discriminative
Yan et al. [YHY ⁺ 19]	part	stat-inter	dyn	SA	pcl	supervised	discriminative
Li et al. [LWY ⁺ 20]	part	stat-inter	dyn	SA	pcl	supervised	discriminative
Kokic et al. [KSHK17]	part	stat-inter	dyn	SA	pcl	supervised	generative
Li et al. [LSK20]	part	stat-inter	dyn	SA	pcl	supervised	generative

- Handcrafted descriptors
 - Atemporal interaction
 - Time-varying interaction
- Supervised learning
 - Object-level functionality
 - Discriminative recognition
 - Generative modeling
 - Part-level functionality
 - Atemporal interaction
 - Time-varying interaction

- **Handcrafted descriptors**
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 - Object-level functionality
 - Discriminative recognition
 - Generative modeling
 - Part-level functionality
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 - Time-varying interaction

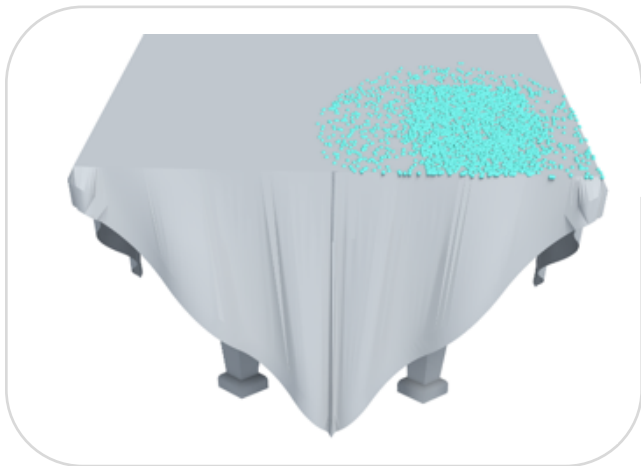
Geometry + interaction methods

- **Handcrafted descriptors**
 - **Atemporal interaction**
 - Time-varying interaction
- **Supervised learning**
 - Object-level functionality
 - Discriminative recognition
 - Generative modeling
 - Part-level functionality
 - Atemporal interaction
 - Time-varying interaction

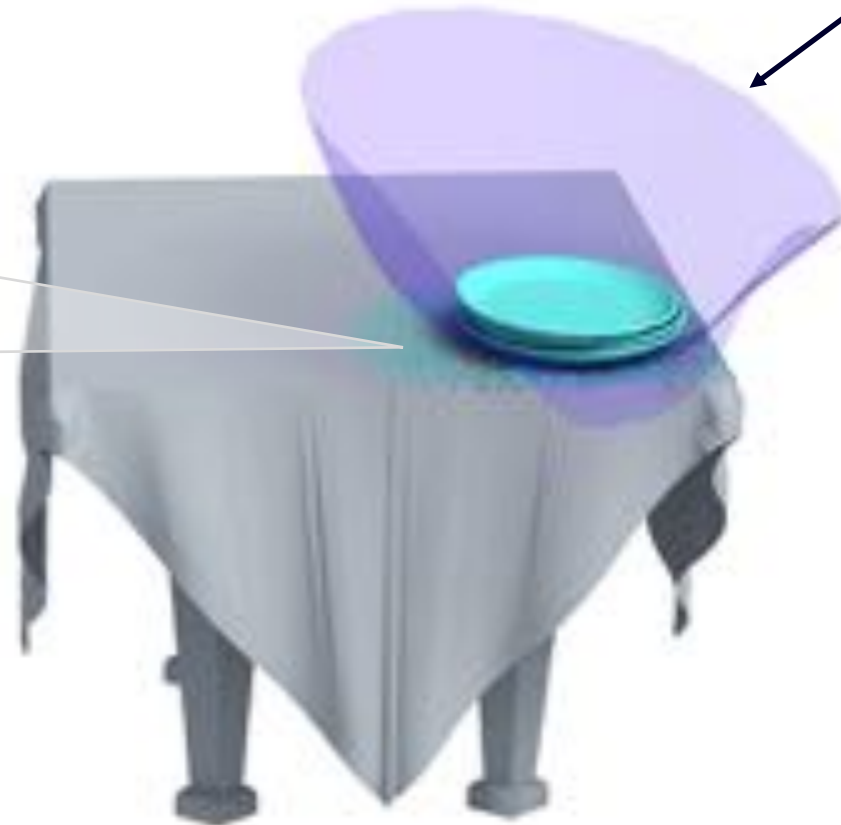


Atemporal interaction representation

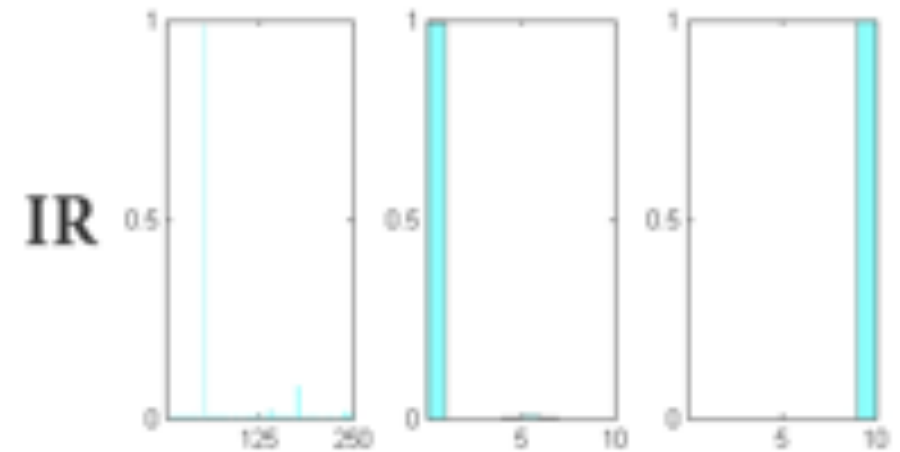
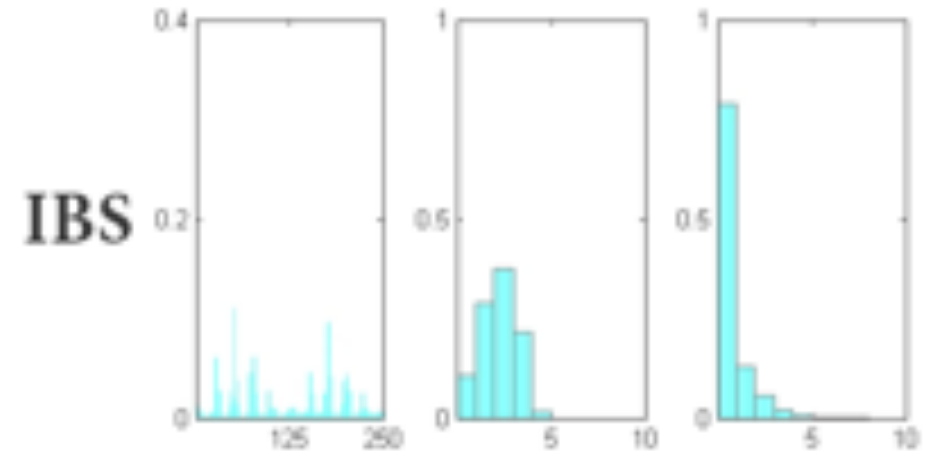
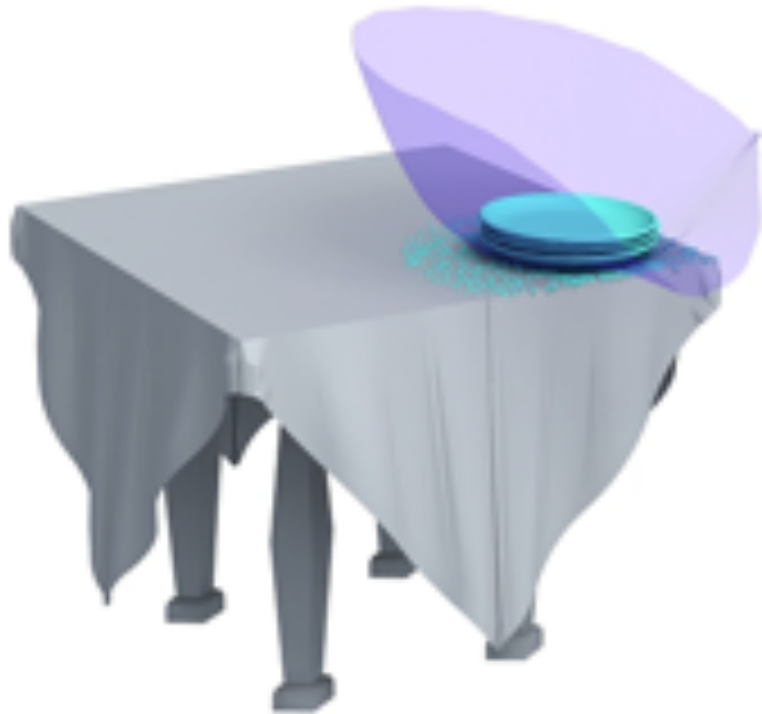
Interaction Bisector Surface
[ZWK14]



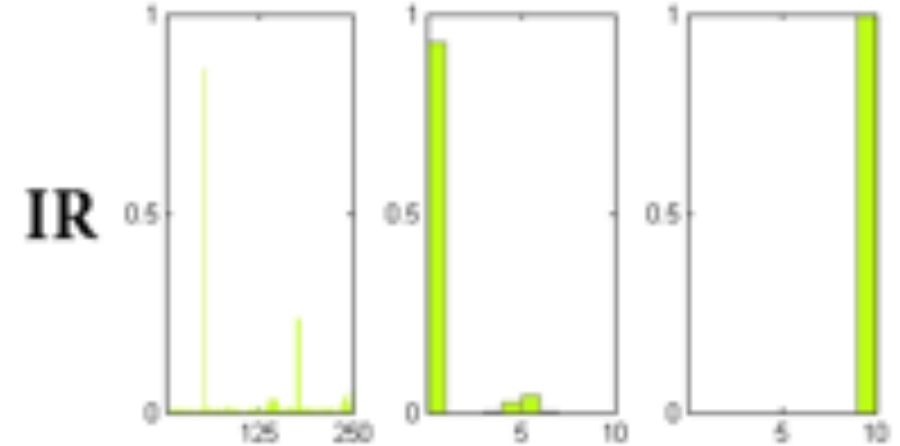
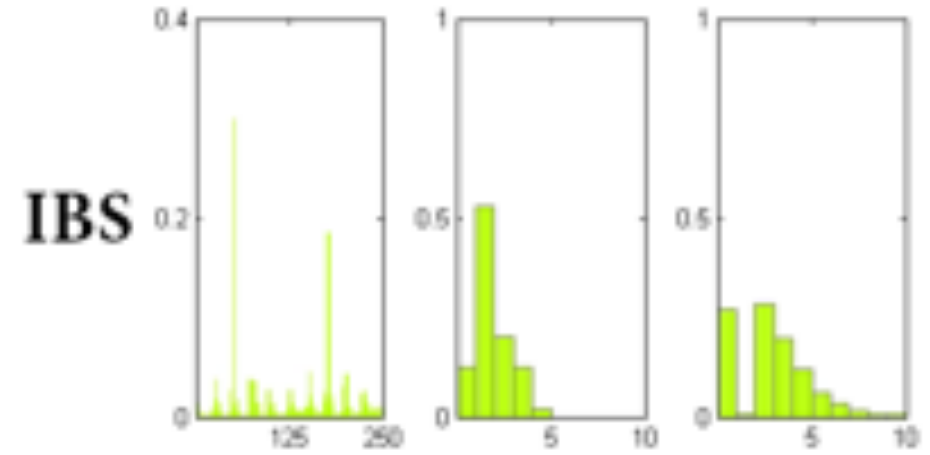
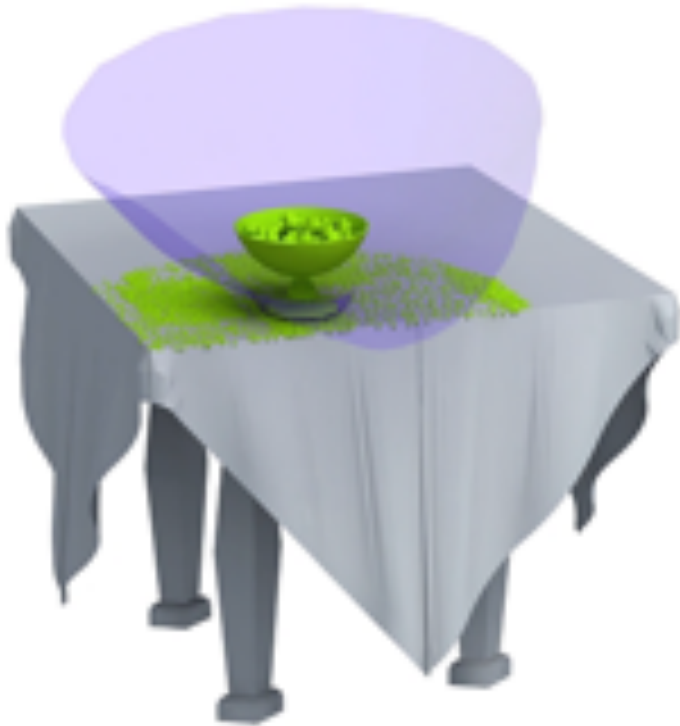
Interaction Region
[HZvK*15]



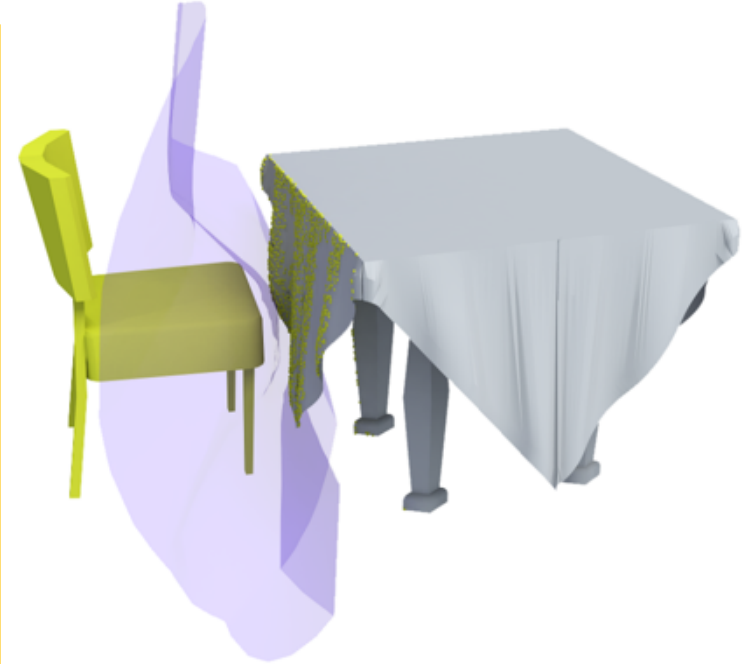
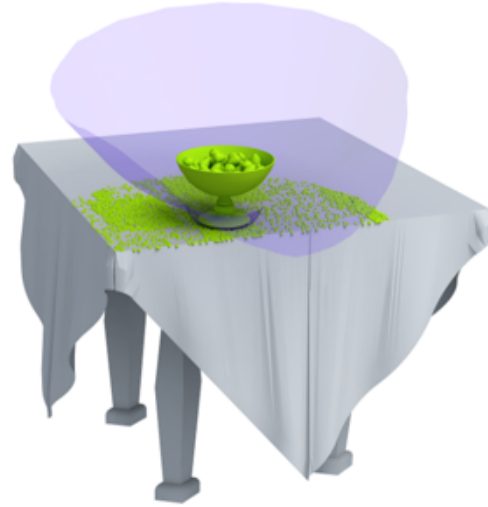
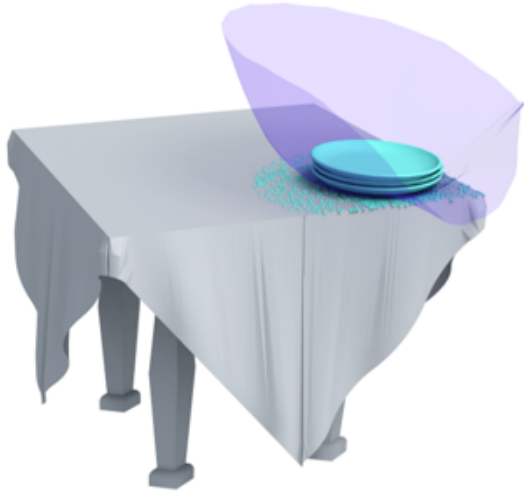
Atemporal interaction representation



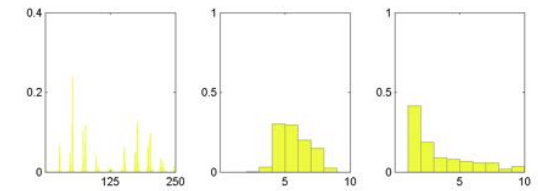
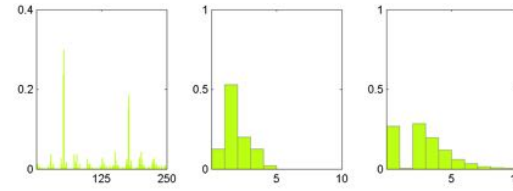
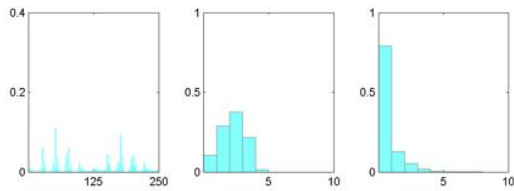
Atemporal interaction representation



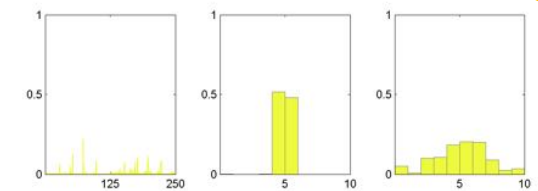
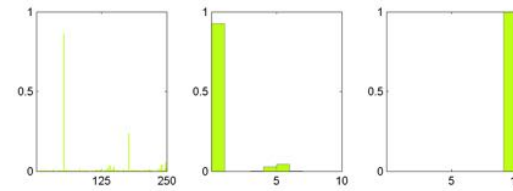
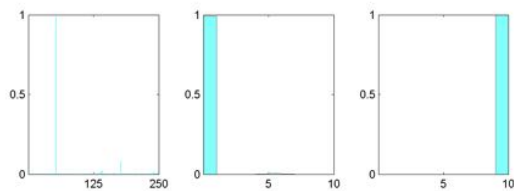
Atemporal interaction representation



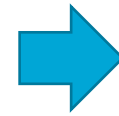
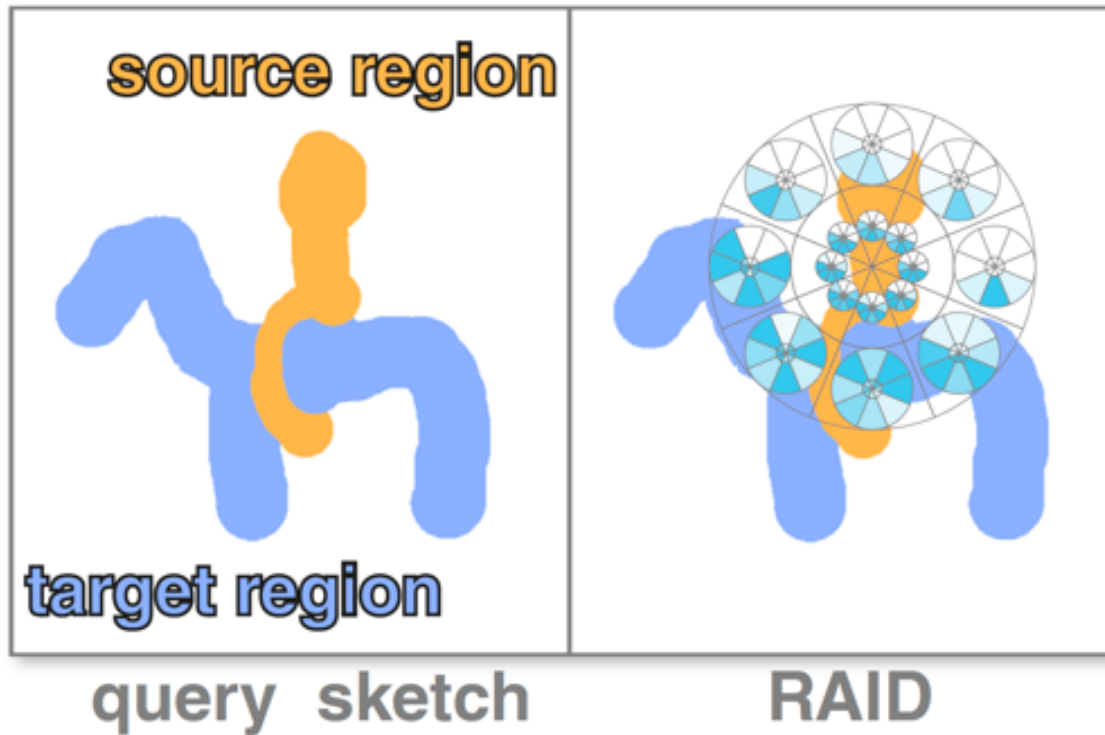
IBS



IR



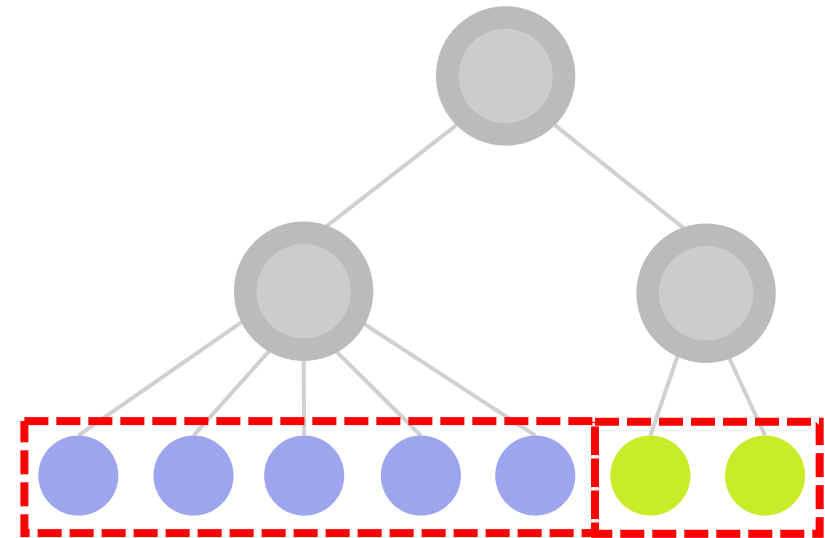
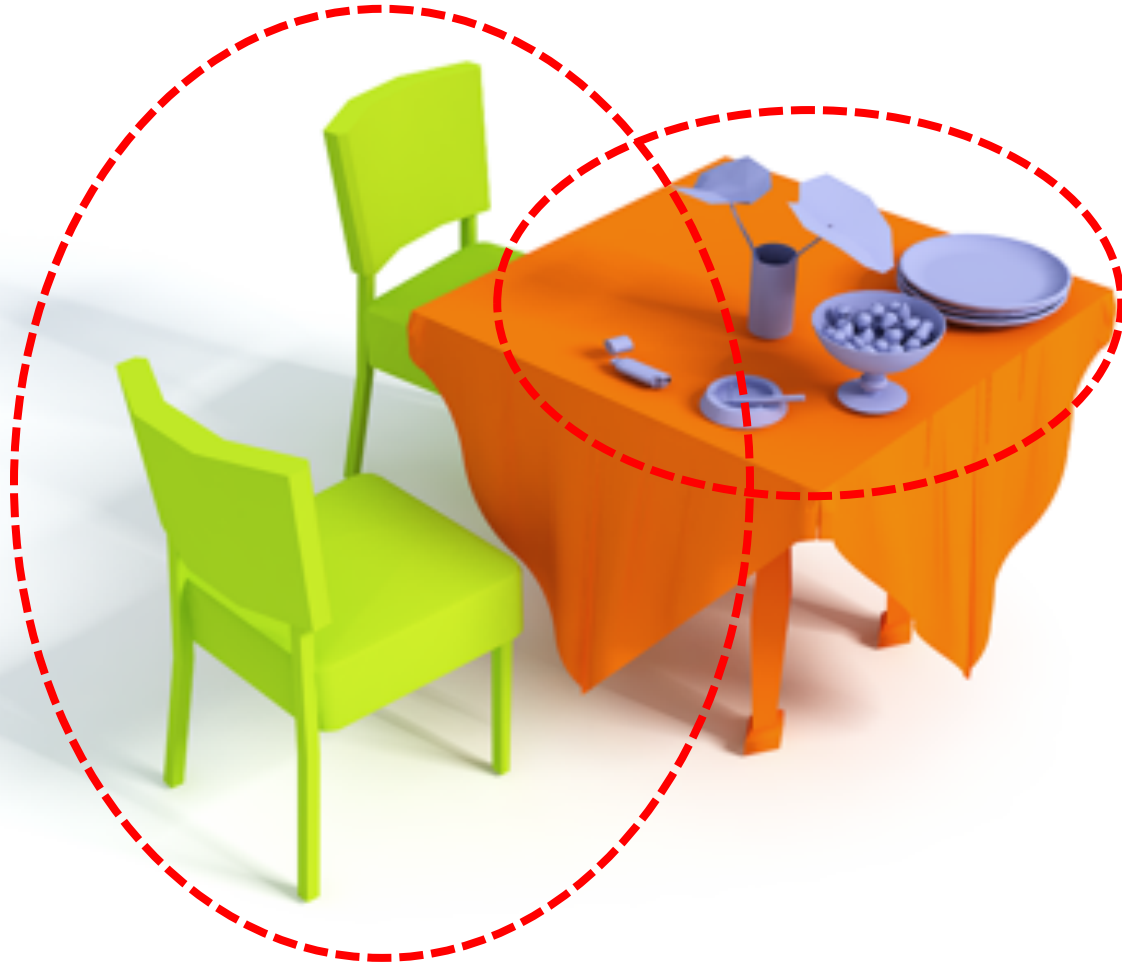
Atemporal interaction representation



RAID: A Relation-Augmented Image Descriptor
[GMW16]

3D RAID
[HLK*17]

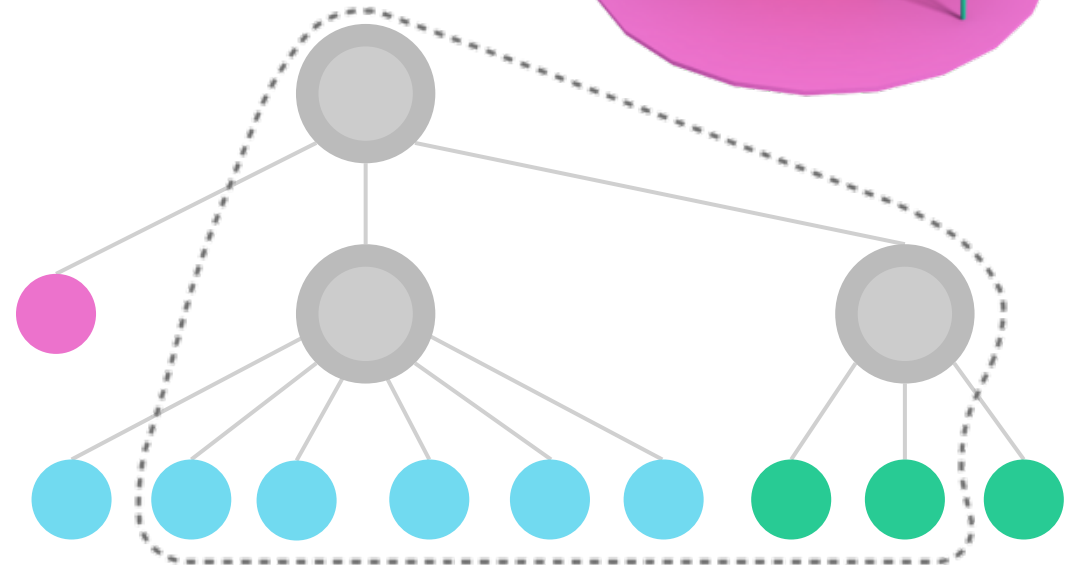
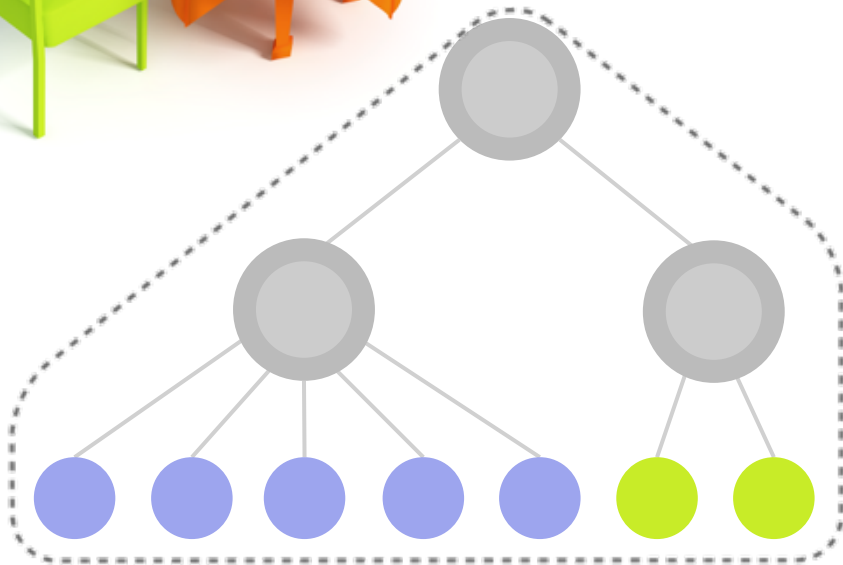
Atemporal multi-interaction organization



Interaction context (ICON)

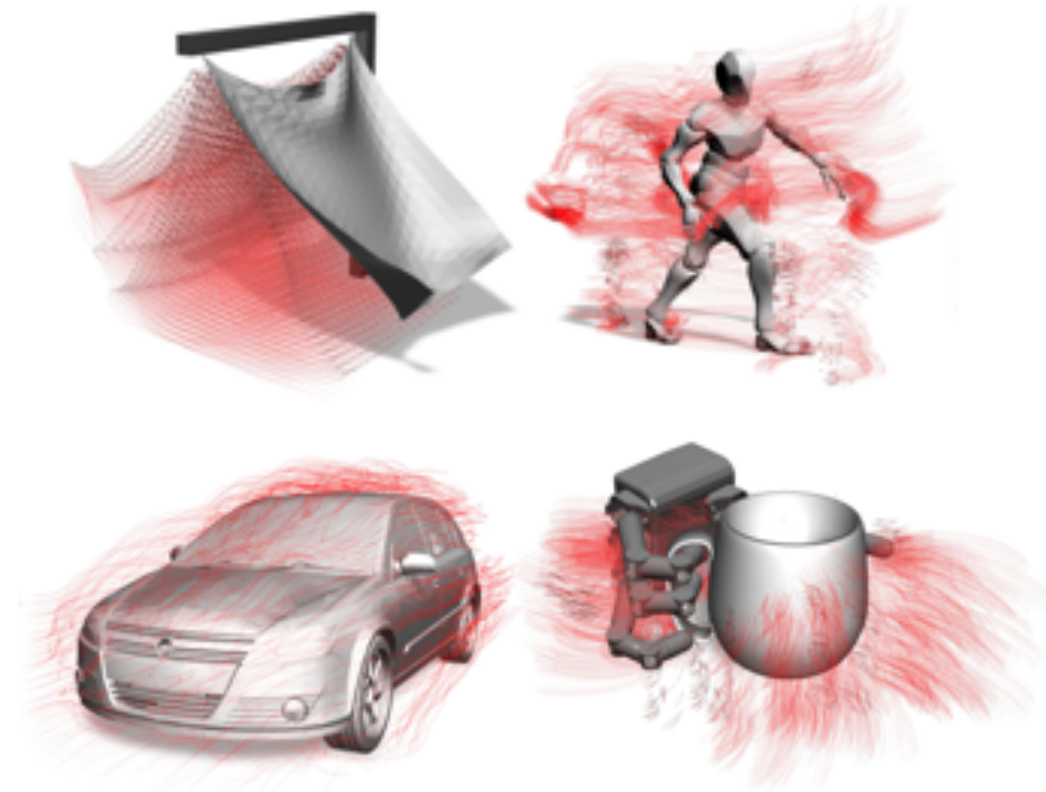
[HZvK*15]

Atemporal multi-interaction organization



Geometry + interaction methods

- **Handcrafted descriptors**
 - Atemporal interaction
 - **Time-varying interaction**
- **Supervised learning**
 - Object-level functionality
 - Discriminative recognition
 - Generative modeling
 - Part-level functionality
 - Atemporal interaction
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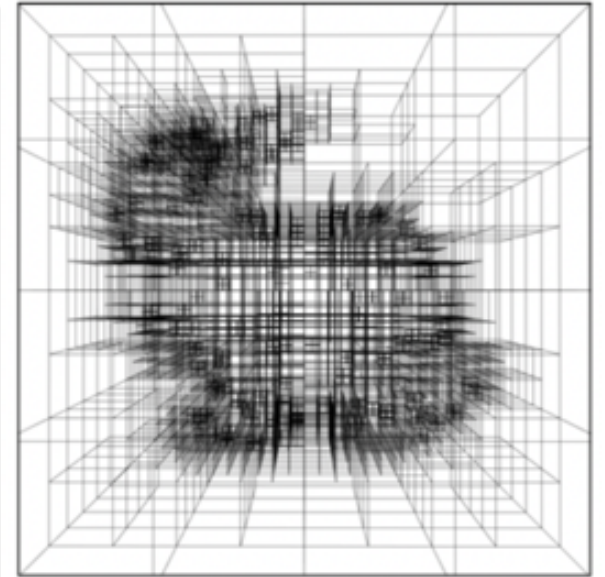


[PKH*17]

Time-varying interaction representation



Motion particles



Sensor regions

Interaction Landscapes descriptor

[PKH*17]

Application: interaction-based retrieval

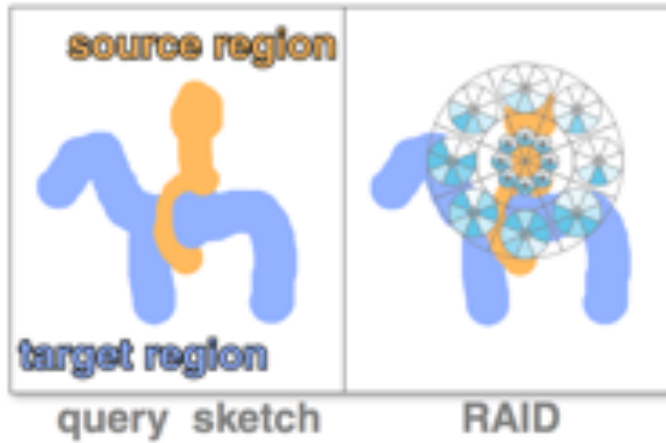


image retrieval
→



RAID
[GMW16]



ICON [HZvK*15]



Interaction Landscapes descriptor [PKH*17]

Functionality recognition



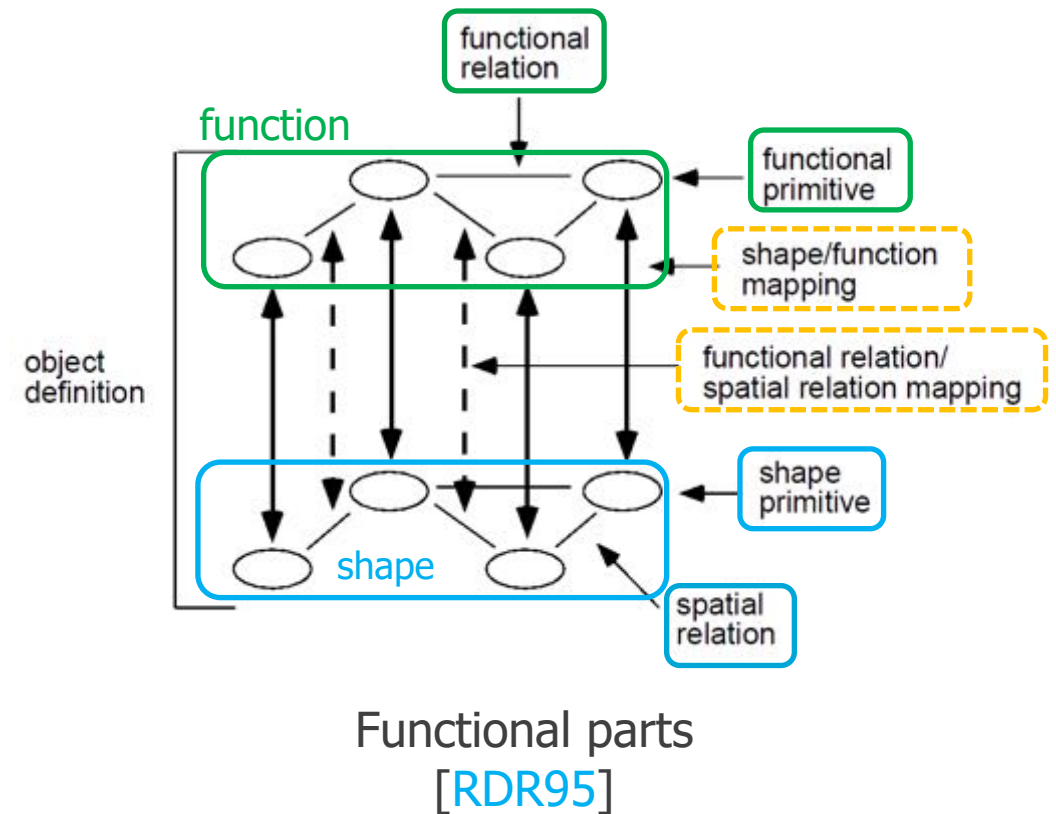
- Backpack
- Chair
- Drying Rack
- Handcart
- Hook



- Handcrafted descriptors
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- Handcrafted descriptors
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Object-level functionality recognition



Learning how objects function via co-analysis of interactions

[HvKW*16]

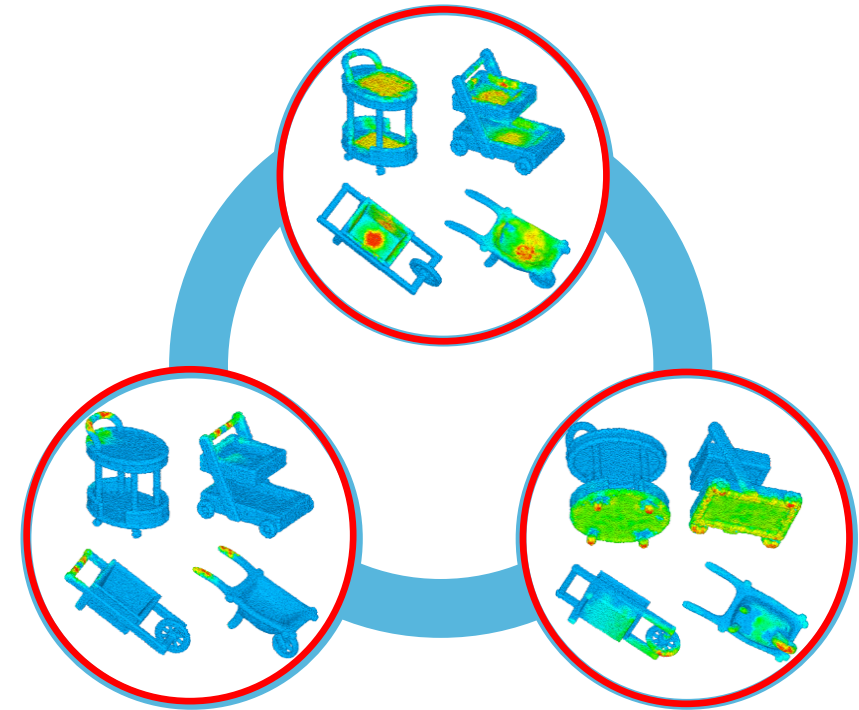
Object-level functionality recognition



Learning how objects function via co-analysis of interactions

[HvKW*16]

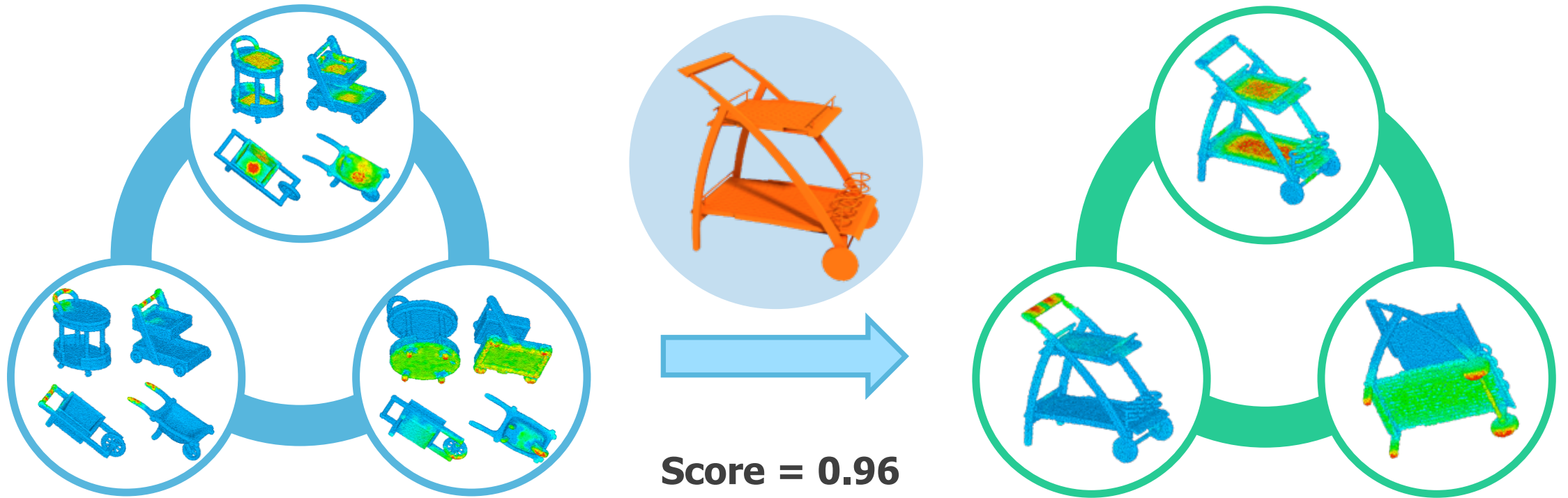
Object-level functionality recognition



Learning how objects function via co-analysis of interactions

[HvKW*16]

Object-level functionality recognition



Learning how objects function via co-analysis of interactions

[HvKW*16]

Application: function enhancement



Learning how objects function via co-analysis of interactions

[HvKW*16]

Generative model



Object usage hallucination

Functionality recognition and context generation



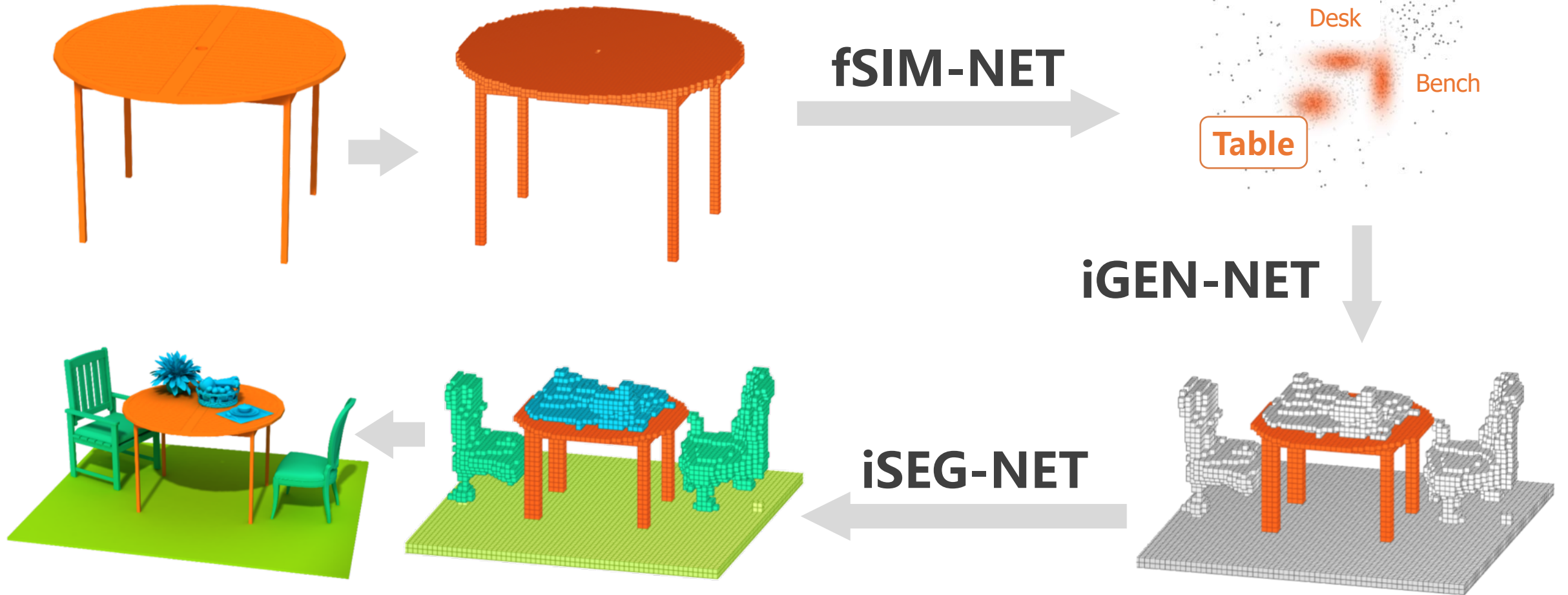
Table



Desk



PG-DNN

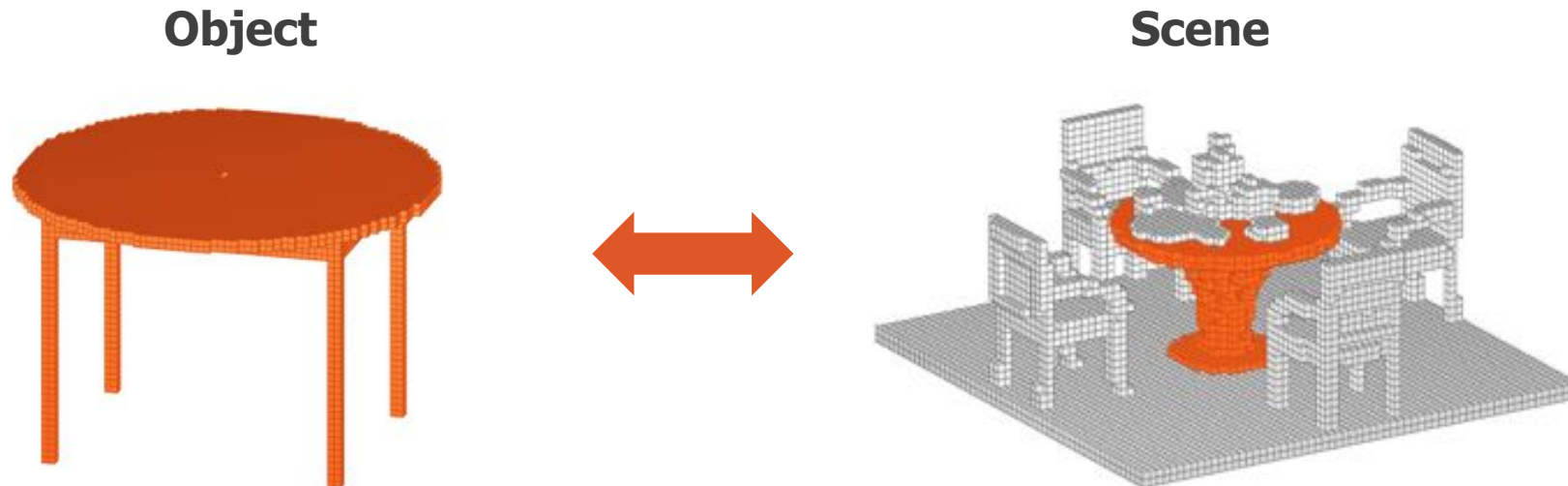


Predictive and Generative Neural Networks for Object Functionality

[[HYZ*18](#)]

Goal 1: Functionality prediction

- Map given object to scenes showing suitable functionalities
 - Learn a functional similarity measure between **objects** and **scenes**

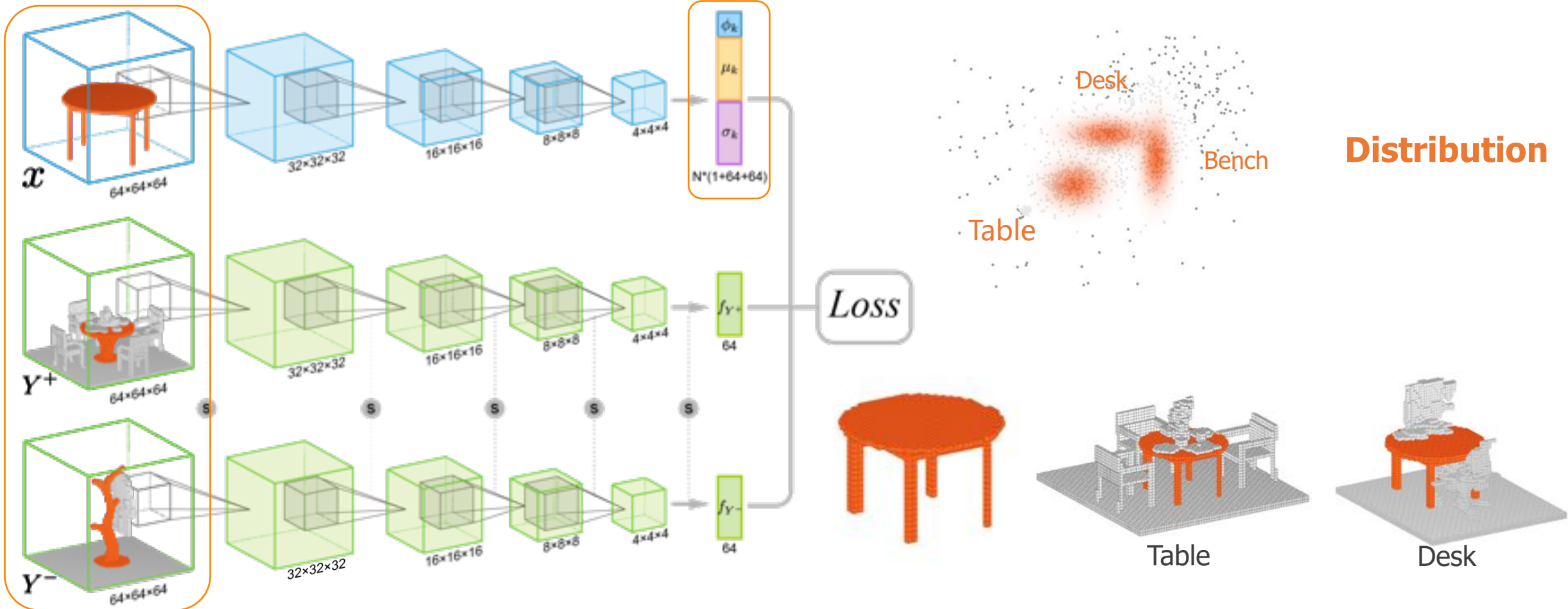


Predictive and Generative Neural Networks for Object Functionality

[[HYZ*18](#)]

fSIM-NET

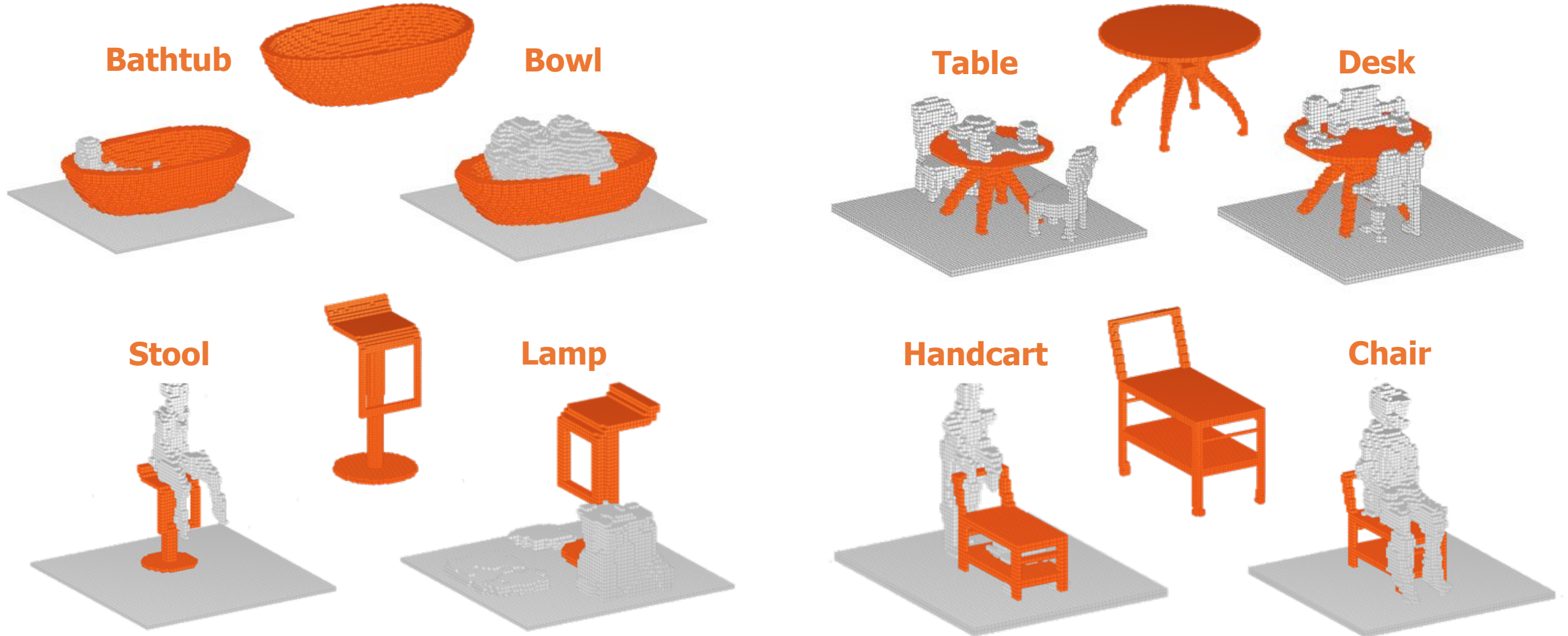
Multiple functionalities



Predictive and Generative Neural Networks for Object Functionality

[HYZ*18]

Multi-functionality

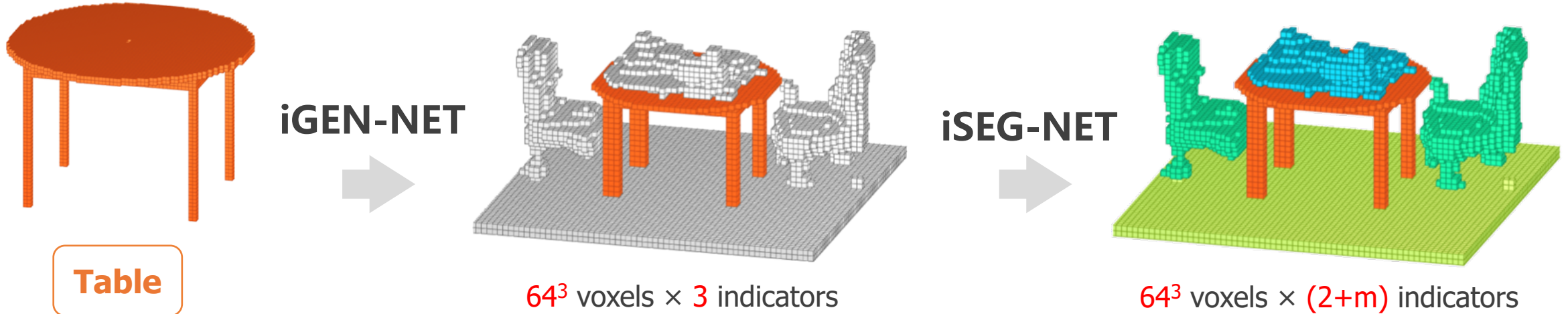


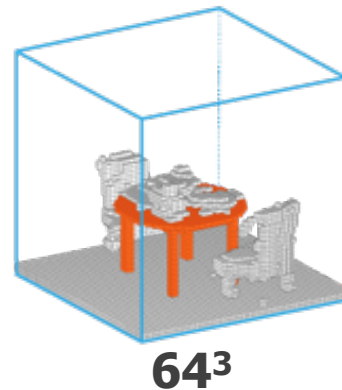
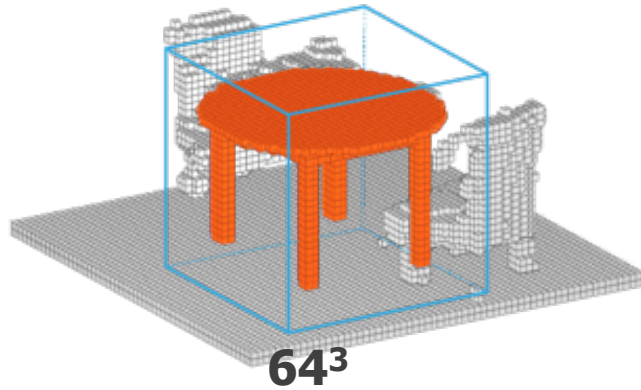
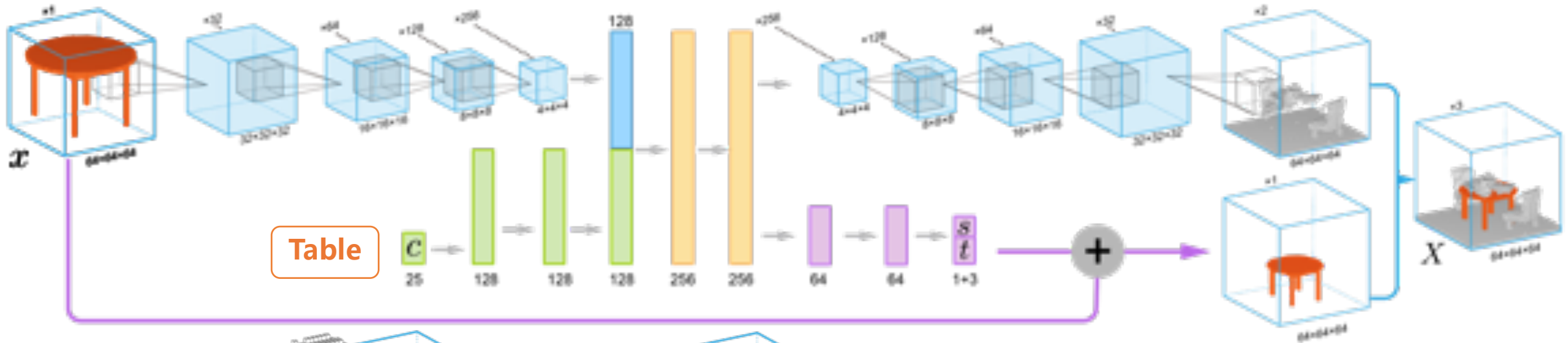
Predictive and Generative Neural Networks for Object Functionality

[HYZ*18]

Goal 2: Object usage hallucination

- Achieve into two steps: context generation and segmentation

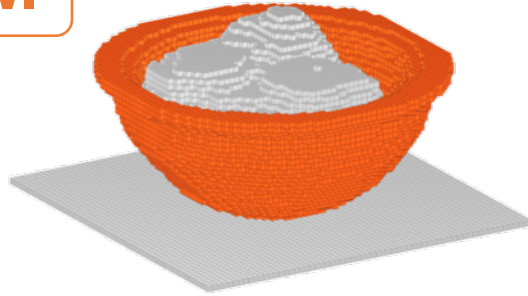
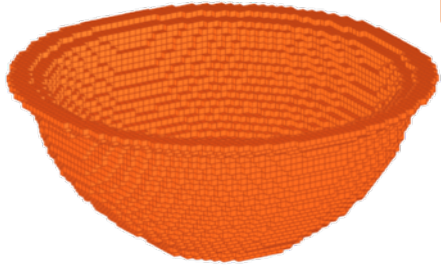




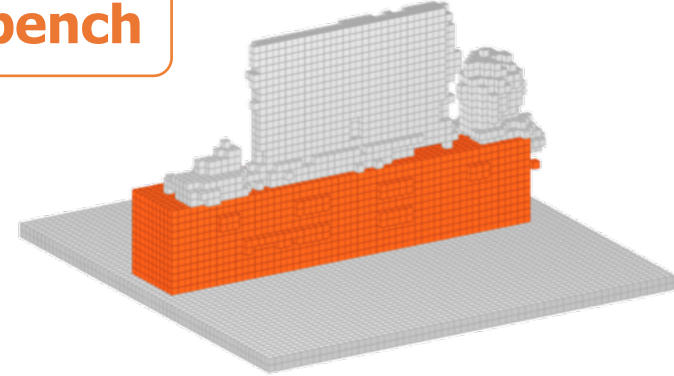
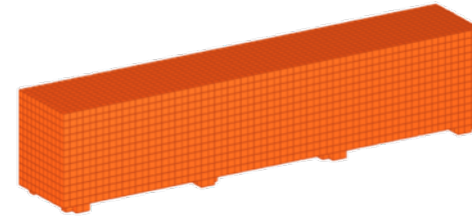
Central Object
Scaled and Translated

Generation results

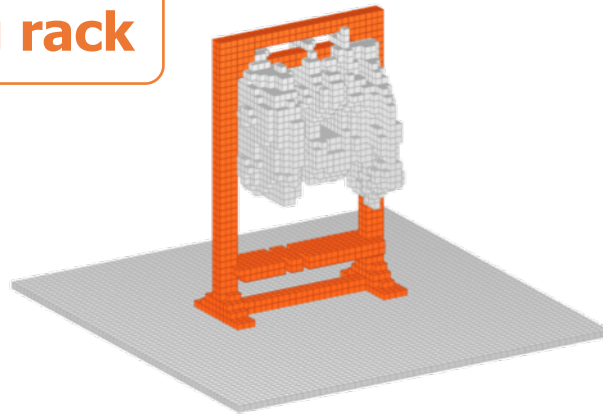
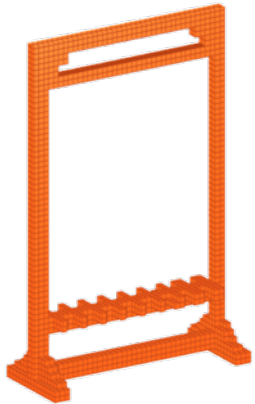
Bowl



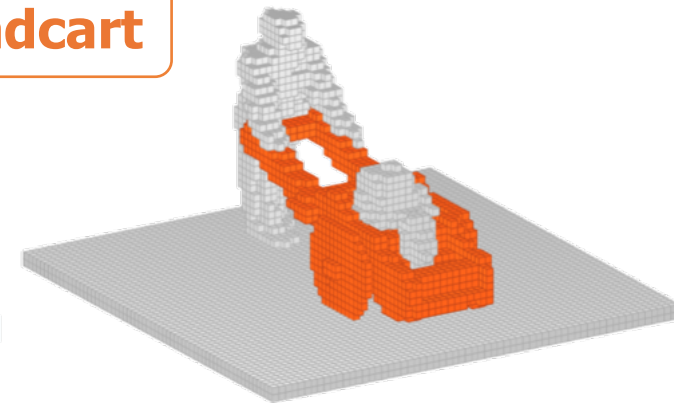
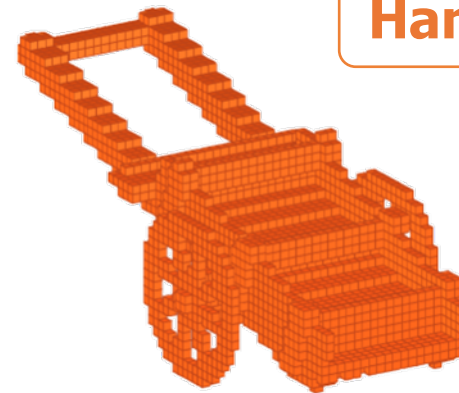
TV bench

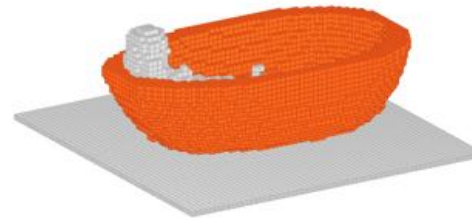
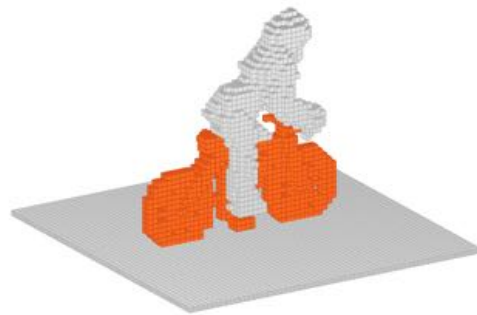
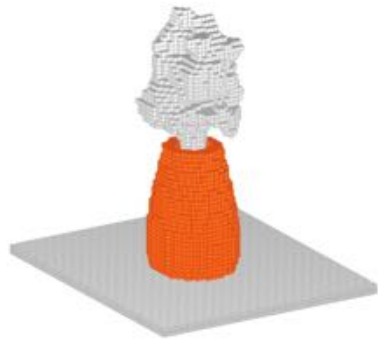
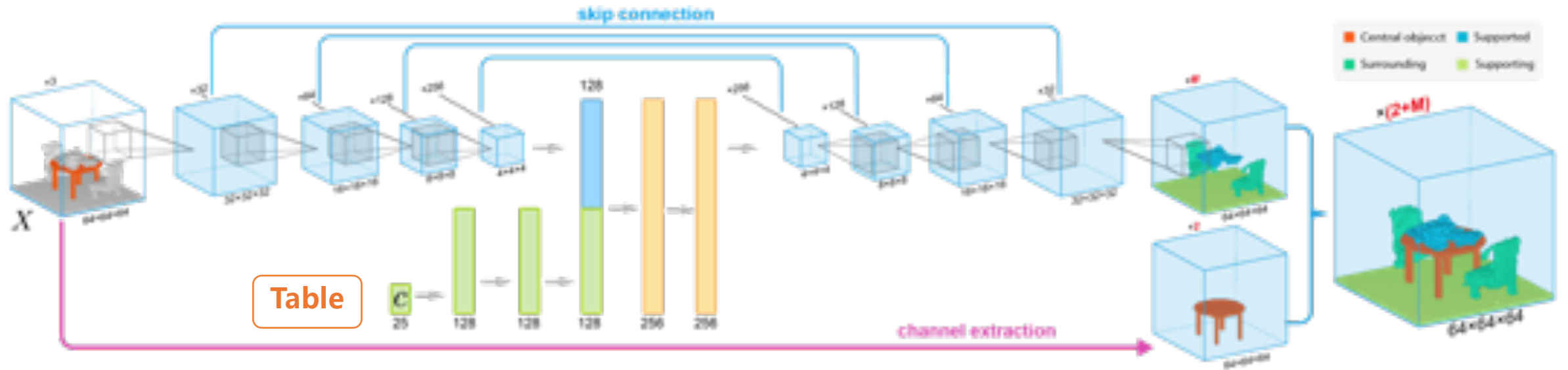


Drying rack



Handcart

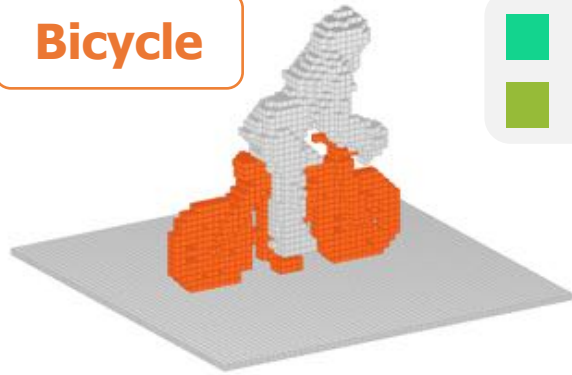




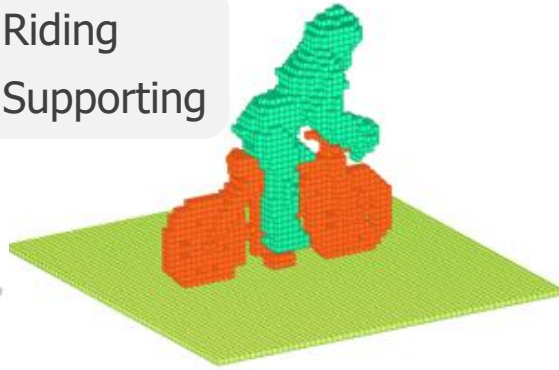
Central Object Fixed

Segmentation results

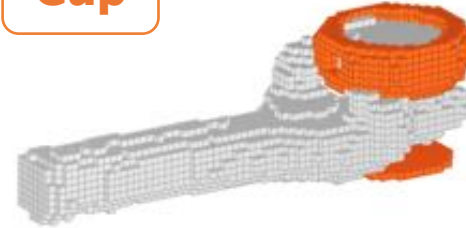
Bicycle



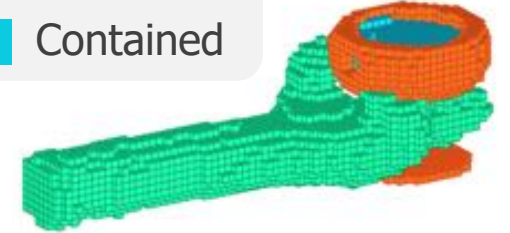
- Riding
- Supporting



Cup



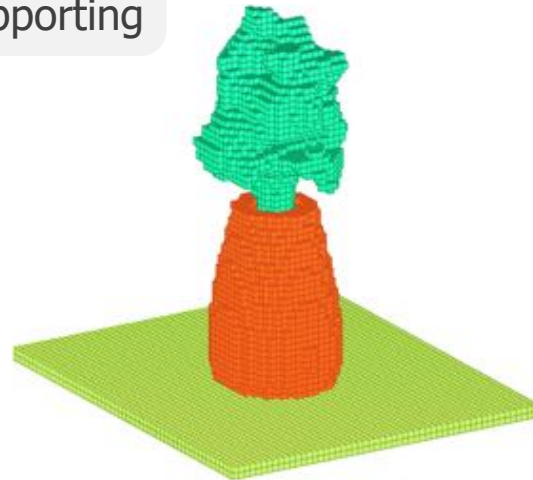
- Holding
- Contained



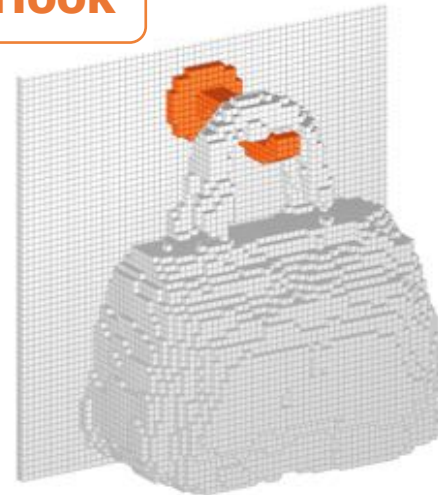
Vase



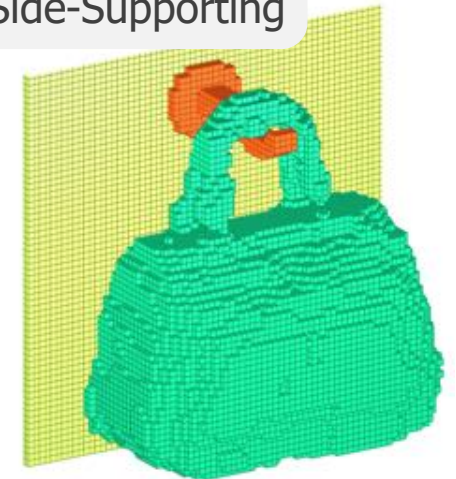
- Contained
- Supporting



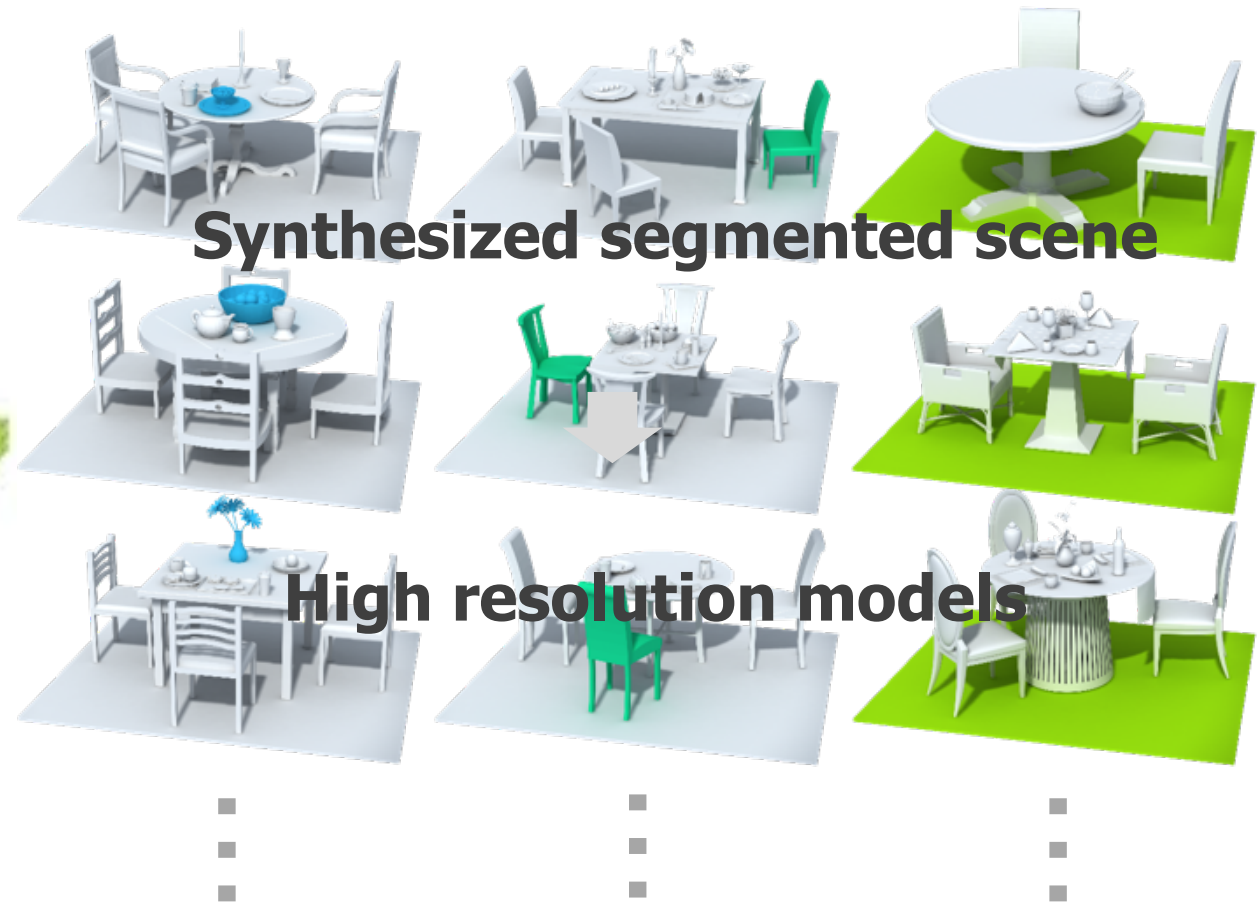
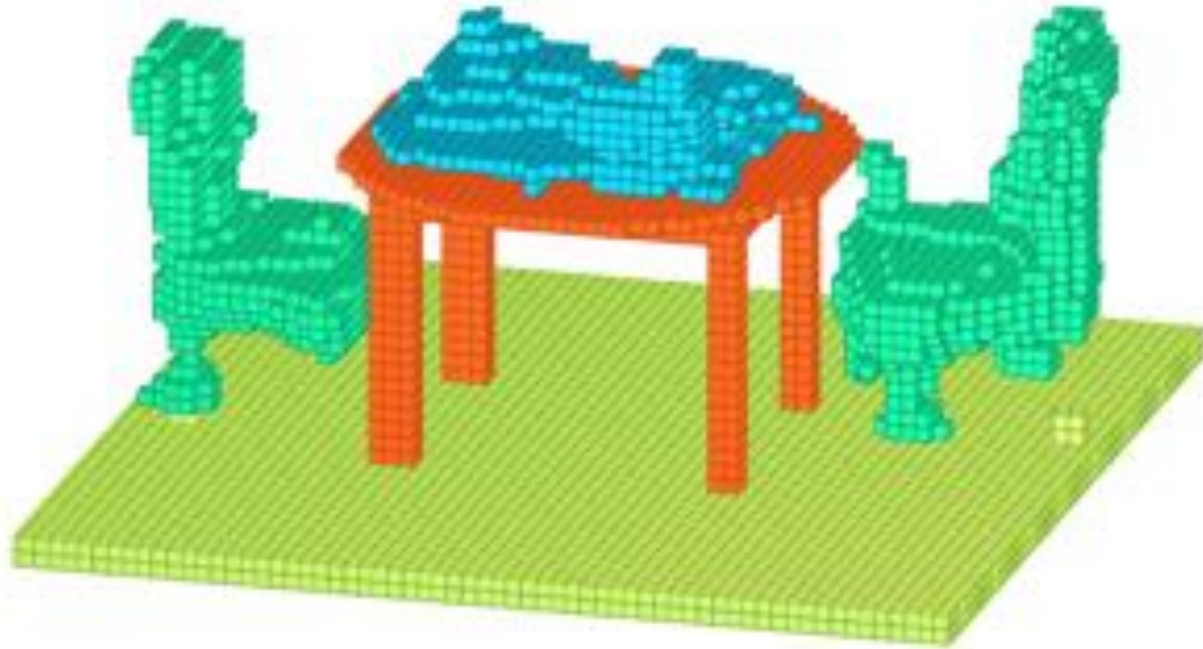
Hook



- Hanging
- Side-Supporting

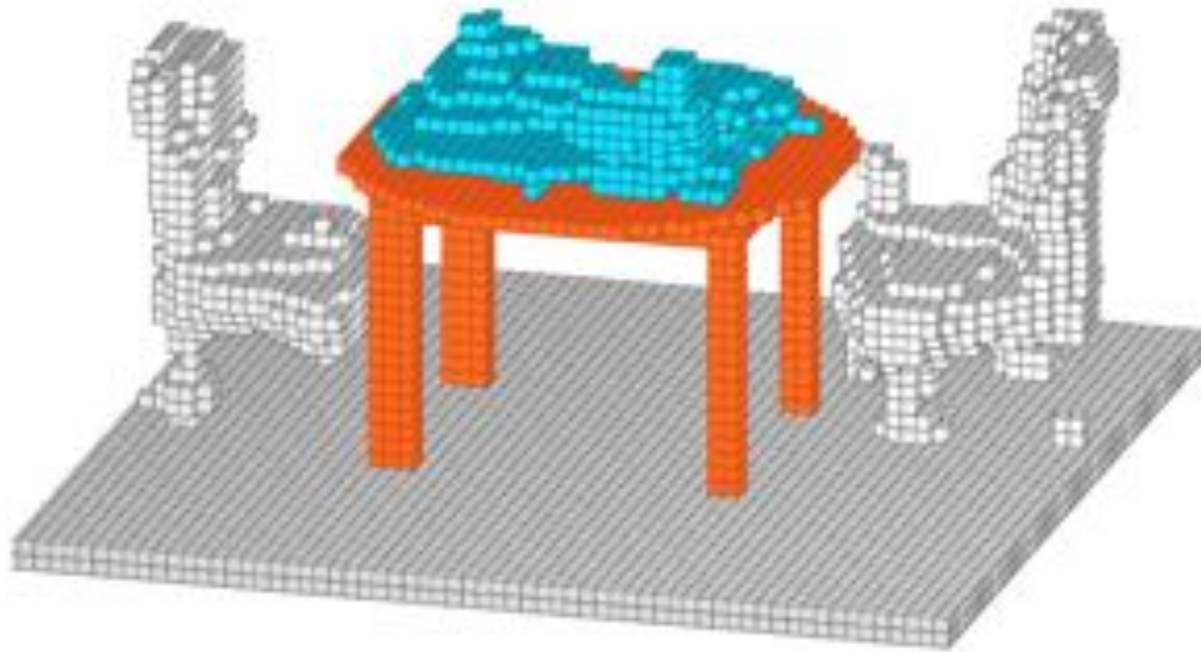


Scene refinement





Scene refinement

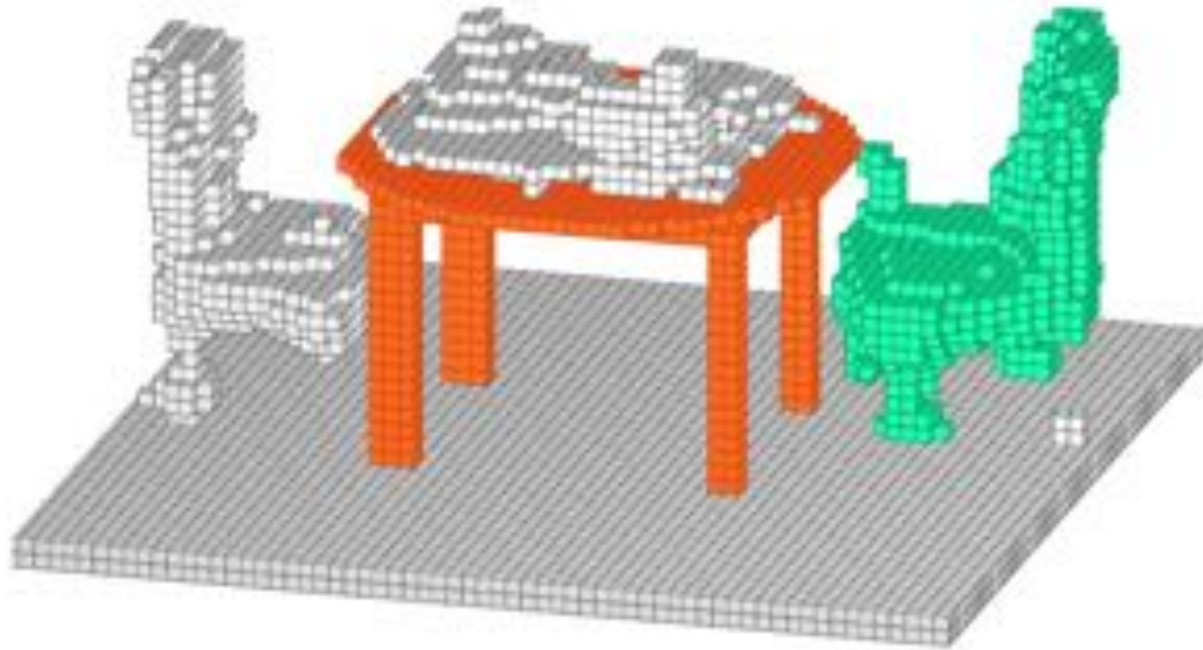


Predictive and Generative Neural Networks for Object Functionality

[HYZ*18]



Scene refinement

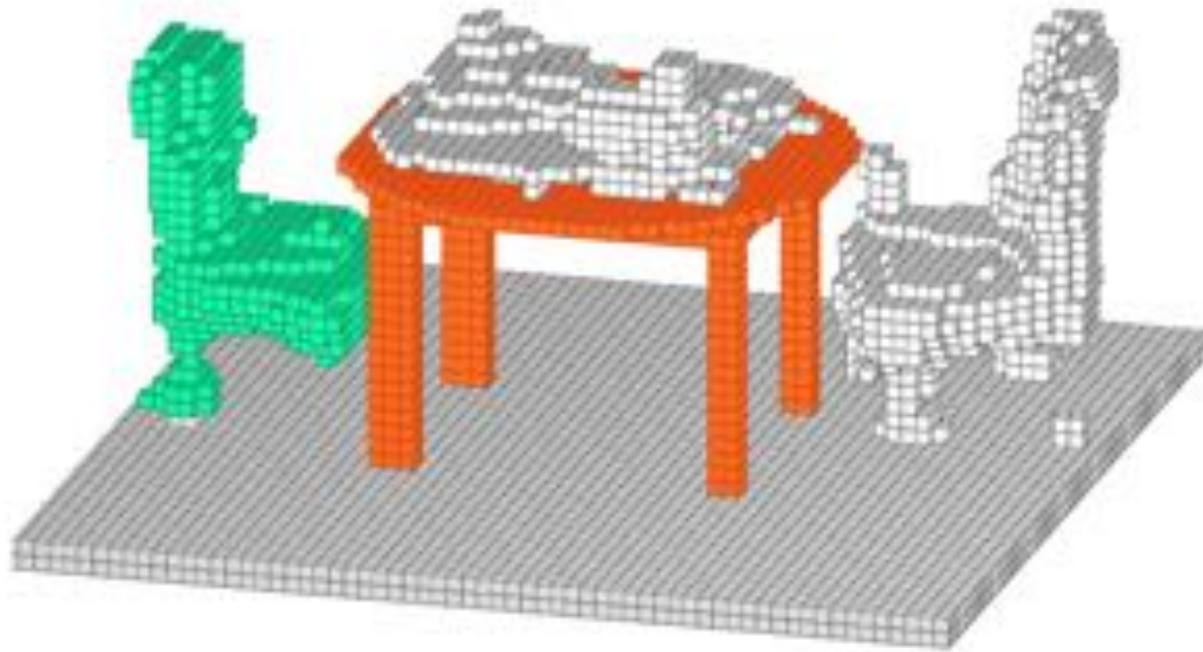


Predictive and Generative Neural Networks for Object Functionality

[HYZ*18]



Scene refinement

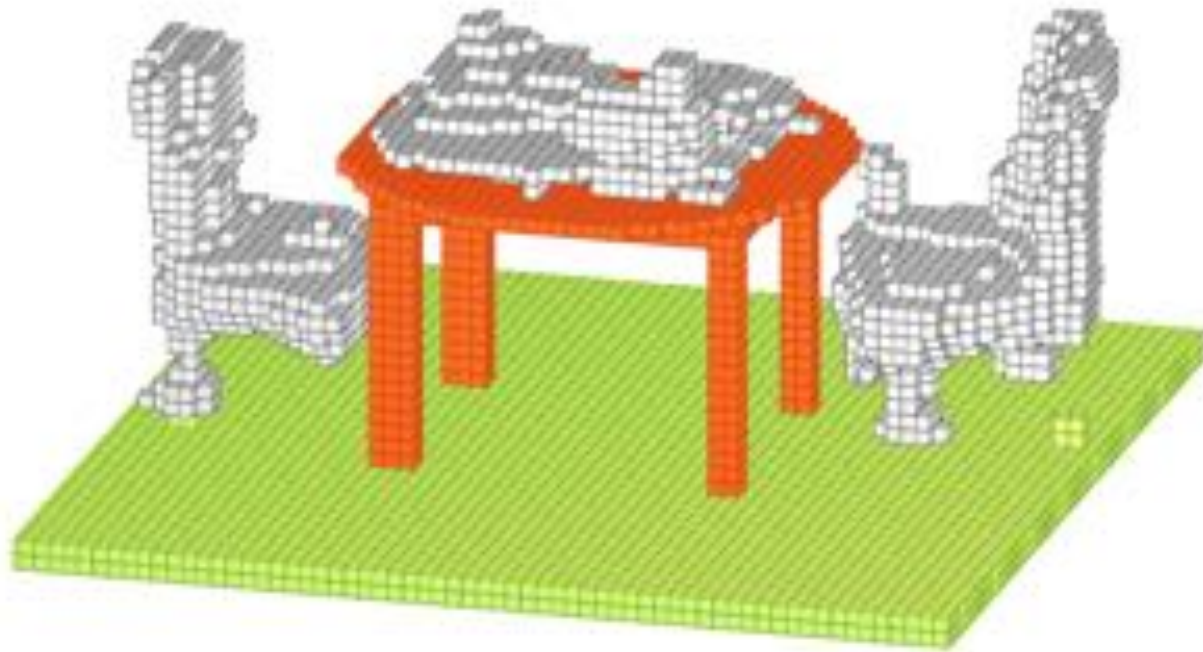


Predictive and Generative Neural Networks for Object Functionality

[HYZ*18]



Scene refinement

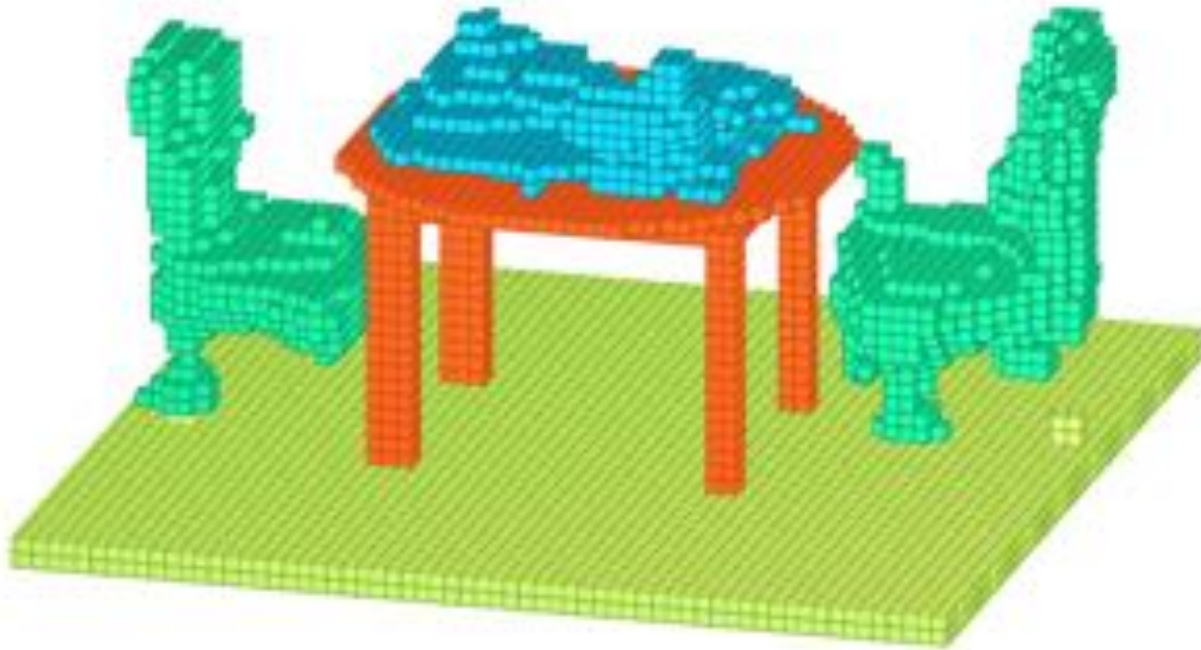


Predictive and Generative Neural Networks for Object Functionality

[[HYZ*18](#)]

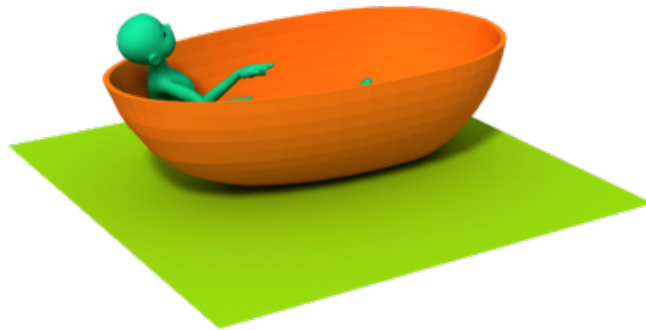
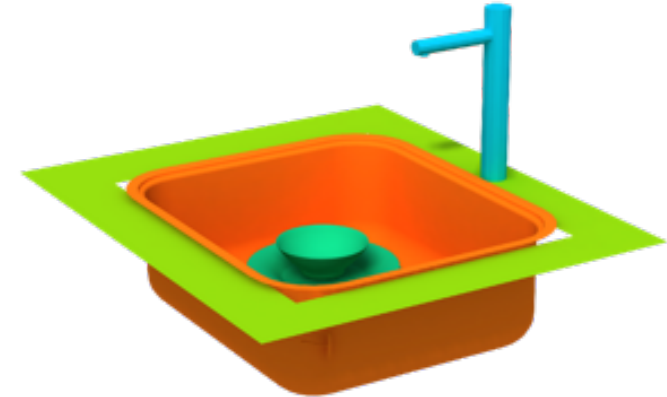
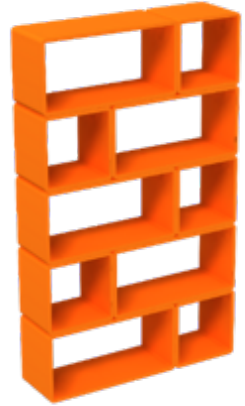


Scene refinement



Predictive and Generative Neural Networks for Object Functionality

[HYZ*18]



Predictive and Generative Neural Networks for Object Functionality

[HYZ*18]

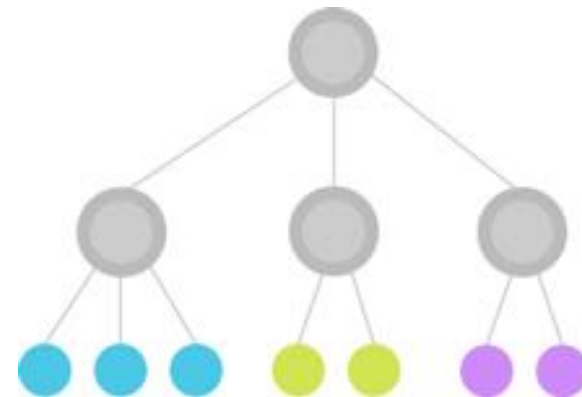
Final results



Predictive and Generative Neural Networks for Object Functionality

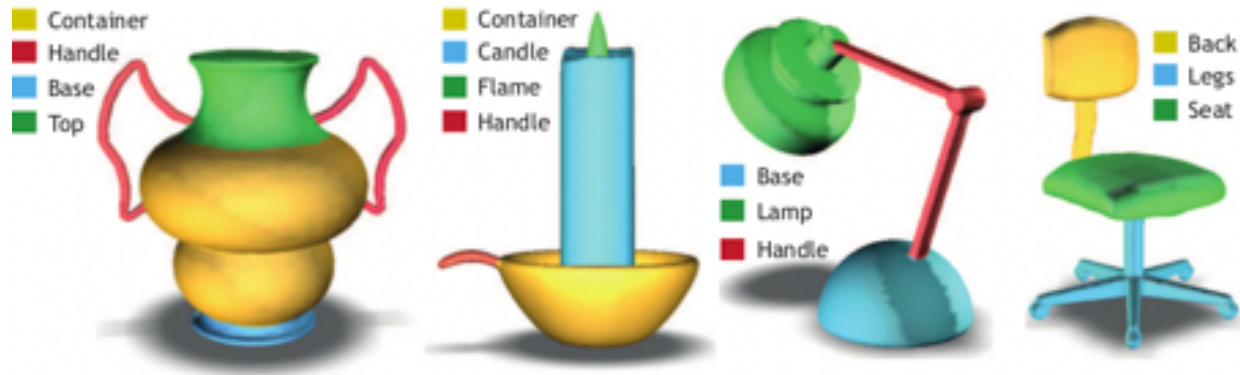
[HYZ*18]

- Handcrafted descriptors
 - Atemporal interaction
 - Time-varying interaction
- **Supervised learning**
 - Object-level functionality
 - Discriminative recognition
 - Generative modeling
 - **Part-level functionality**
 - Atemporal interaction
 - Time-varying interaction

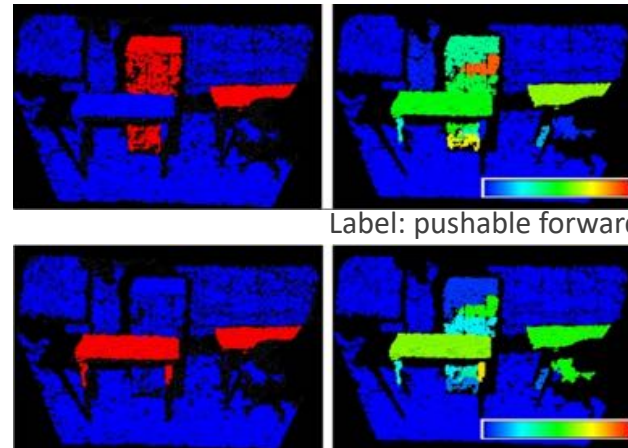


[HZvK*15]

Part-level semantic labeling (atemporal)



Segmentation and semantic labeling
[LMS13]

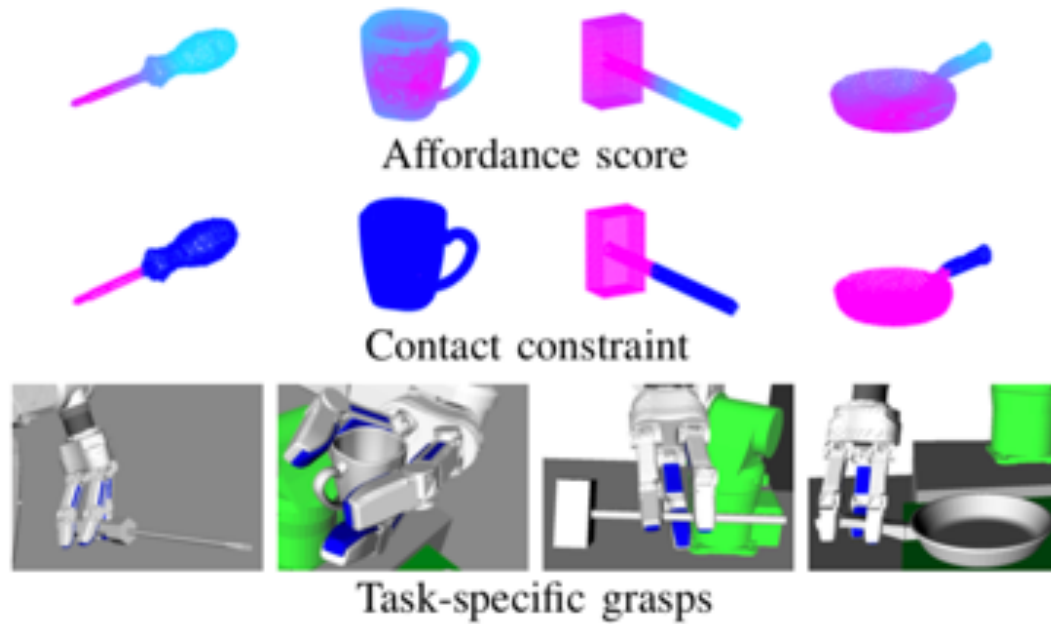


Label: pushable forward

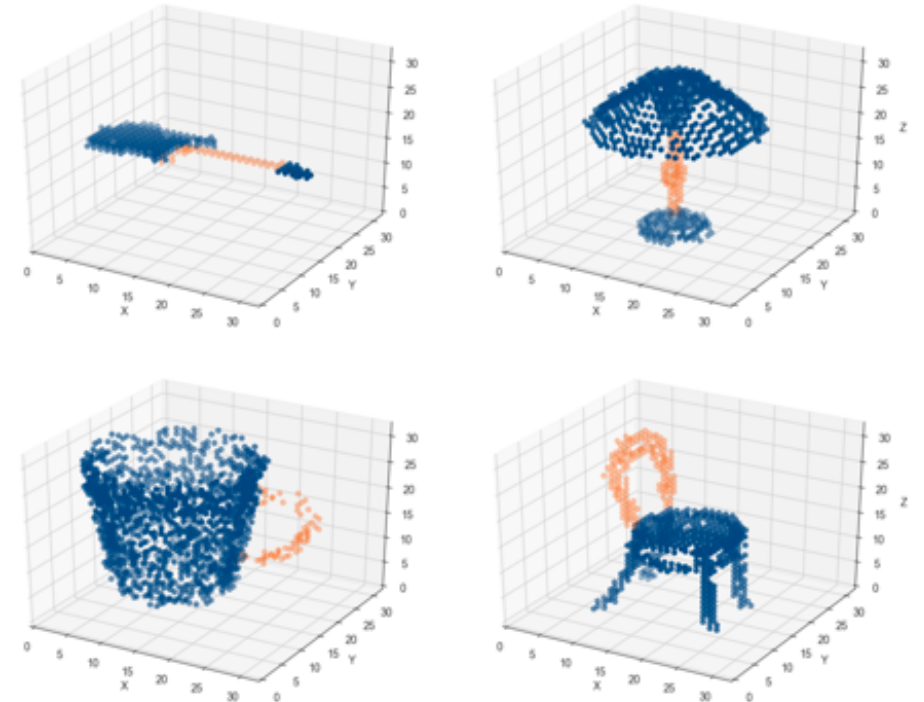
Label: liftable

Semantic labeling with object affordance
[KS14]

Part-level grasping affordance prediction (atemporal)



Affordance detection for task-specific grasping
[KSHK17]



Learning to grasp 3d objects
[LSK20]

Part-level mobility prediction (Time-varying interaction)



Static shape



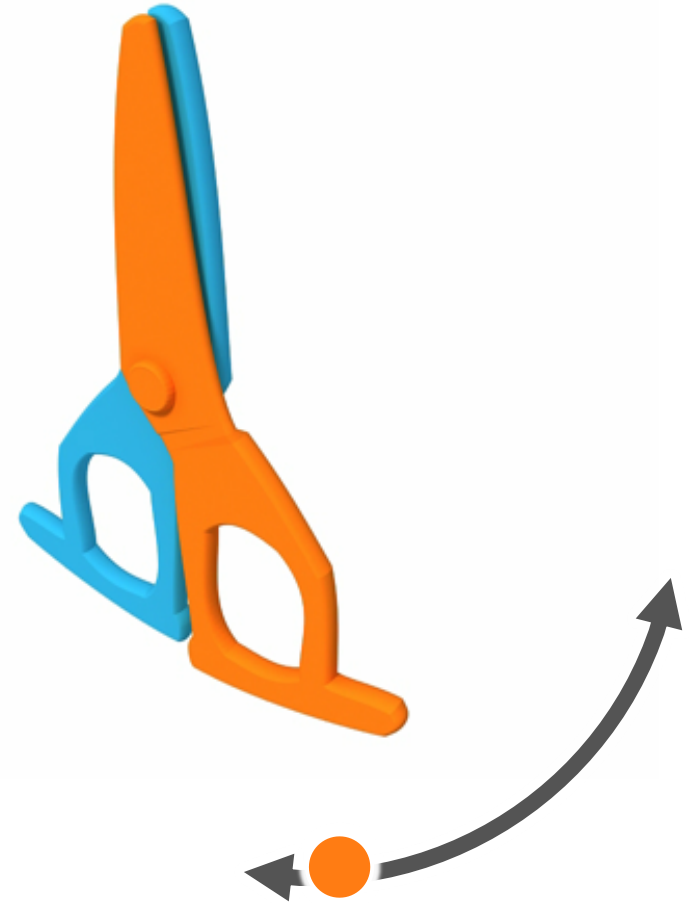
Pre-segmented
input



Dynamic motion

Learning to predict part mobility from a single static snapshot
[HLK*17]

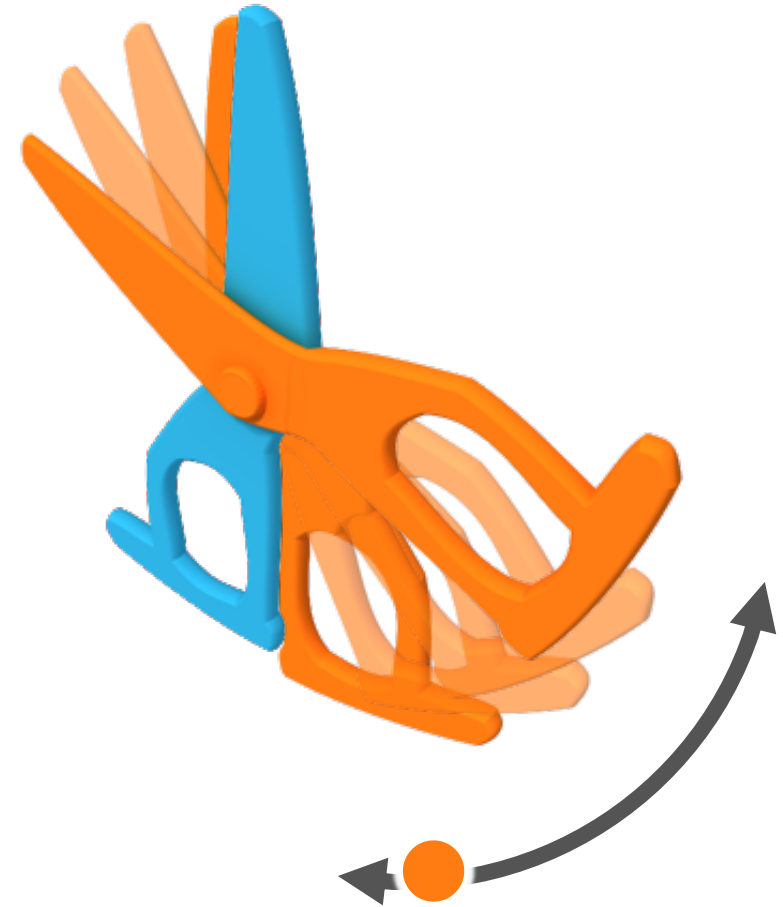
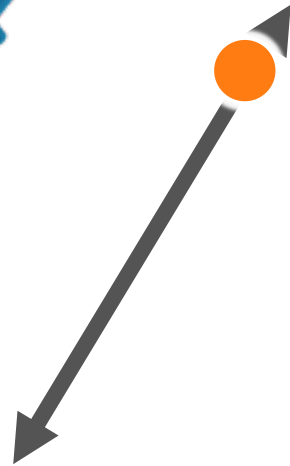
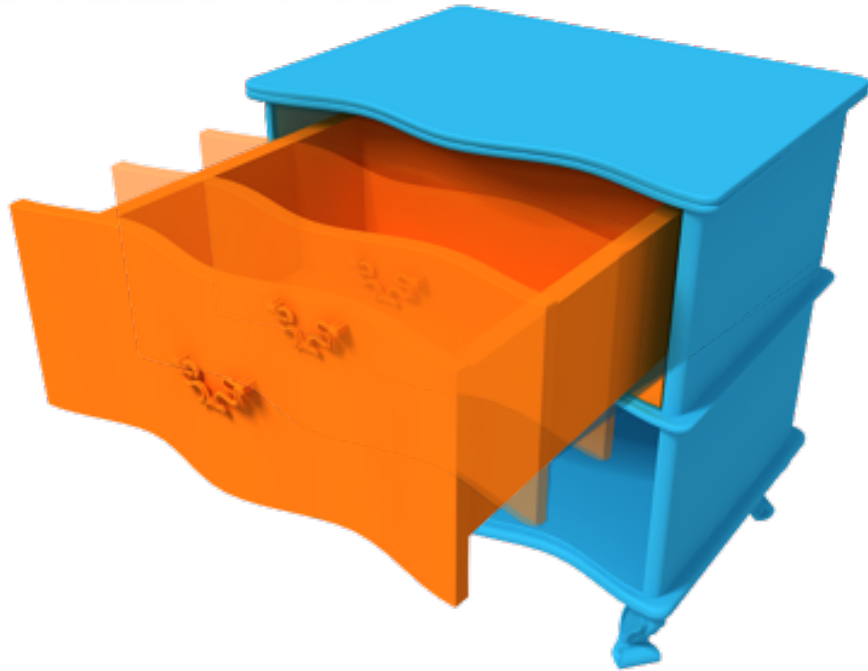
Key observation: linearity of motion



Learning to predict part mobility from a single static snapshot

[HLK*17]

Linearity of motion

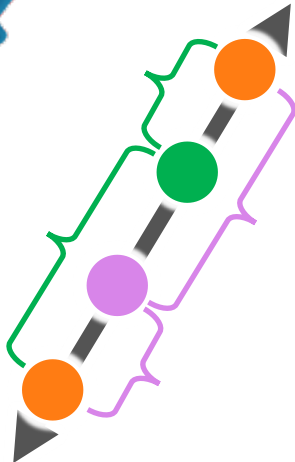
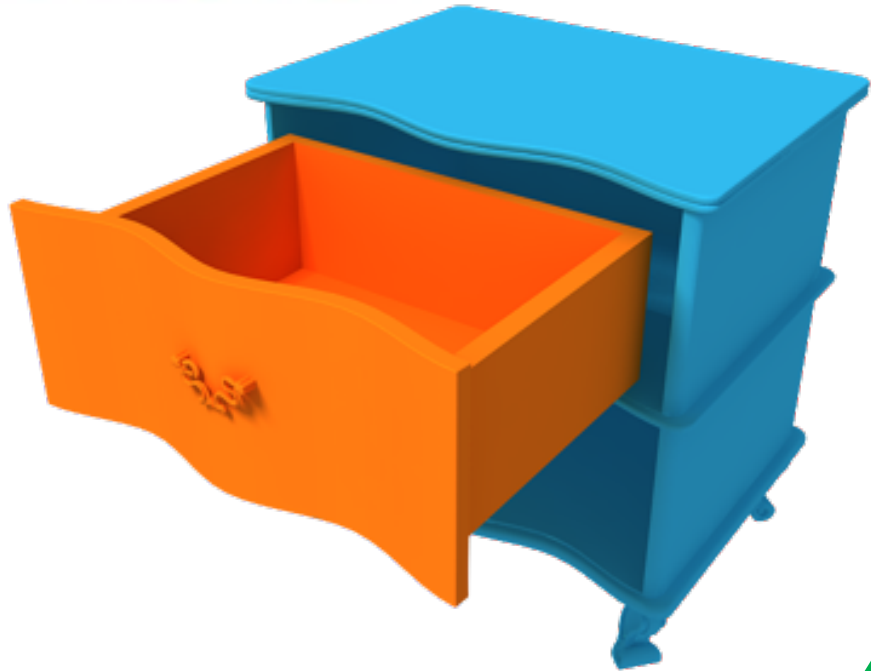


Learning to predict part mobility from a single static snapshot

[HLK*17]



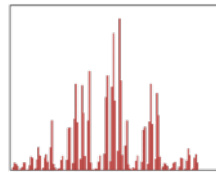
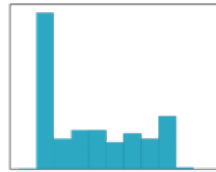
Start & end snapshots



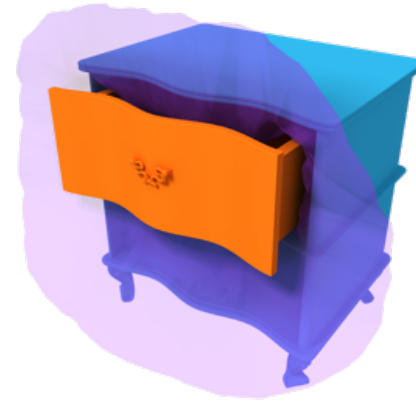
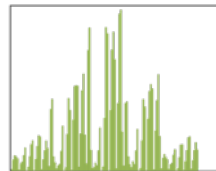
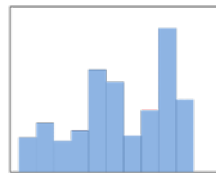
Learning to predict part mobility from a single static snapshot

[HLK*17]

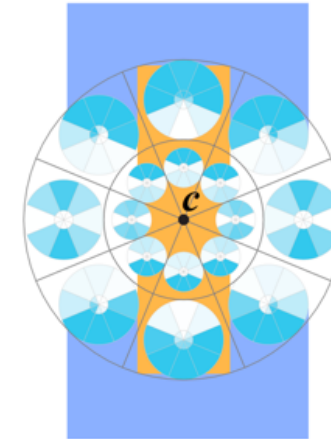
Snapshot descriptor



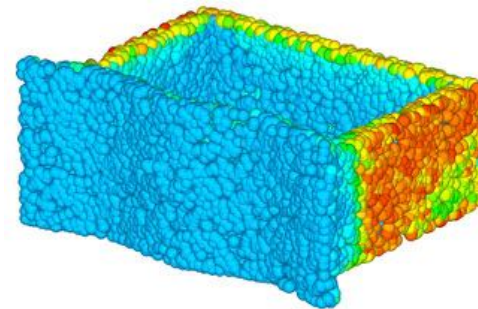
...



Interaction Bisector Surface
[Zhao et al. 2014]



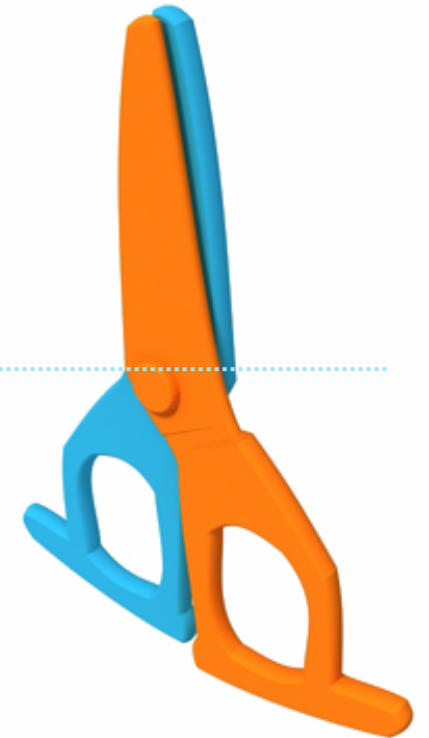
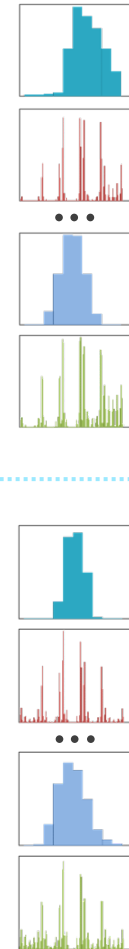
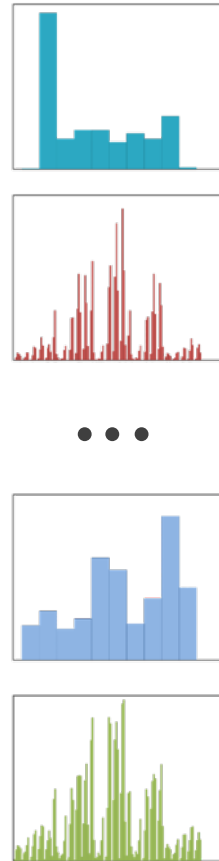
RAID-3D
[Guerrero et al. 2016]



Interaction Region
[Hu et al. 2015]

Learning to predict part mobility from a single static snapshot
[HLK*17]

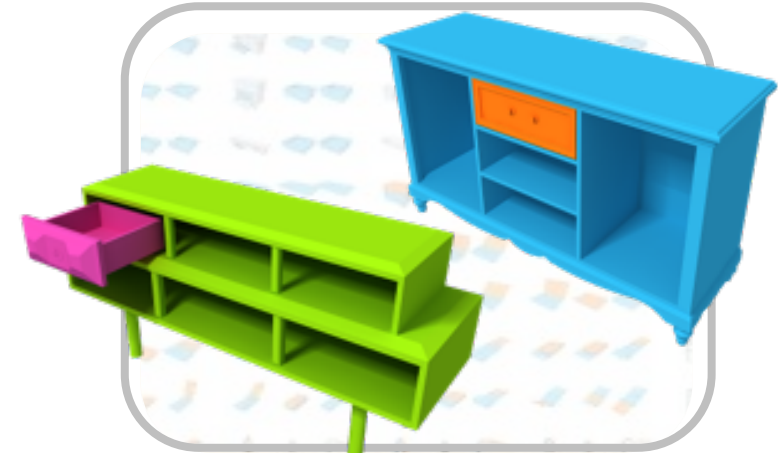
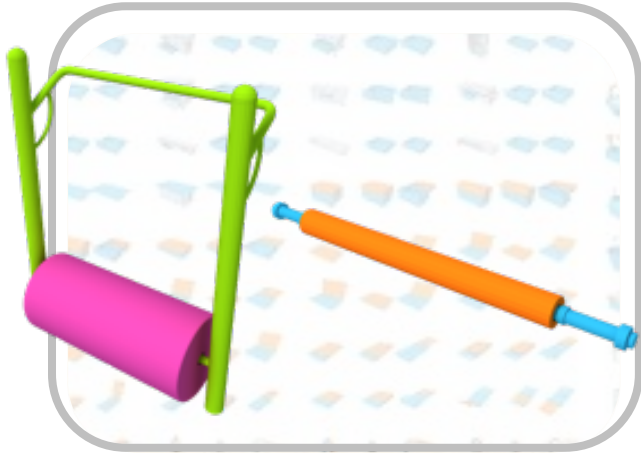
Snapshot-to-unit distance



Learning to predict part mobility from a single static snapshot

[HLK*17]

Nearest neighbor Retrieval



Learning to predict part mobility from a single static snapshot

[HLK*17]

Motion transfer



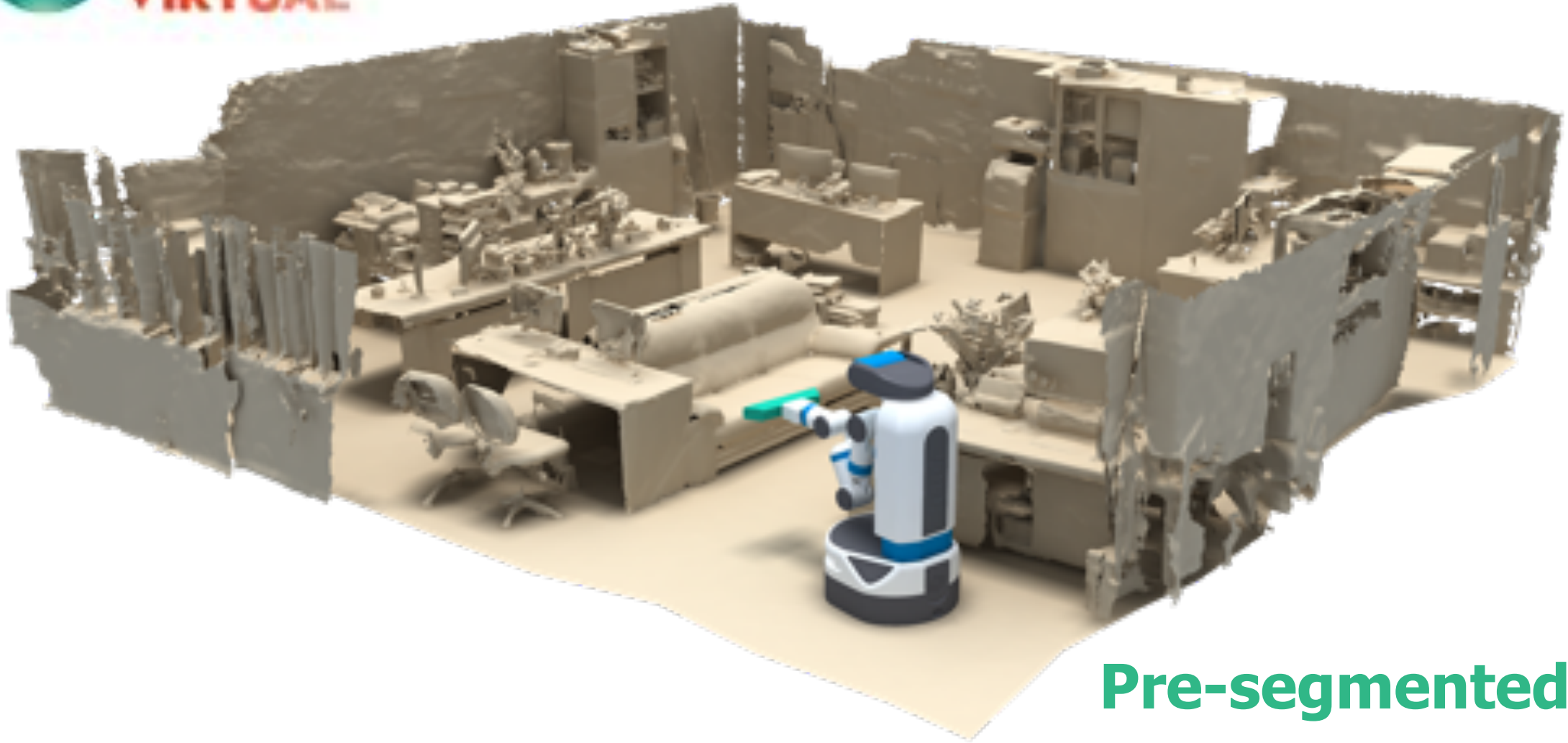
Learning to predict part mobility from a single static snapshot

[HLK*17]



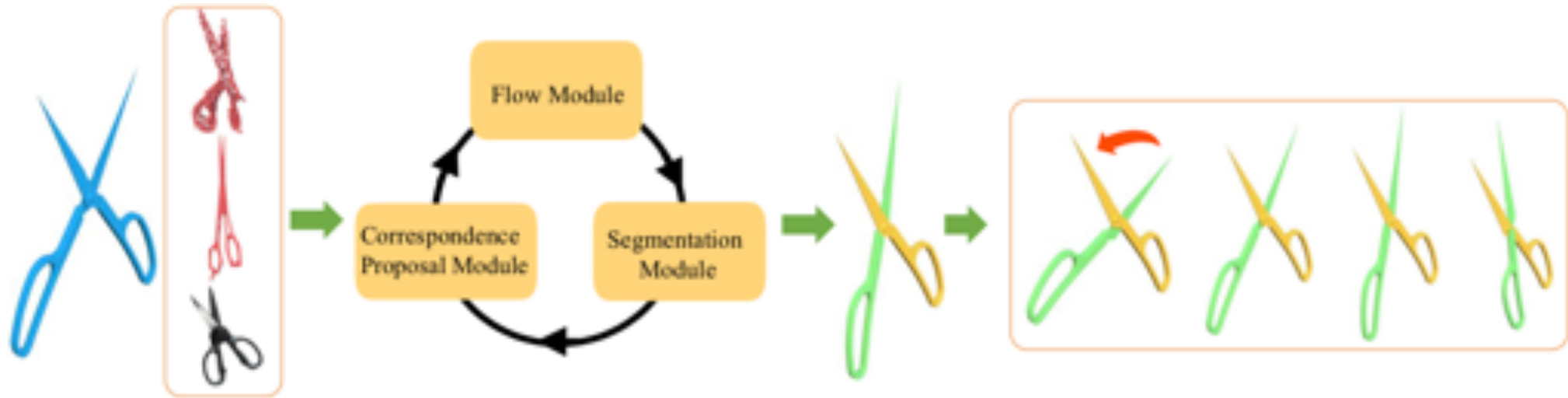
**SIGGRAPH
ASIA 2020
VIRTUAL**

Limitation



Pre-segmented X

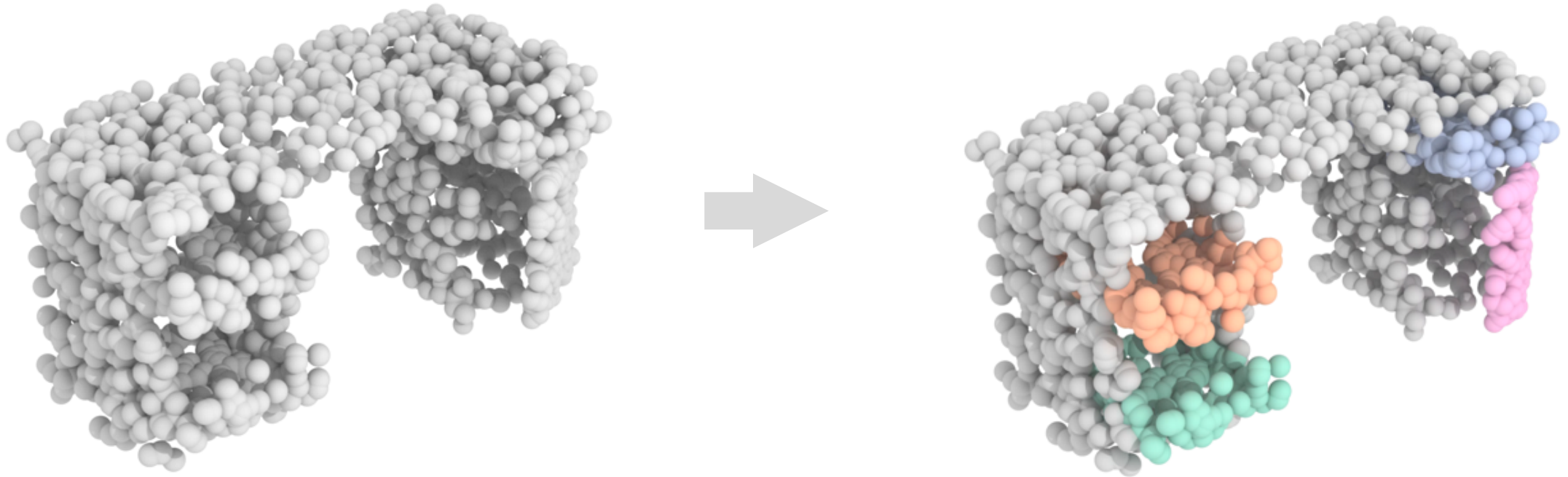
Part-level mobility prediction (Time-varying interaction)



Paired input

Deep part induction from articulated object pairs
[YHL*18]

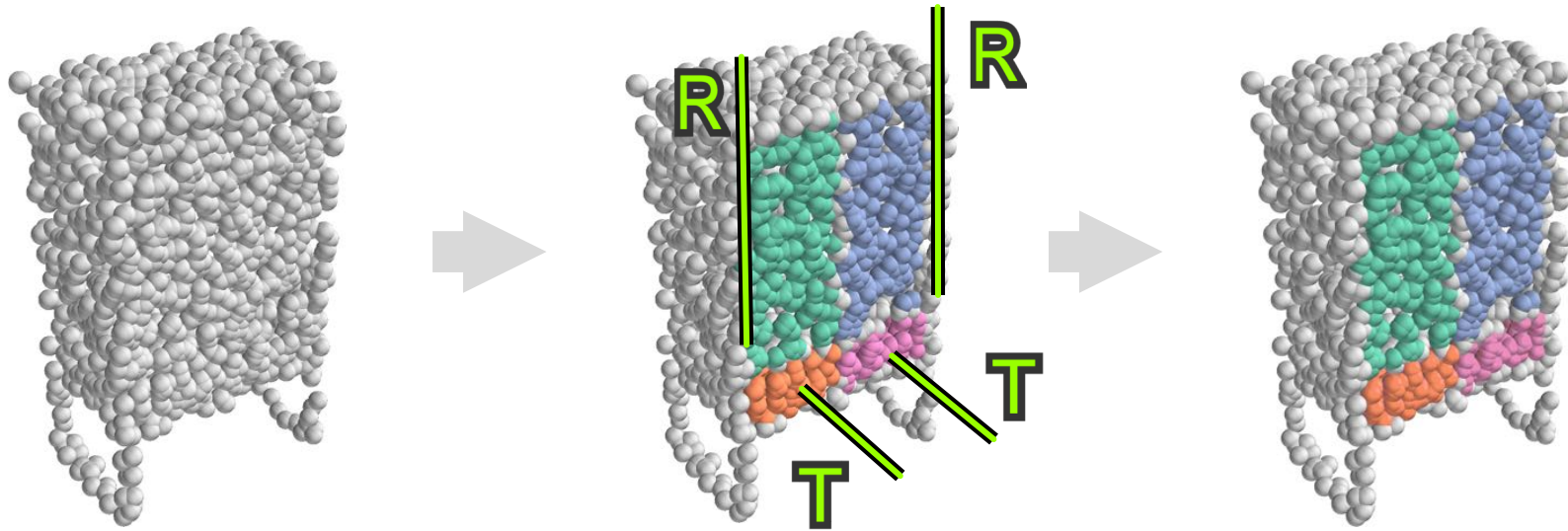
Part-level mobility prediction (Time-varying interaction)



single un-segmented partial

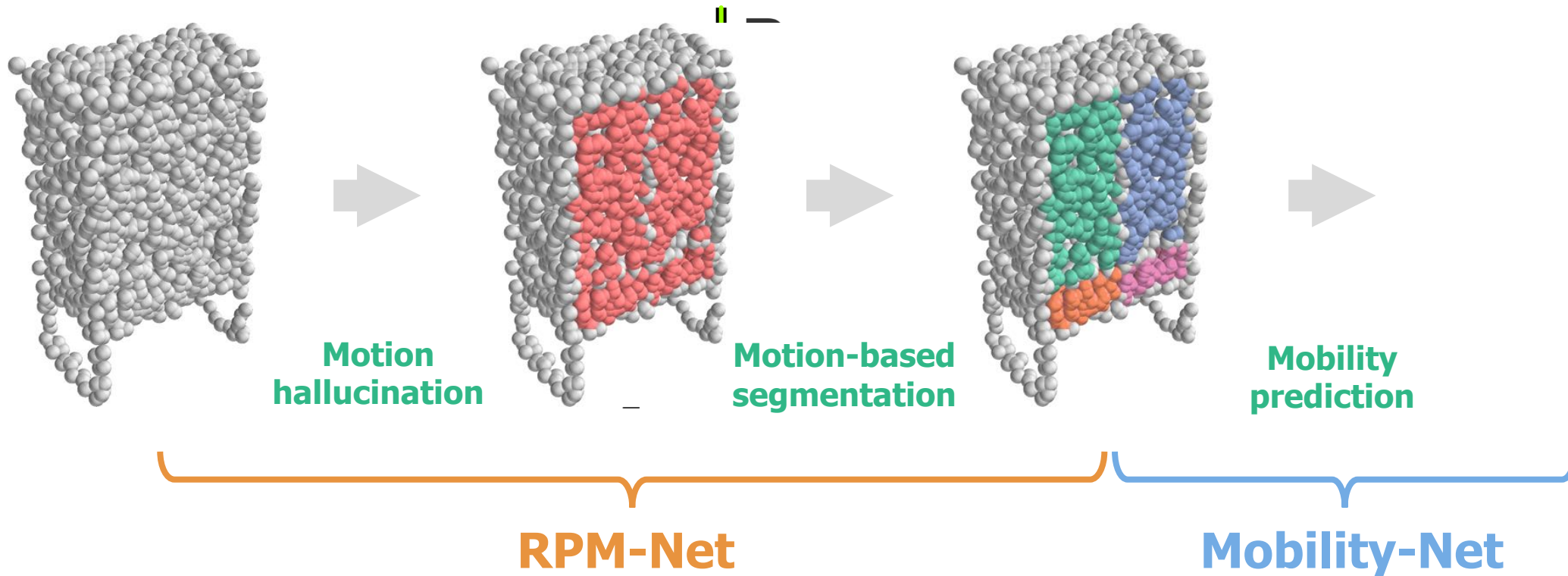
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Direct mobility prediction



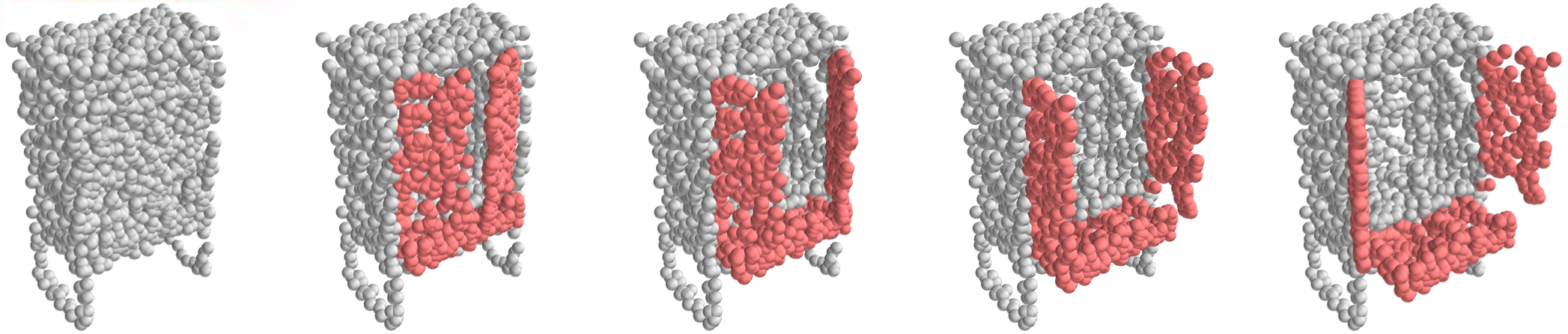
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Key contribution

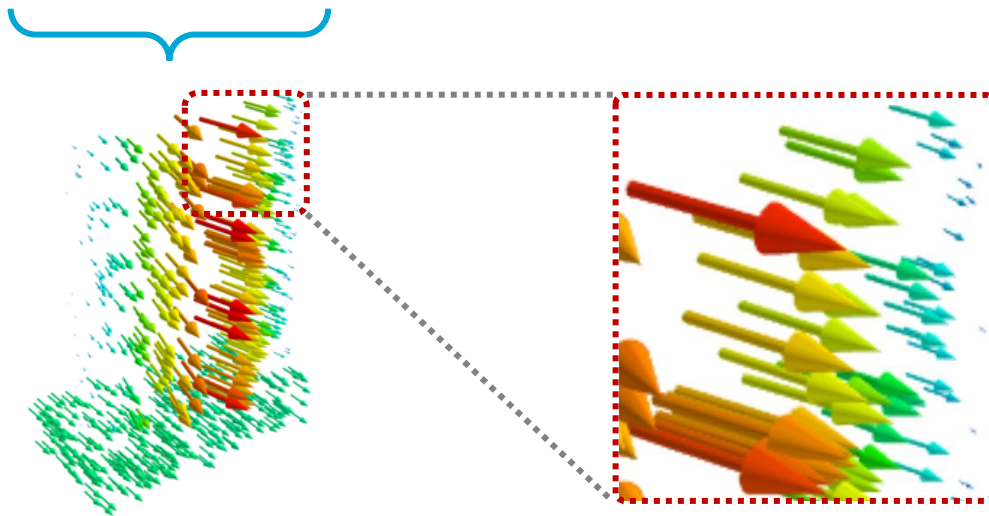


RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Motion displacement



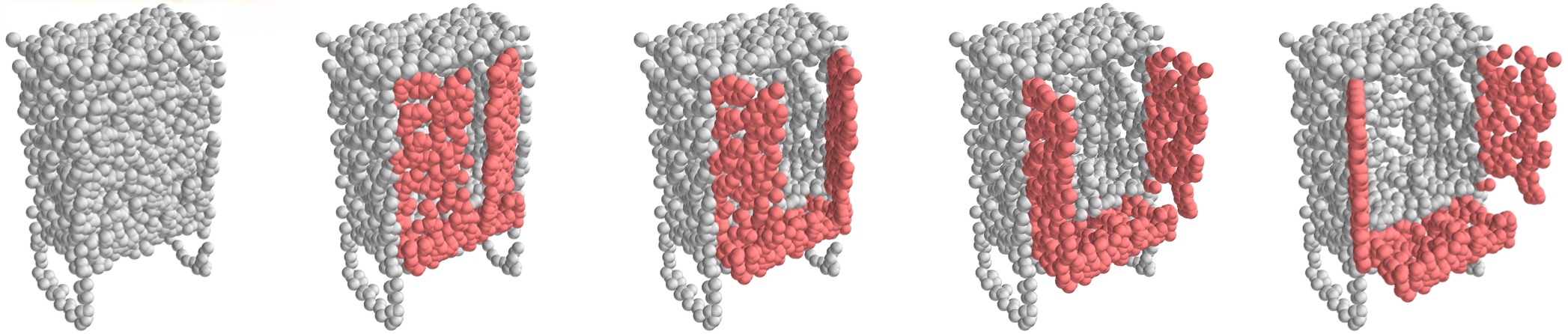
Point-wise
displacement



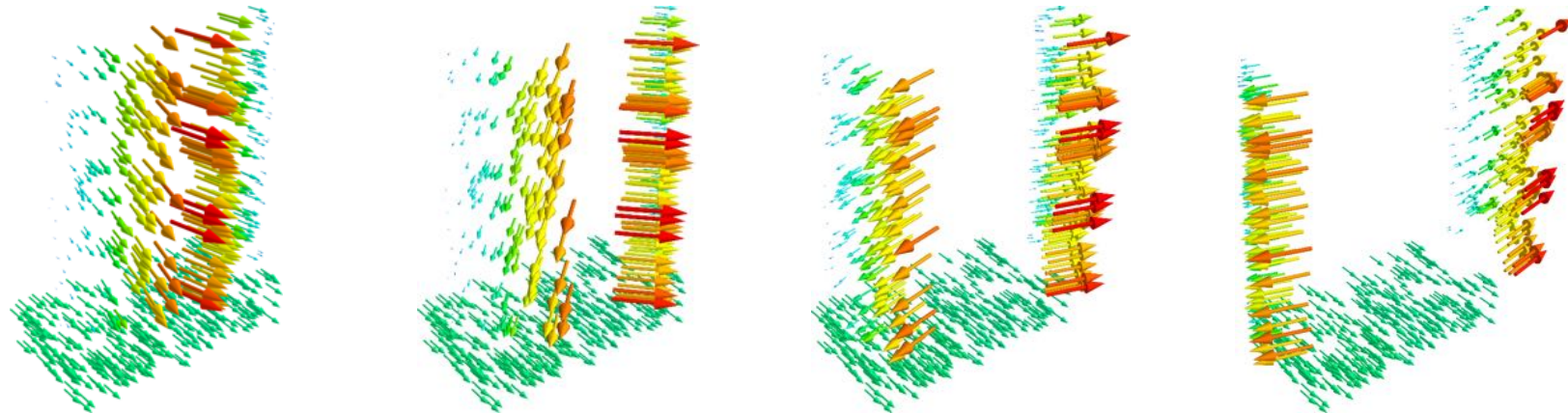
RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

Motion displacement



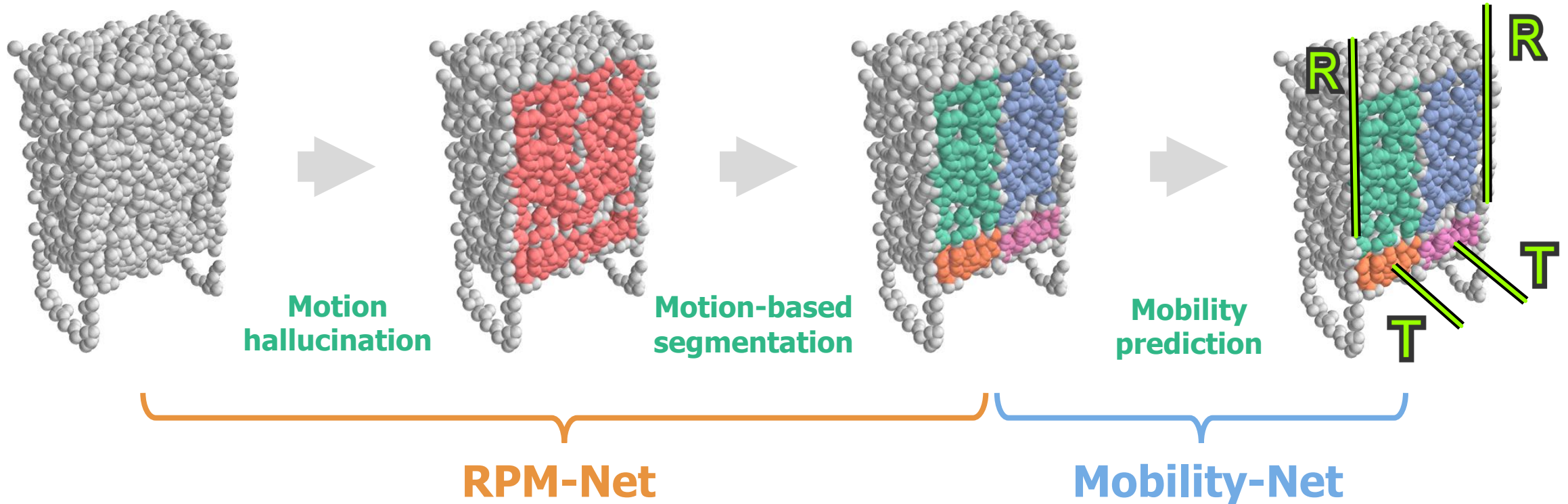
**Point-wise
displacement**



RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

Overview

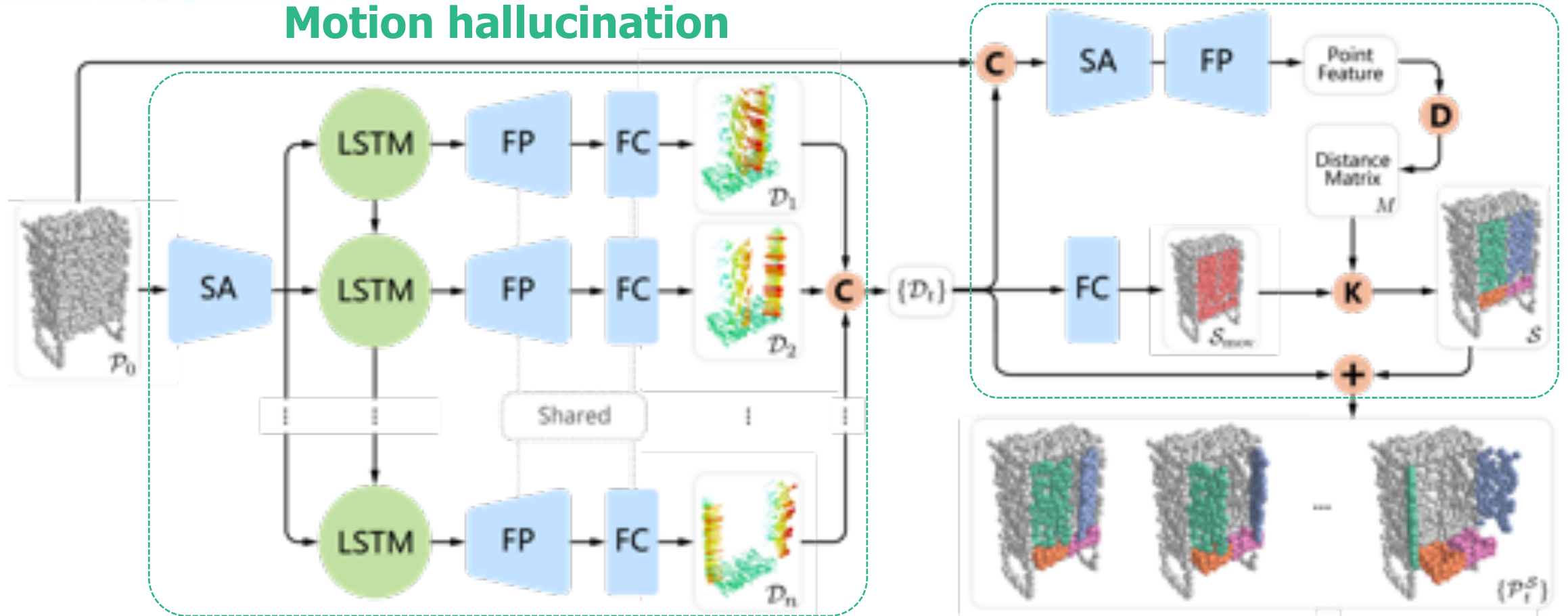


RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

Motion-based segmentation

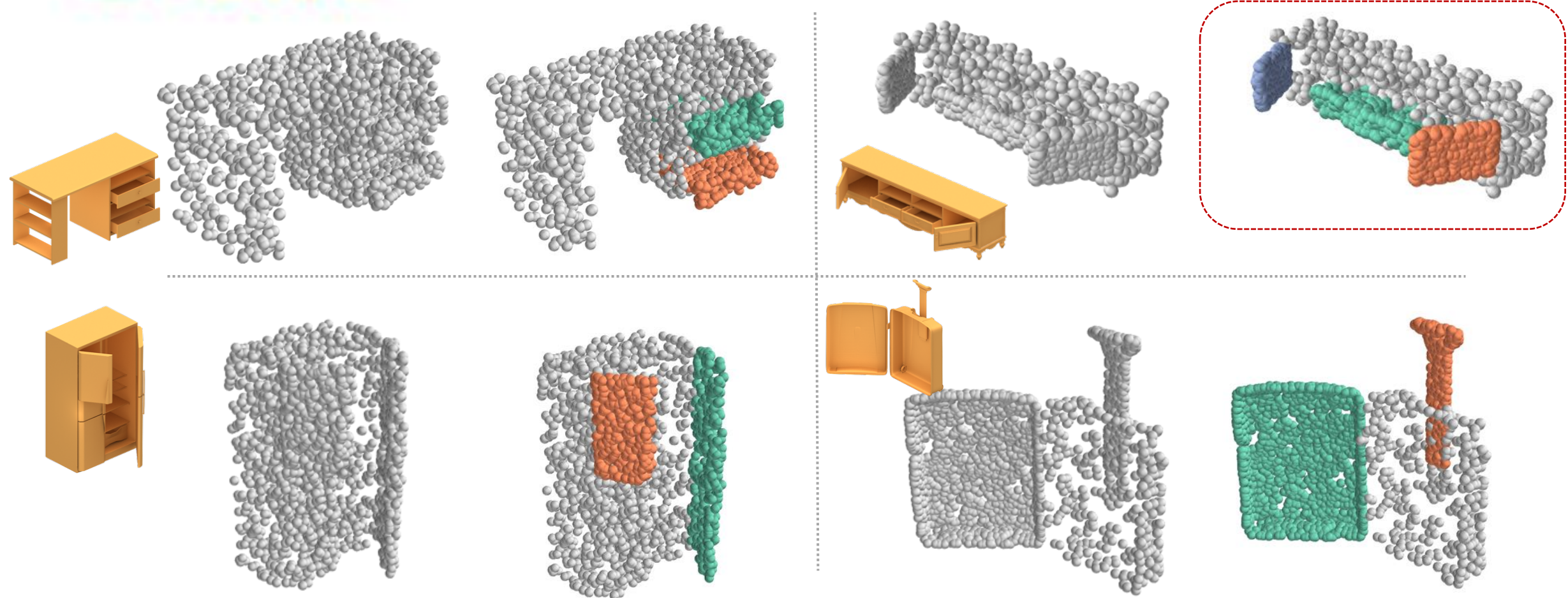
Motion hallucination



RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

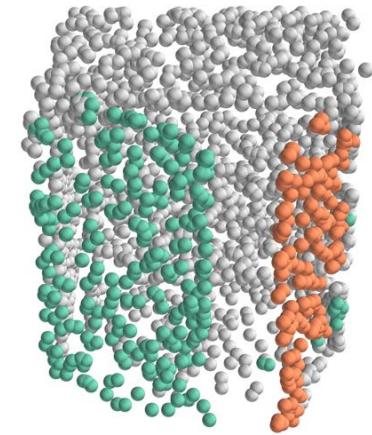
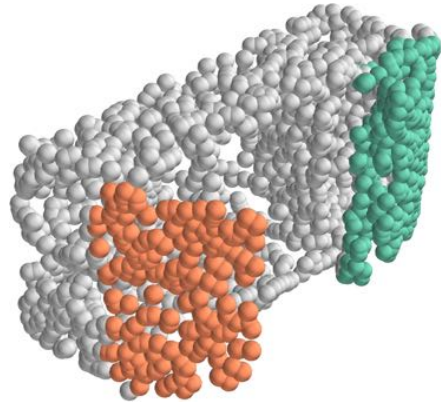
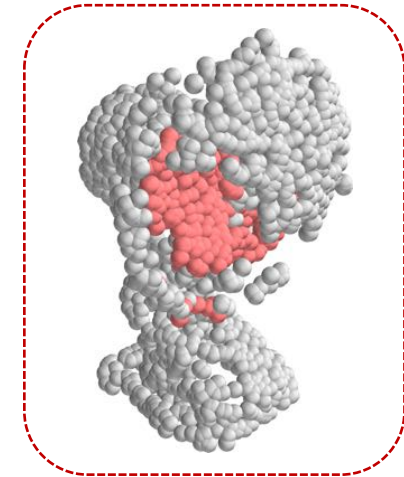
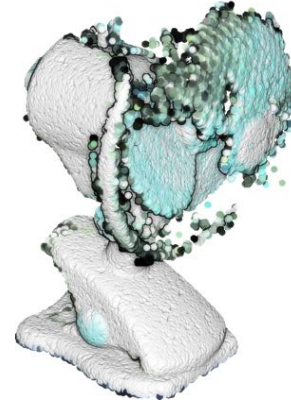
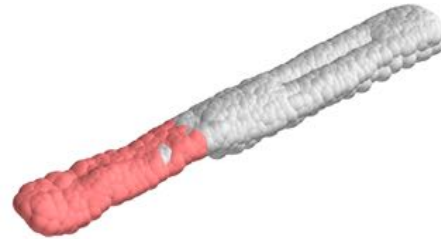
RPM-Net results



RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

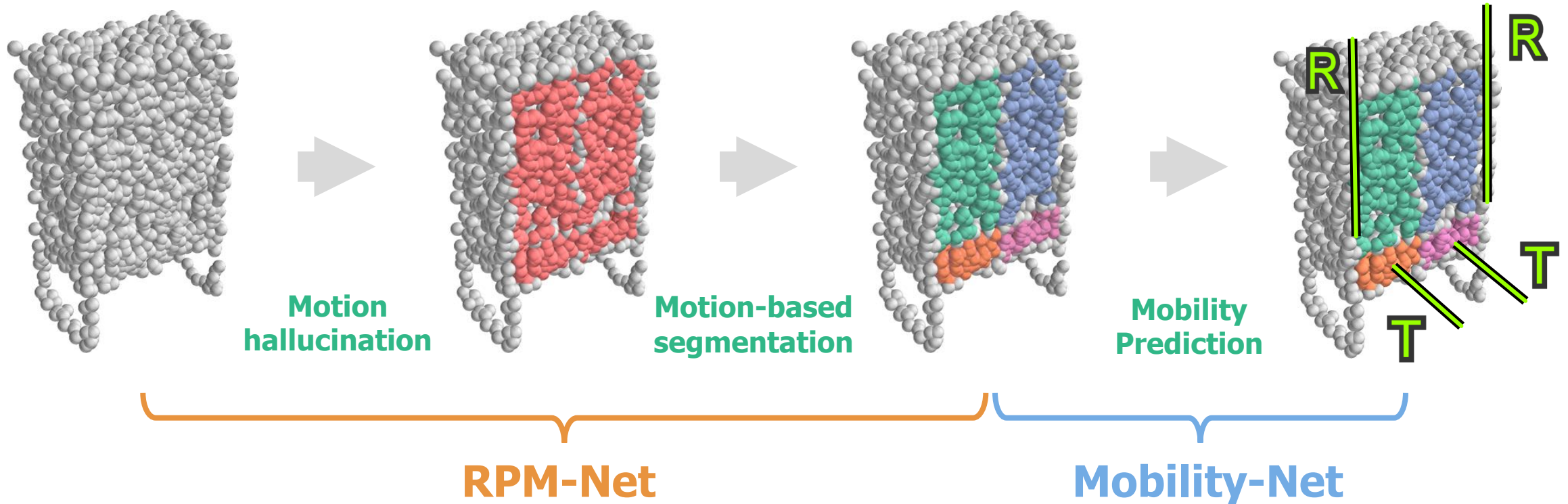
RPM-Net results



RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

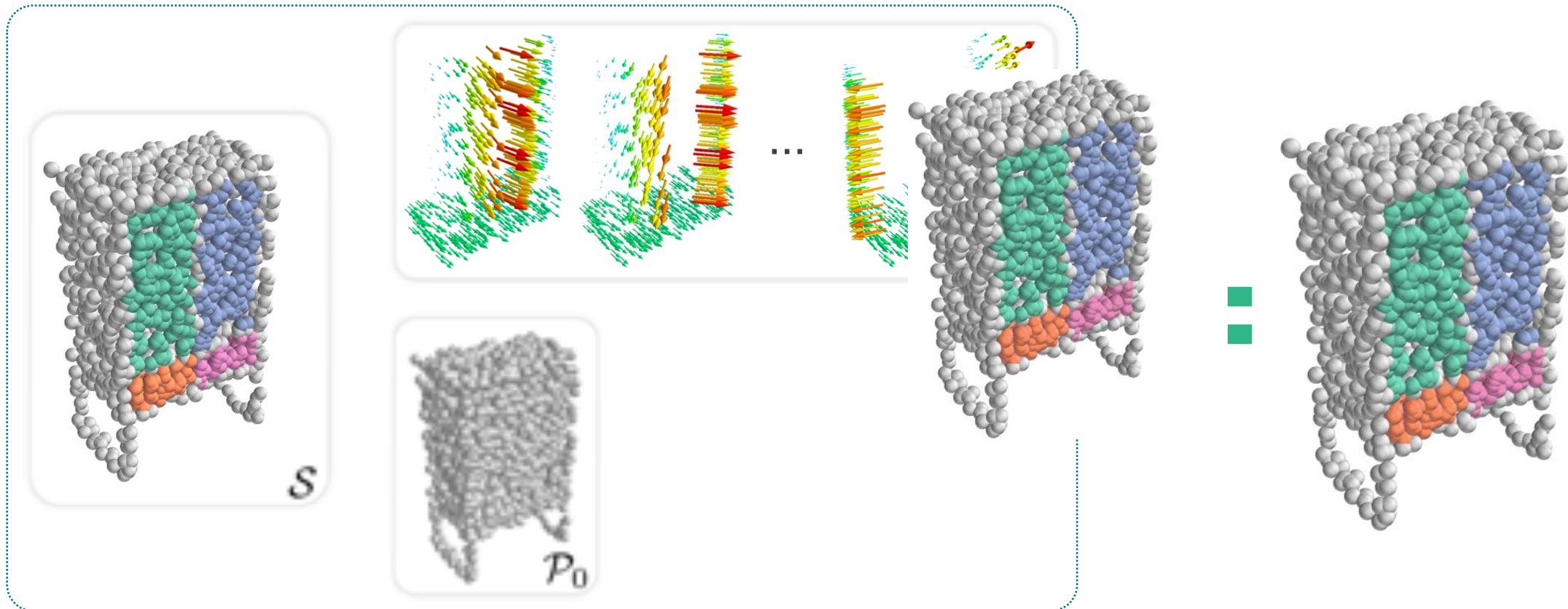
Overview



RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

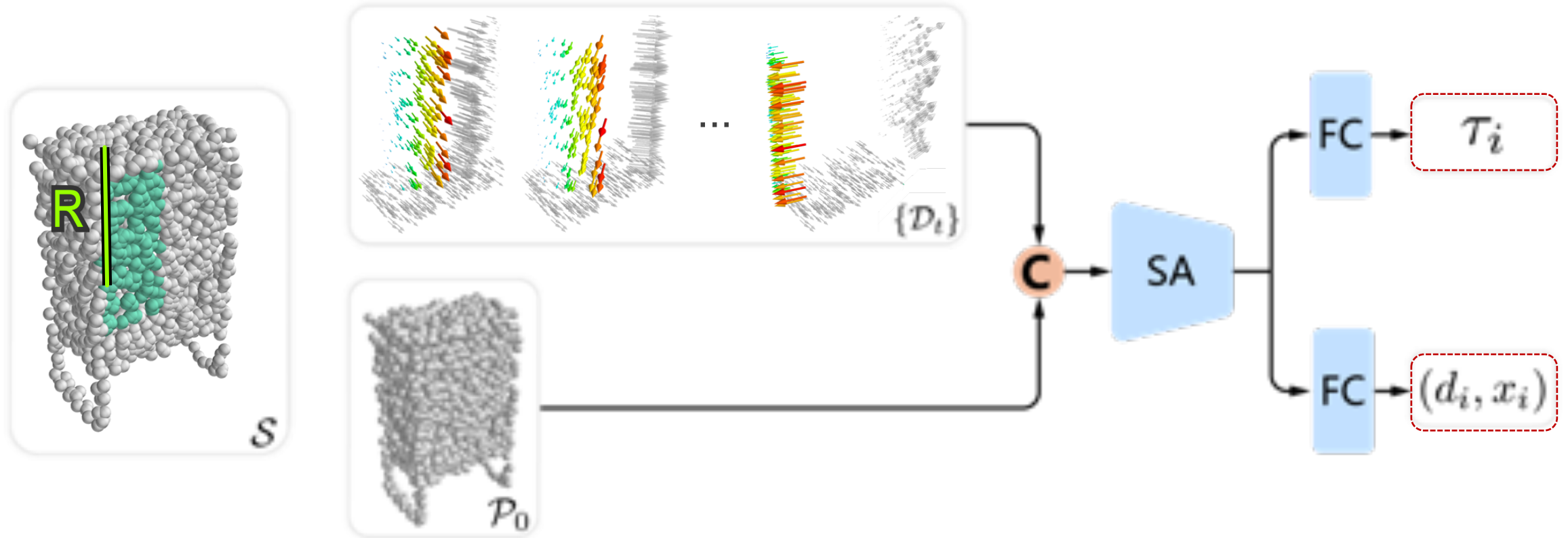
Mobility-Net: mobility prediction



RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

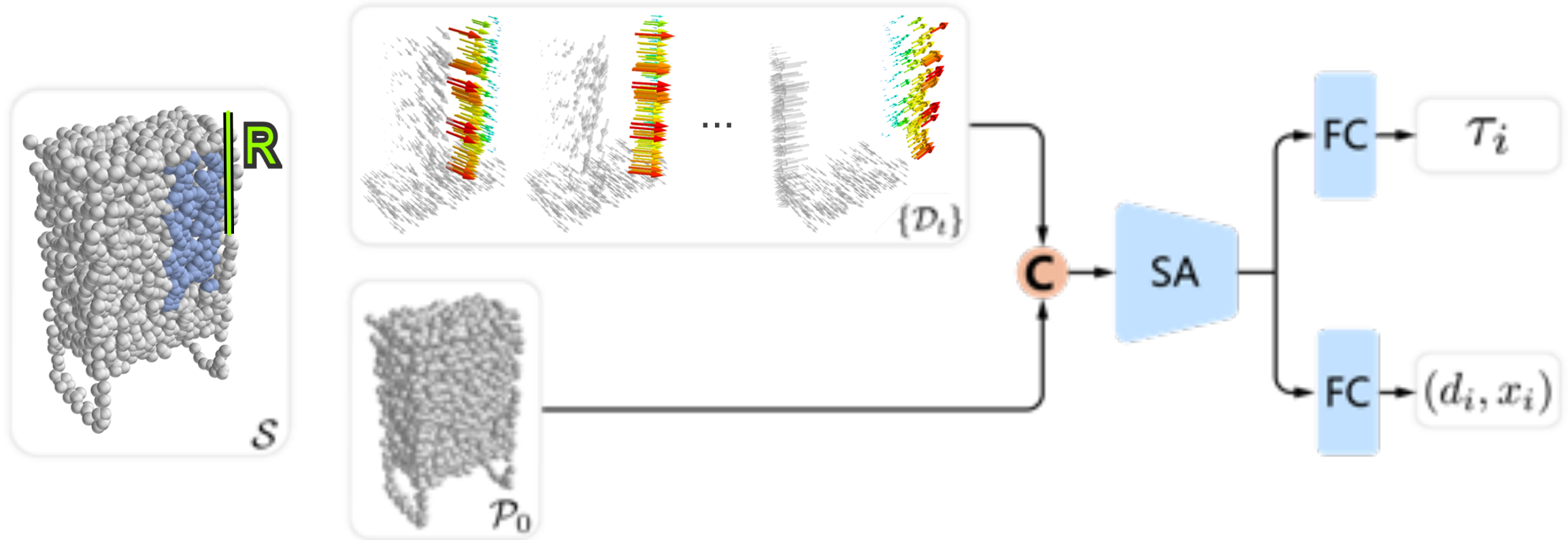
Mobility-Net: mobility prediction



RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

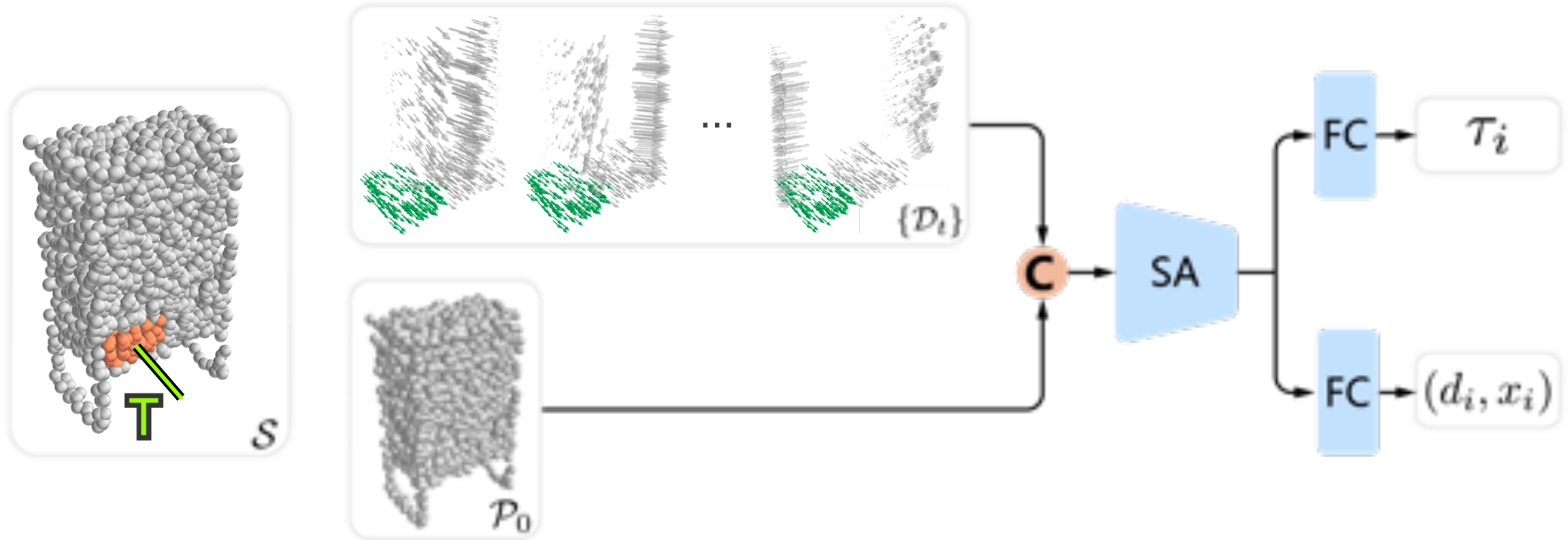
Mobility-Net: mobility prediction



RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

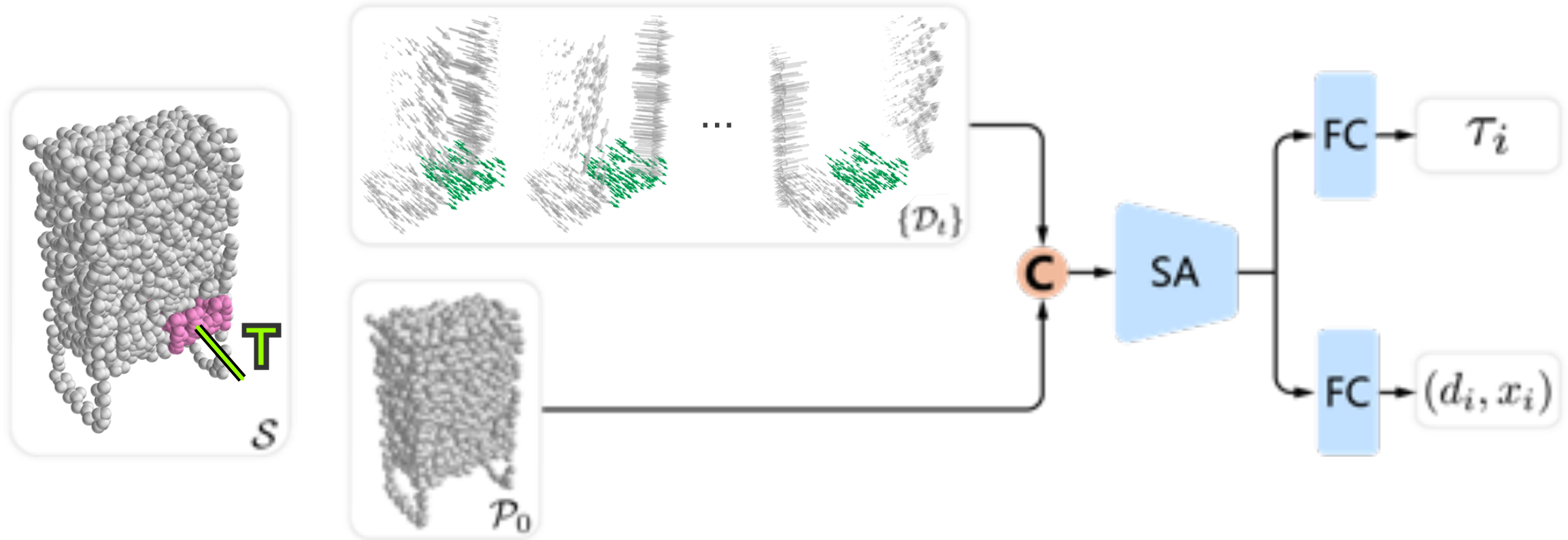
Mobility-Net: mobility prediction



RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

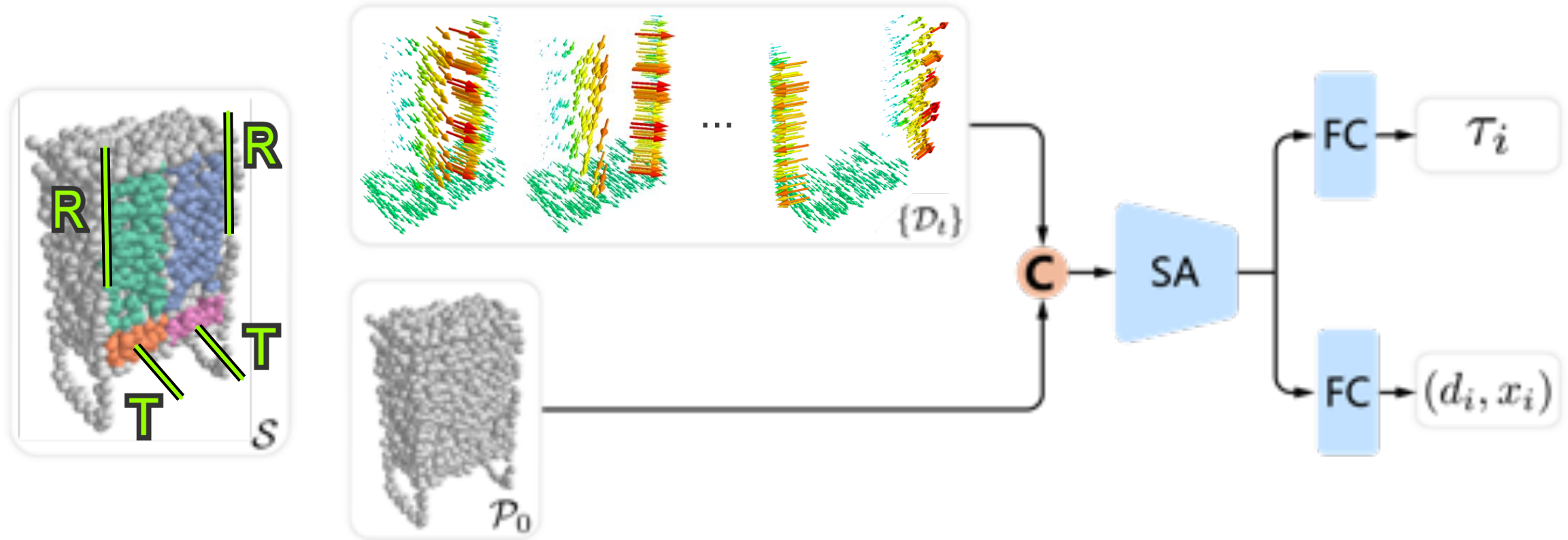
Mobility-Net: mobility prediction



RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

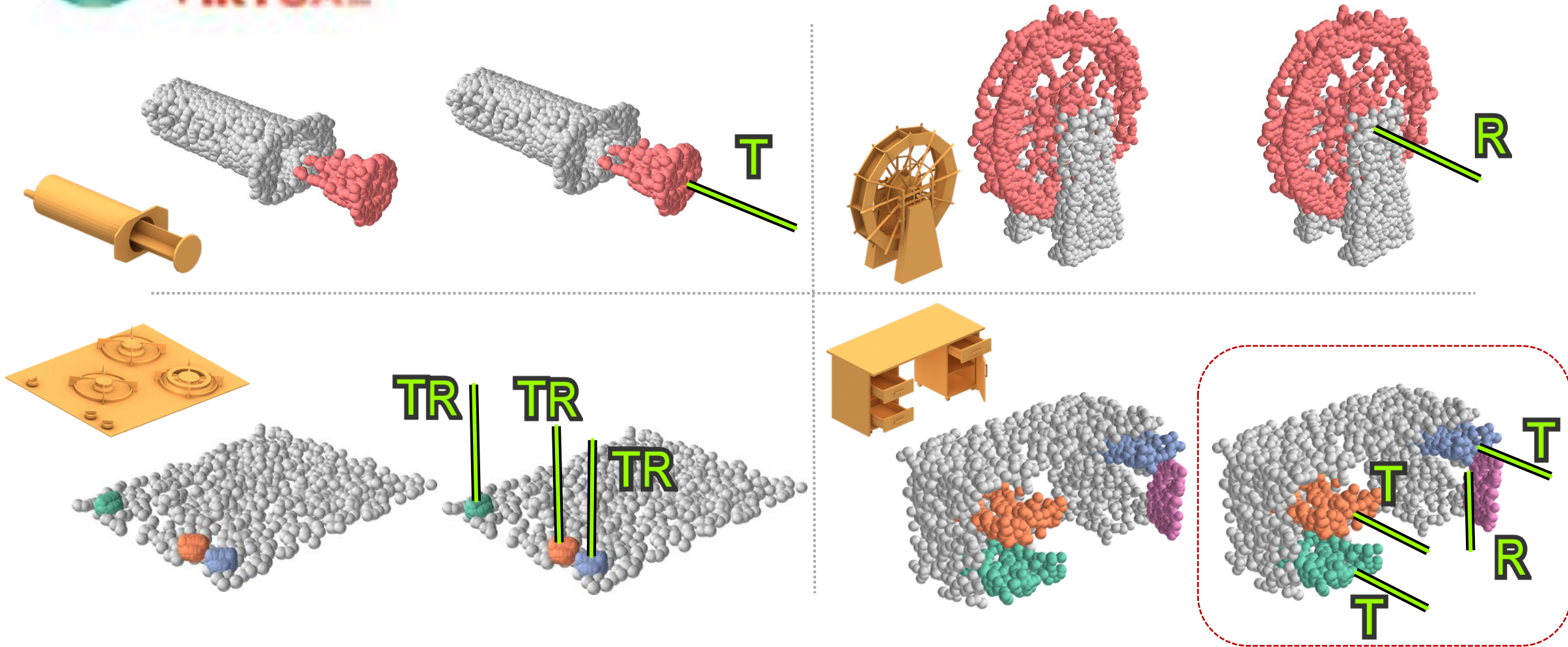
Mobility-Net: mobility prediction



RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

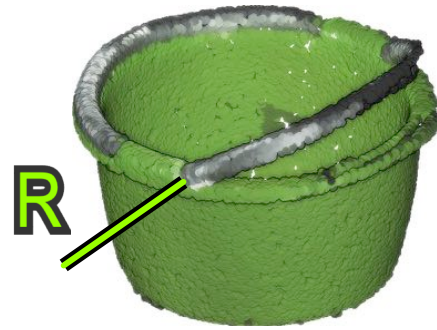
Mobility-Net results



RPM-Net: recurrent prediction of motion and parts from point cloud

[YHY*19]

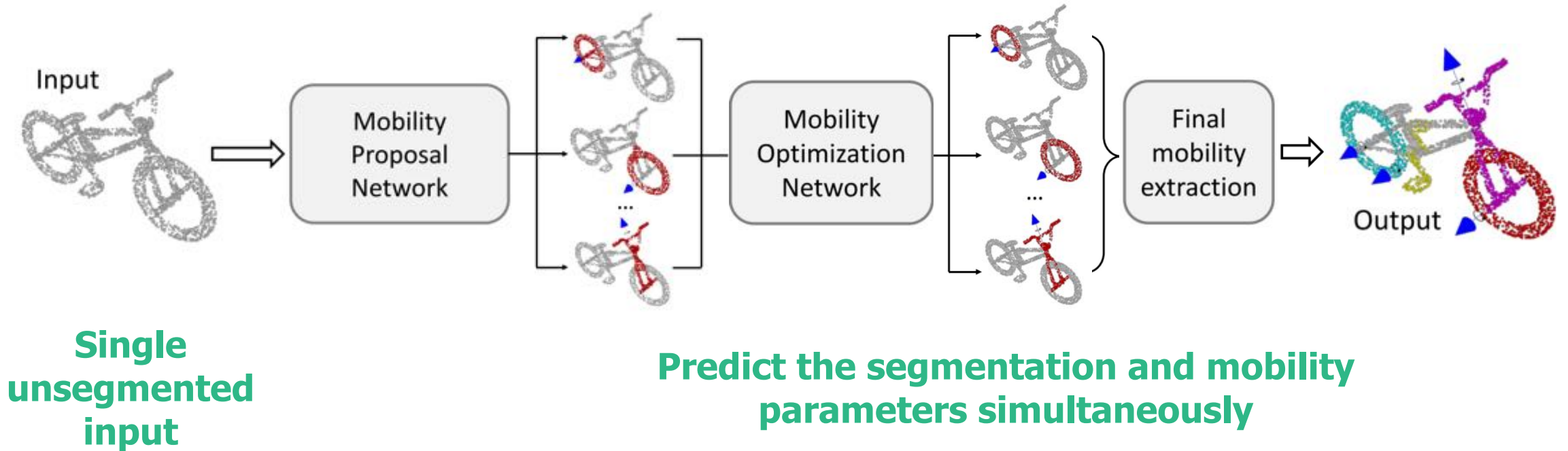
Mobility-Net results



RPM-Net: recurrent prediction of motion and parts from point cloud

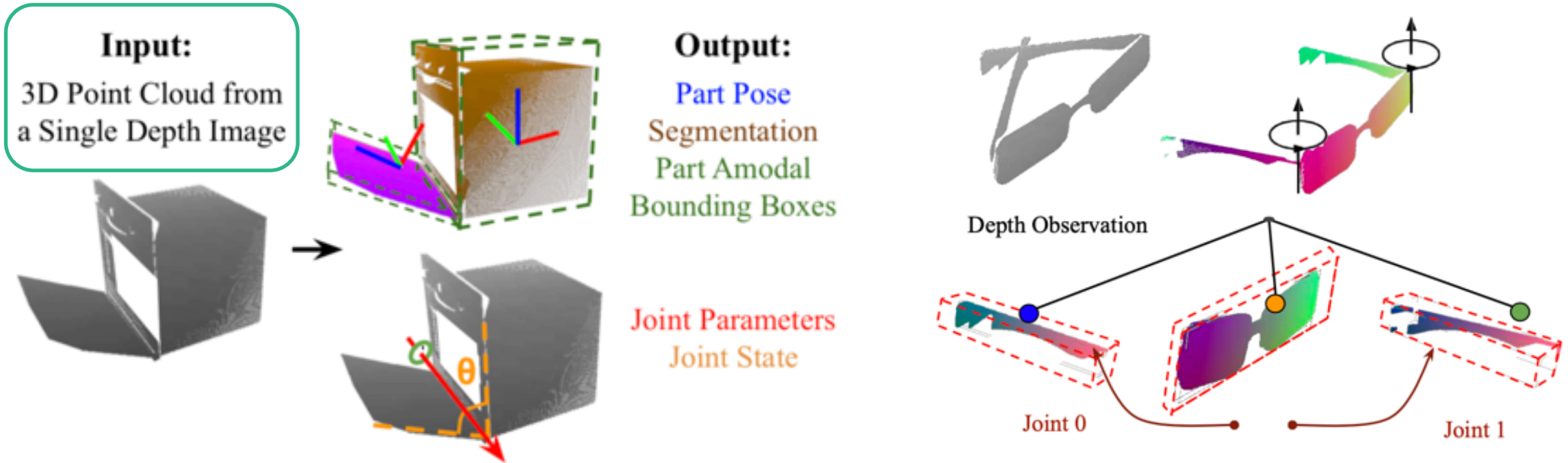
[YHY*19]

Part-level mobility prediction (Time-varying interaction)



Shape2Motion: joint analysis of motion parts and attributes from 3D shapes
[WZS*19]

Part-level mobility prediction (Time-varying interaction)



Category-level articulated object pose estimation
[LWY*20]

Geometry + interaction methods

Works	Representation of geometry or interactions				Additional classification criteria		
	Functional entity	Component / interacting entity	Dynamicity	Relations	Input	Approach	Model type
Geometry+interaction (GI)							
Hu et al. [HZK ⁺ 15]	object	stat-inter	stat	BR	pcl	handcrafted	discriminative
Hu et al. [HYKW ⁺ 16]	object	stat-inter	stat	BR	pcl	supervised	discriminative
Pirk et al. [PKH ⁺ 17]	object	dyn-inter	dyn	VF	mesh	handcrafted	discriminative
Myers et al. [MTFA15]	part	stat-inter	stat	SA	rgbd	supervised	discriminative
Kim et al. [KS14]	part	stat-inter	stat	SA	rgbd	supervised	discriminative
Laga et al. [LMS13]	part	stat-inter	stat	SA+SG	mesh	supervised	discriminative
Hu et al. [HLK ⁺ 17]	part	stat-inter	dyn	SA+BR	pcl	supervised	discriminative
Xiang et al. [XQM ⁺ 20]	part	stat-inter	dyn	SA	mesh	supervised	discriminative
Hu et al. [HYZ ⁺ 18]	object	stat-inter	stat	SA+BR	vol	supervised	generative
Yi et al. [YHL ⁺ 18]	part	stat-inter	dyn	SA	pcl	supervised	discriminative
Wang et al. [WZS ⁺ 19]	part	stat-inter	dyn	SA	pcl	supervised	discriminative
Yan et al. [YHY ⁺ 19]	part	stat-inter	dyn	SA	pcl	supervised	discriminative
Li et al. [LWY ⁺ 20]	part	stat-inter	dyn	SA	pcl	supervised	discriminative
Kokic et al. [KSHK17]	part	stat-inter	dyn	SA	pcl	supervised	generative
Li et al. [LSK20]	part	stat-inter	dyn	SA	pcl	supervised	generative



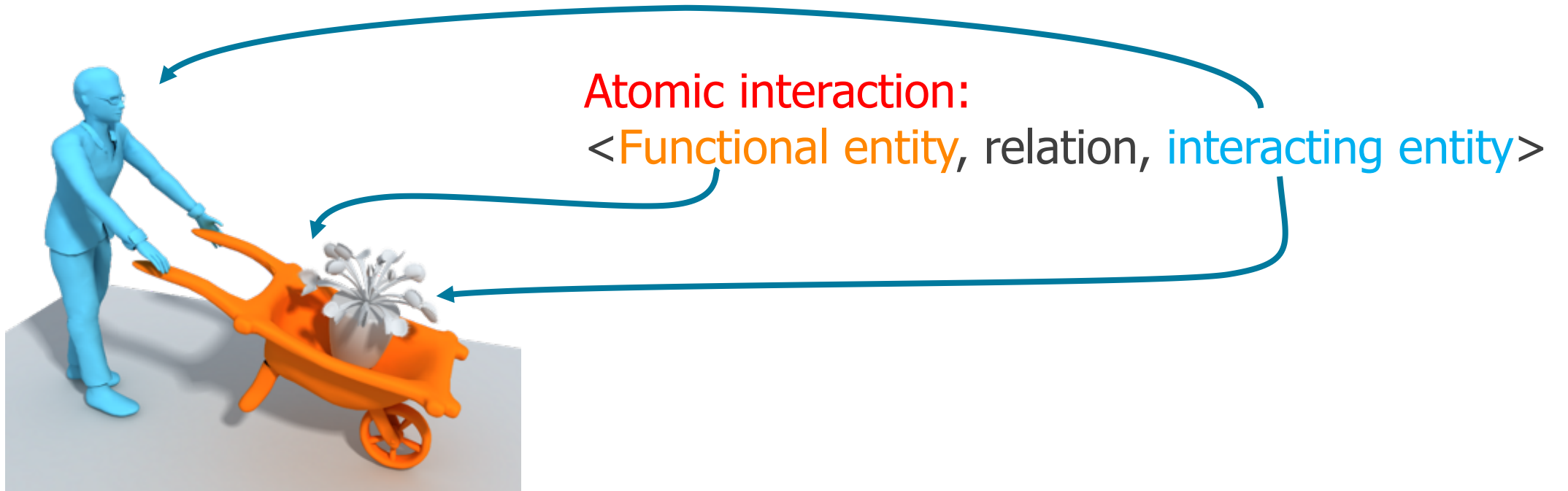
- Focus on **object** and **part** level functionalities
- Start with **handcrafted** functionality descriptors
- Recent learning-based methods for **prediction** and **generation**
- Both **atemporal** and **time-varying** interactions

Geometry + Agent



Our definition of functionality

Functionality = Geometry + **Interaction**



Geometry + agent methods

- Interaction with (humanoid) agent
- Can be special case of geometry + interaction methods
- Critical for human-centric functionality
- Recent interest in applications for fabrication, VR/AR

Much recent work

Works	Functional entity	Representation of geometry or interactions			Additional classification criteria		
		Component / interacting entity	Dynamicity	Relations	Input	Approach	Model type
Geometry+agent (GA)							
Grabner et al. [GGVG11]	scene	agent-inter	stat	HA	mesh	supervised	generative
Savva et al. [SCH ⁺ 14]	scene	agent-inter	stat	SA+HA	mesh	supervised	discriminative
Zhu et al. [ZJZ ⁺ 16]	scene	agent-inter	stat	SA	mesh	supervised	generative
Jiang et al. [JKS13]	multi-object	agent-inter	stat	SA	rgbd	supervised	discriminative
Wang et al. [WLY17]	multi-object	agent-inter	stat	SA+HA	mesh	supervised	discriminative
Fisher et al. [FSL ⁺ 15]	multi-object	agent-inter	stat	SA+HA	mesh	supervised	generative
Savva et al. [SCH ⁺ 16]	multi-object	agent-inter	stat	SA+HA	mesh	supervised	generative
Ma et al. [MLZ ⁺ 16]	multi-object	agent-inter	dyn	SA+HA	mesh	unsupervised	generative
Zheng et al. [ZLDM16]	object	agent-inter	stat	SA	mesh	handcrafted	generative
Kim et al. [KCGF14]	object	agent-inter	stat	SA	mesh	supervised	generative
Bar-Aviv & Rivlin [BAR06]	object	agent-inter	stat	SA+HA	mesh	handcrafted	discriminative
Zhu et al. [ZZCZ15]	object	agent-inter	dyn	SA+HA	rgbd	supervised	discriminative
Zhao et al. [ZCK17]	object	agent-inter	dyn	SA+HA	mesh	handcrafted	discriminative
Lee et al. [LCL06]	object	agent-inter	dyn	SA	mesh	supervised	generative
Li et al. [LLK ⁺ 19]	scene	agent-inter	stat	SA+HA	rgbd	supervised	generative
Zhang et al. [ZHN ⁺ 20]	scene	agent-inter	stat	SA+HA	rgbd	supervised	generative
Mao et al. [MZX ⁺ 19]	object	agent-inter	stat	SA	mesh	supervised	generative
Fu et al. [FFY ⁺ 20]	scene	agent-inter	stat	SA+HA	mesh	supervised	discriminative
Monsrpart et al. [MGC ⁺ 19]	scene	agent-inter	stat	SA	rgbd	supervised	generative
Raiz et al. [RMC19]	scene	agent-inter	stat	SA+BR	mesh	supervised	generative
Starke et al. [SZKS19]	object	agent-inter	dyn	SA	vol	supervised	generative
Akizuki et al. [AA18]	object	agent-inter	dyn	SA+HA	rgbd	supervised	discriminative

Axes of variation

- Representation focus: agent-centric or functional entity-centric
- Functional entity level
- Relation type: time-varying or not
- Generation: agent(s) \leftrightarrow scene
- Discrimination: scene quality metrics and object understanding

Axes of variation

Works	Functional entity	Representation of geometry or interactions			Additional classification criteria		
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Akizuki et al. [AA18]	object	agent-inter	dyn	SA+HA	rgbd	supervised	discriminative

Representation focus

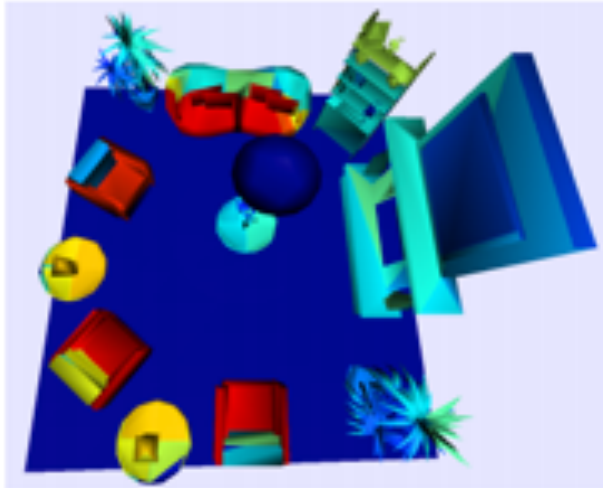
Geometry-centric



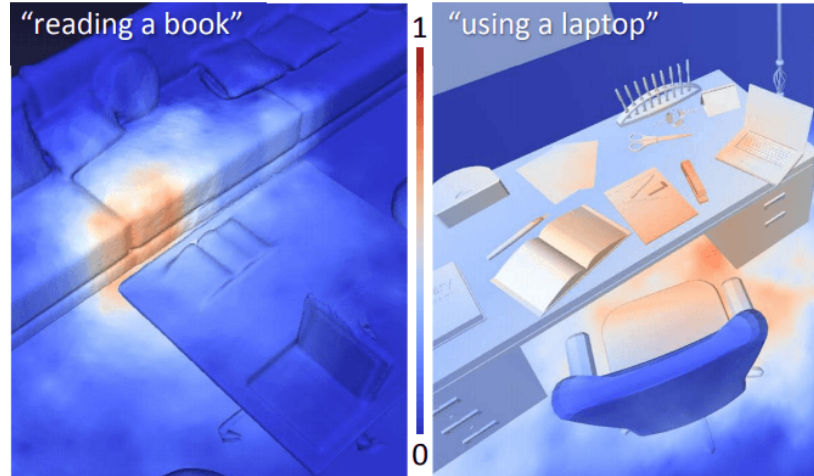
Agent-centric



Geometry-centric representations



Sittability prediction
[GGVG11]



Action maps
[SCH*14]

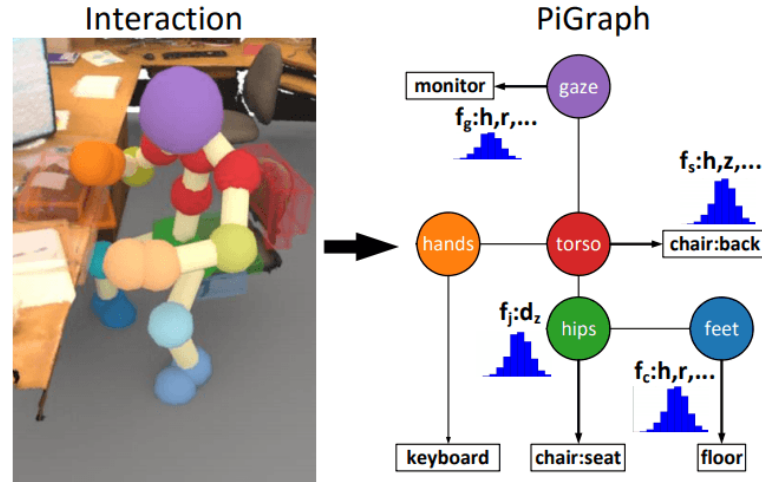


Object interactions
[FSL*15]

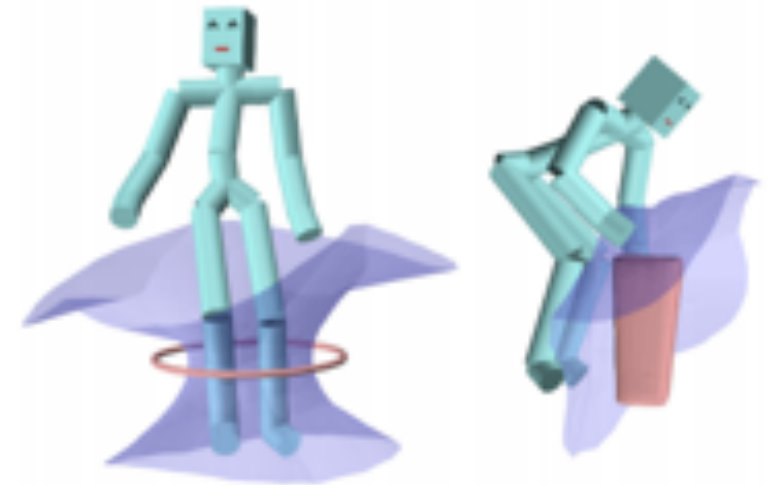
Agent-centric representations



Shape2pose
[KCGF14]



PiGraphs
[SCH*16]



Character-object IBS
[ZCK17]

Functional entity level



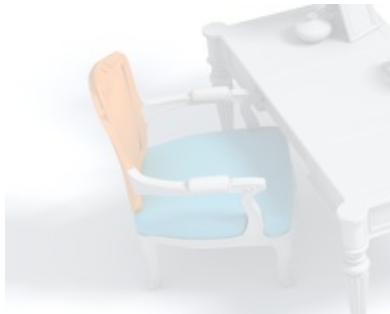
Scene



Multi-object



Object



Multi-part

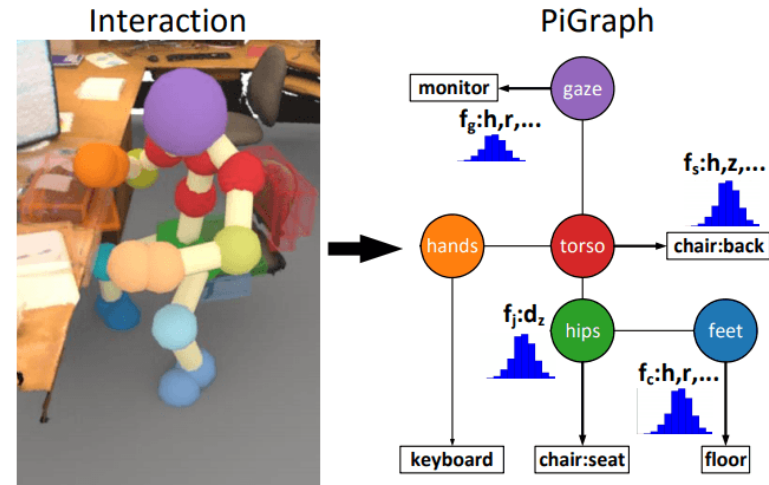


Part

Functional entity level: multi-object



Object interactions
[FSL*15]

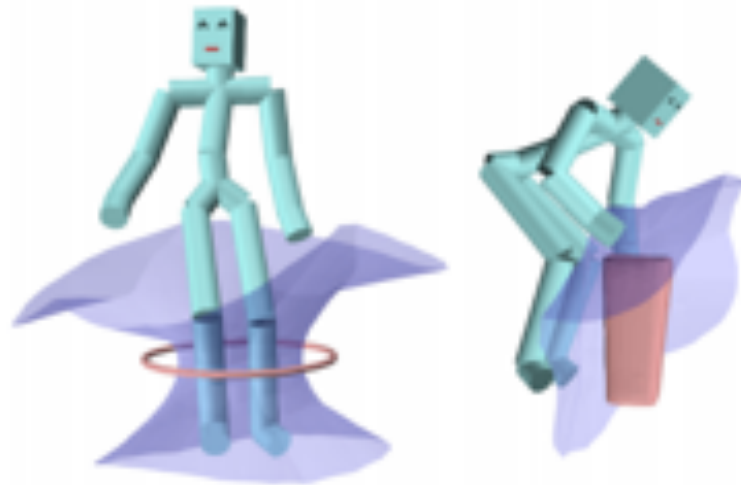


PiGraphs
[SCH*16]

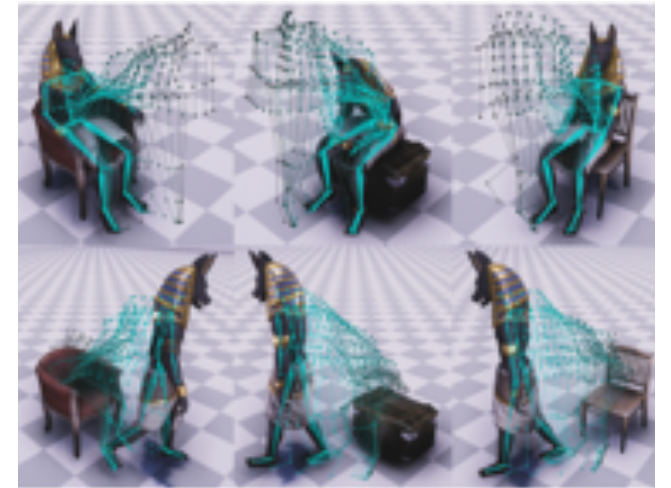
Functional entity level: object



Shape2pose
[KCGF14]



Character-object IBS
[ZCK17]

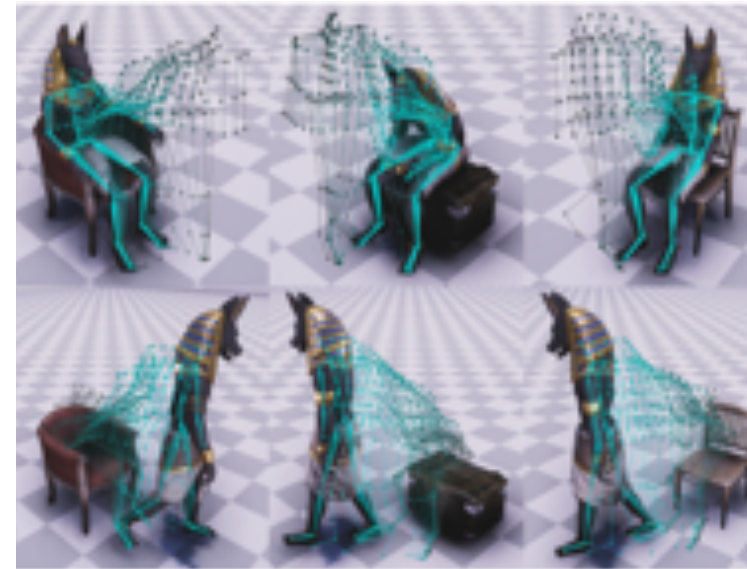
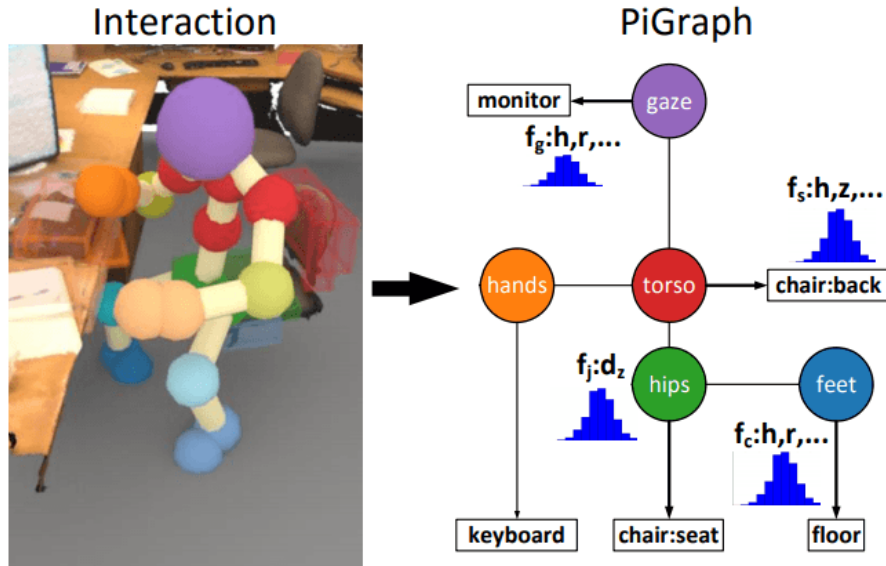


Character interactions
[SZKS19]

Relation type

Atemporal

Time-varying



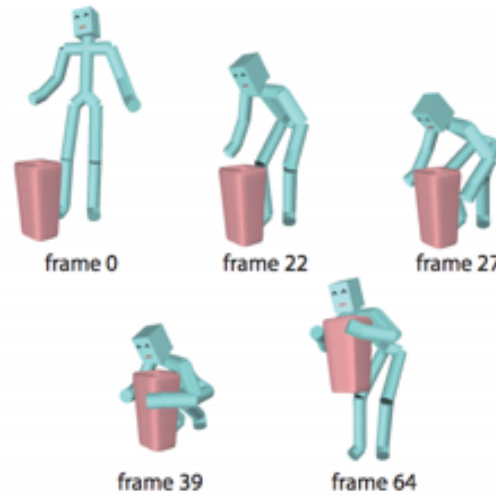
[SCH*16]

[SZKS19]

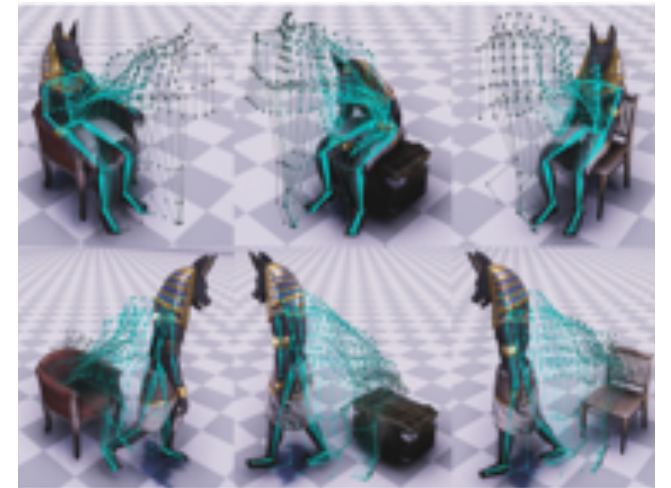
Relation type: time-varying



Motion patches
[LCL06]



Character-object IBS
[ZCK17]

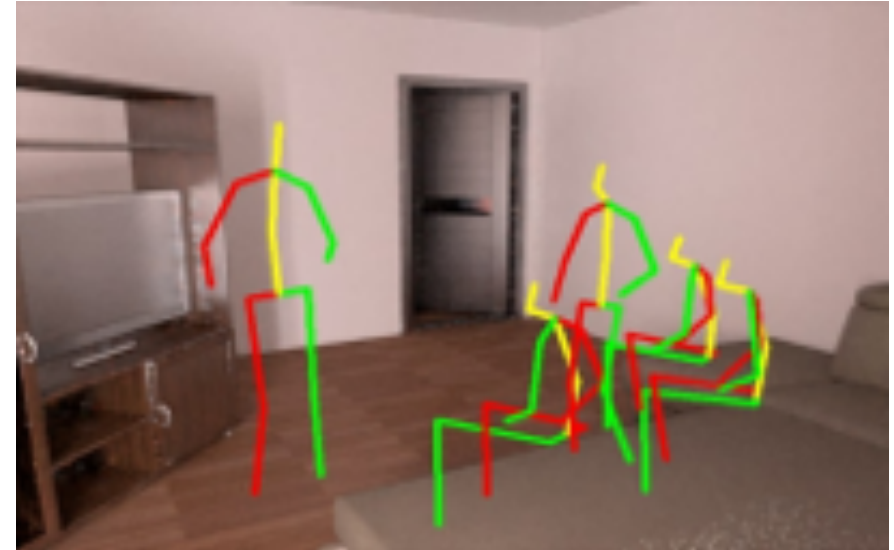


Character interactions
[SZKS19]

Generation: scene \rightarrow agent(s)

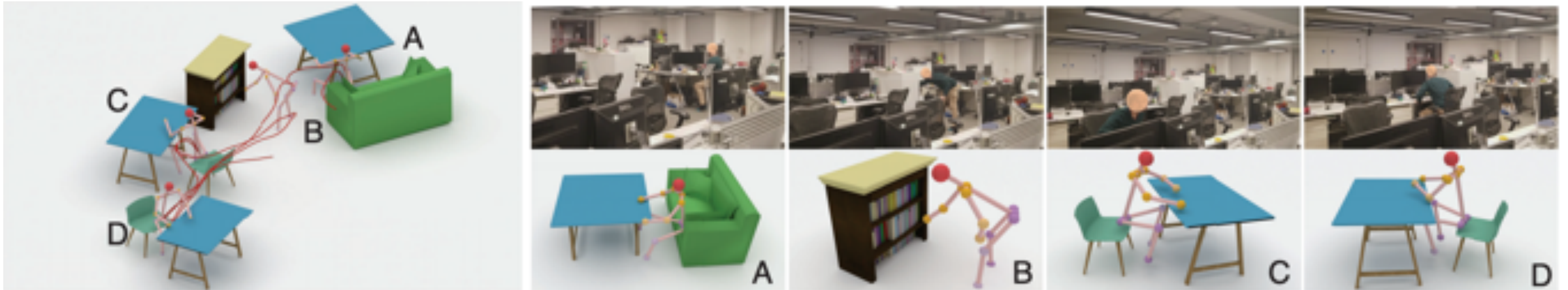


Generating 3D people
[ZHN*20]



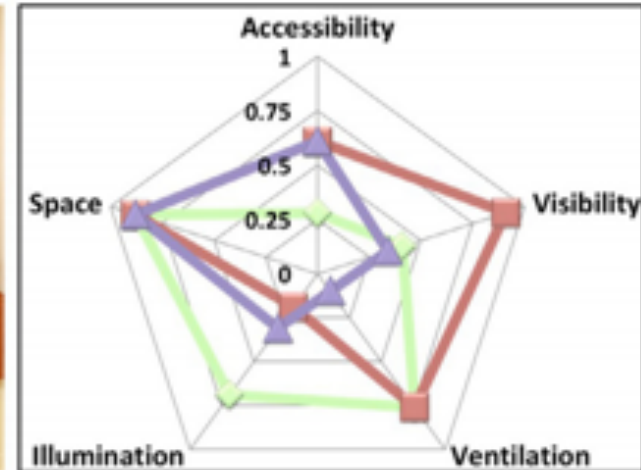
Putting humans in a scene
[LLK*19]

Generation: agent → scene



iMapper
[MGC*19]

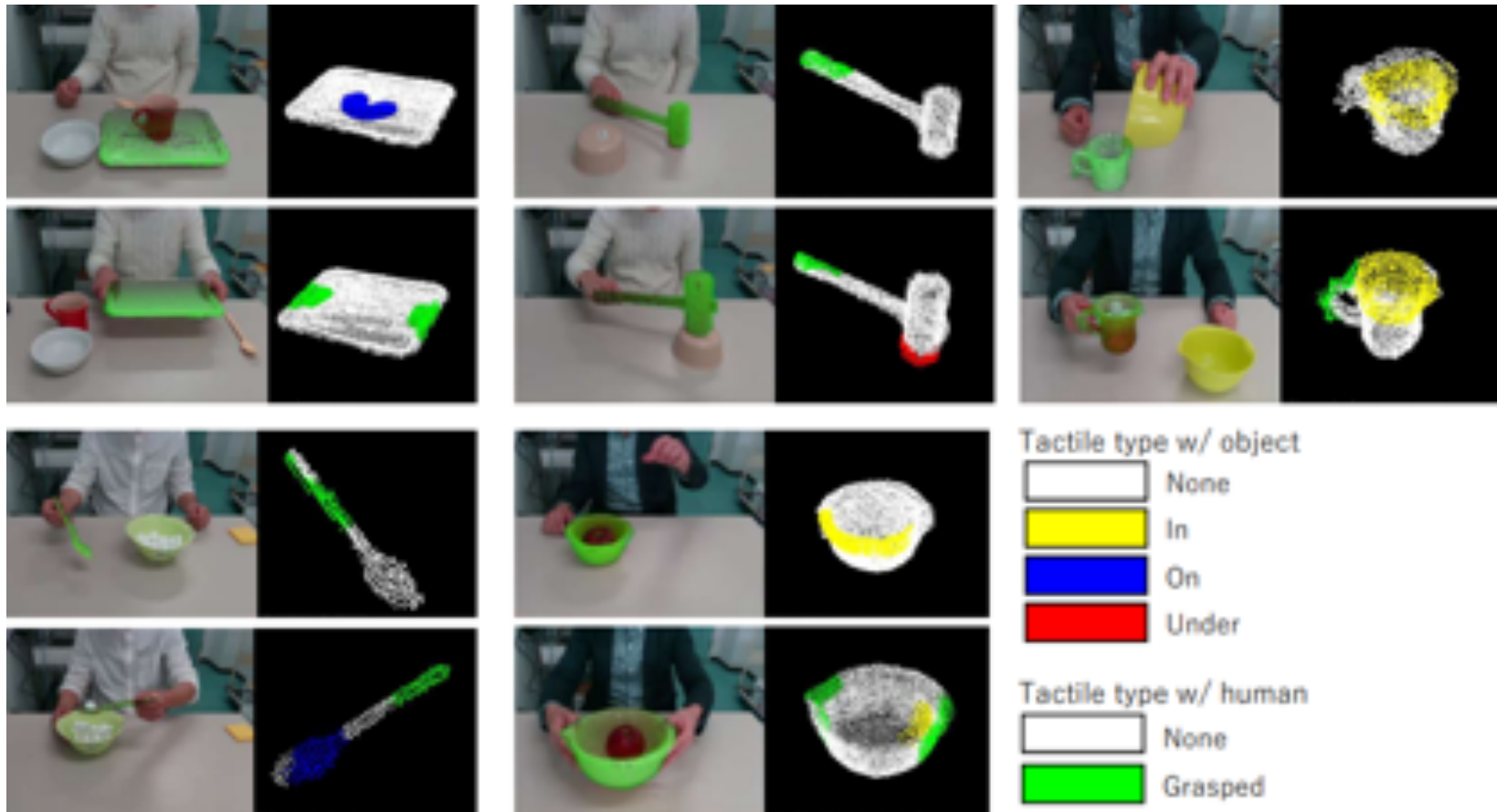
Discrimination: scene quality metrics



Human-centric scene assessment metrics

[FFY*20]

Discrimination: object understanding



Tool use classification

[AA18]

Future directions for geometry + agent methods

- Finer scale actions
- Social actions and hierarchical actions
- Time-varying relations in time-varying scenes
- Connections with robotics, computer vision, embodied AI

Summary: geometry + agent methods

Virtual and augmented reality



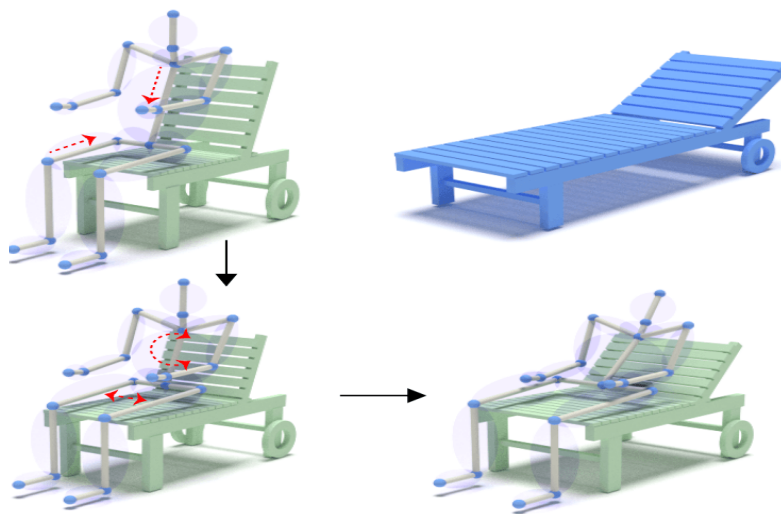
[image source:
<https://commons.wikimedia.org/wiki/File:Augmented-reality.jpg>]

Fabrication



[image source:
https://commons.wikimedia.org/wiki/File:GENERATIC-collection-by-Emmanuel_Touraine-for-VENTURY-027.jpg]

Applications

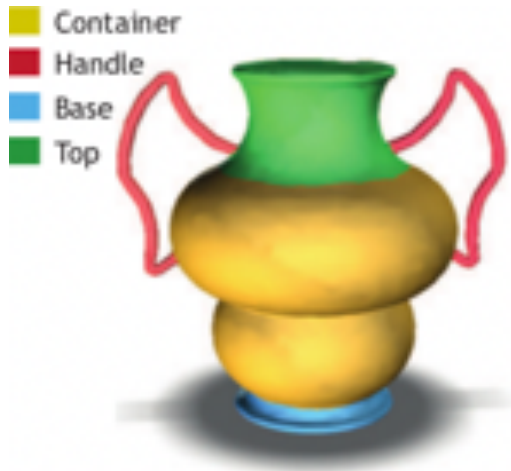


Application domains

- Classification, segmentation, and labeling
- Retrieval
- Synthesis
- Modeling and editing
- Visualization and fabrication
- Robotics and AI

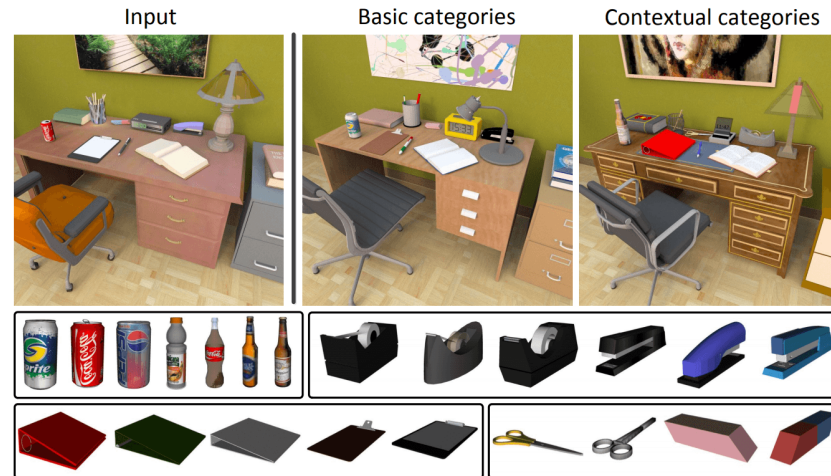
Classification, segmentation, labeling

Part classification



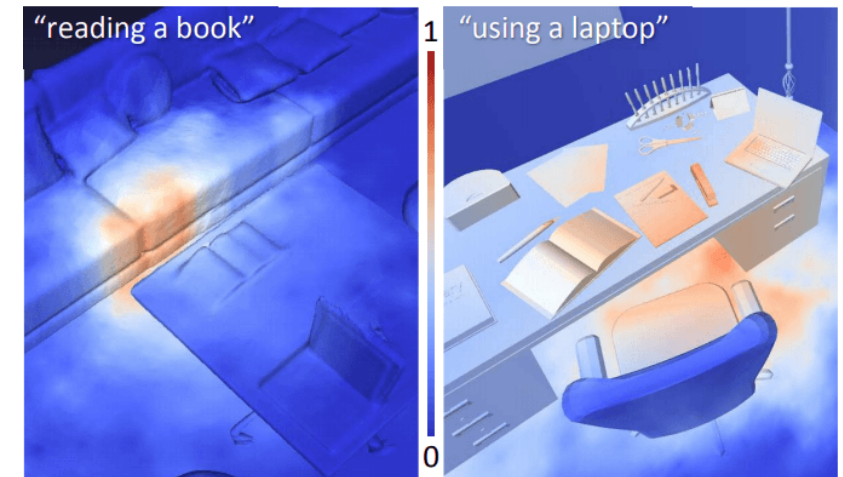
[LMS13]

Object classification



[FRS*12]

Scene classification



[SCH*14]

Retrieval

Part retrieval



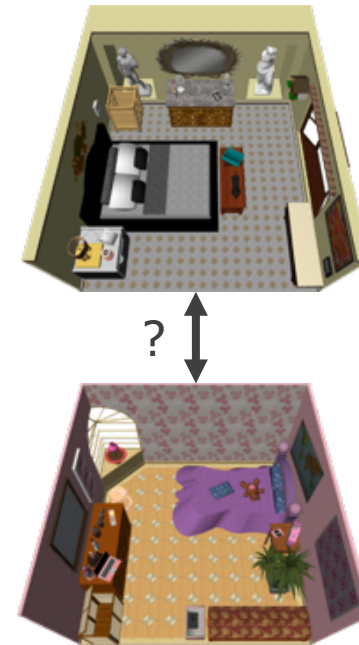
[GMW16]

Object-in-scene retrieval



[HZvK*15]

Scene retrieval



$$\begin{pmatrix} \int M_{sit} \\ \int M_{read} \\ \int M_{walk} \\ \int M_{sleep} \\ \vdots \end{pmatrix} \in \mathbb{R}^k$$

[SCH*14]

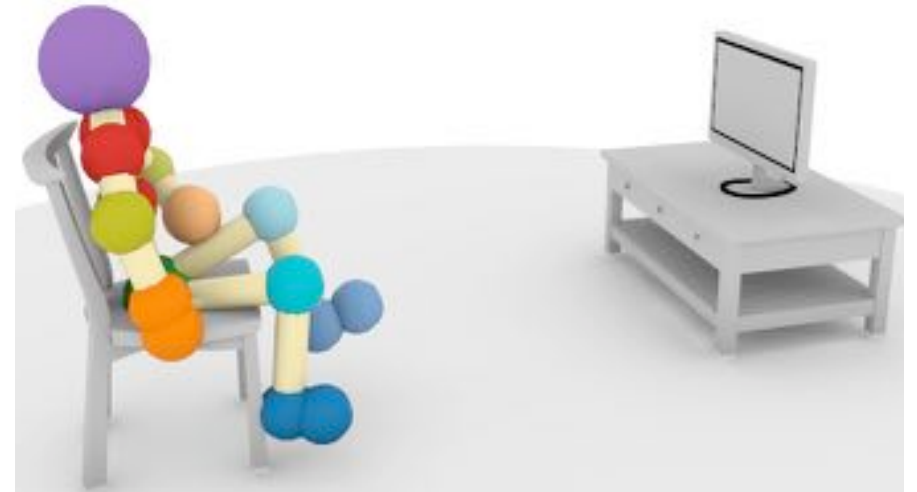
Synthesis

3D scene synthesis



[FSL*15]

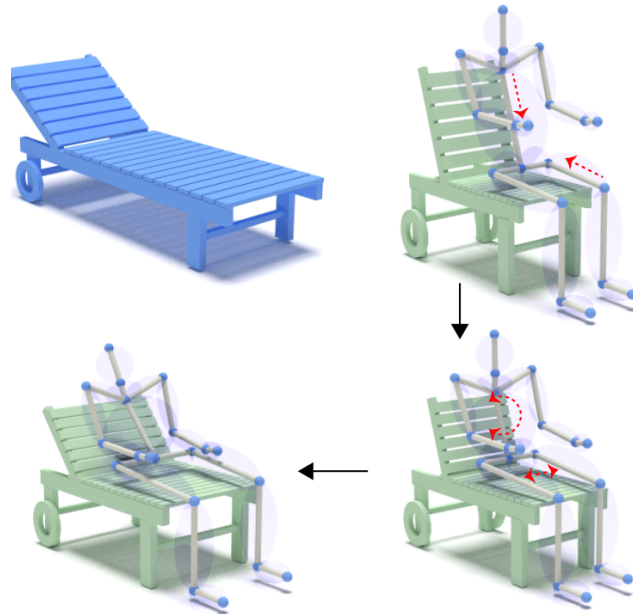
Human interaction synthesis



[SCH*16]

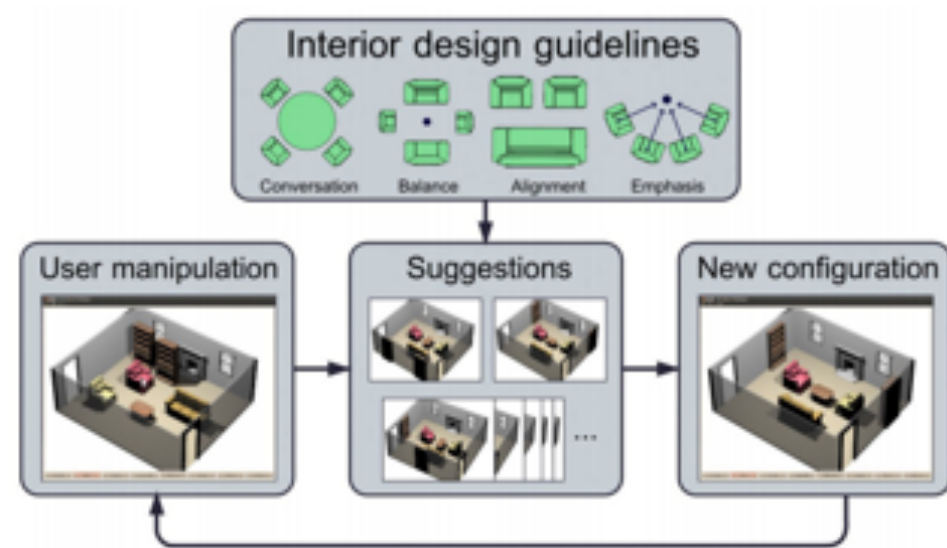
Modeling and editing

Object modeling



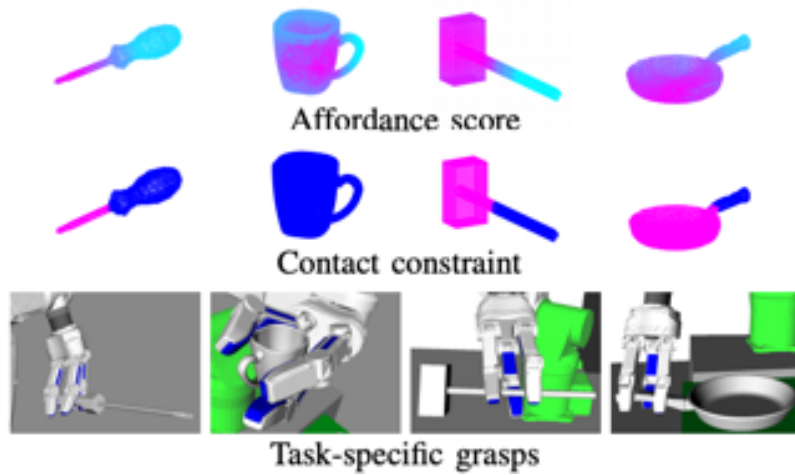
[ZLDM16]

Scene editing



[MSL*11]

Affordance detection for grasping



[KSHK17]

SAPIEN: interactive 3D simulation



[XQM*20]

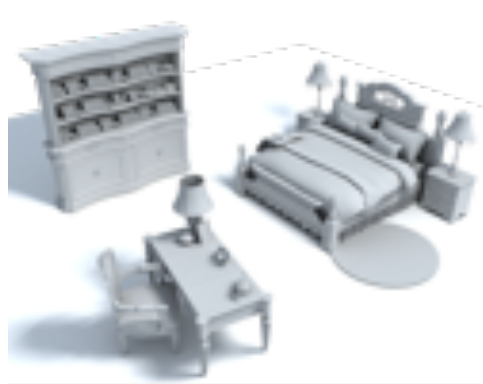
Applications: summary

- Many application domains
- Functionality critical for both analysis and synthesis tasks
- Despite much recent work, open research questions abound

Future Directions



Different levels of functional entities



(a) Scene



(b) Object-union



(c) Object



(d) Part-union

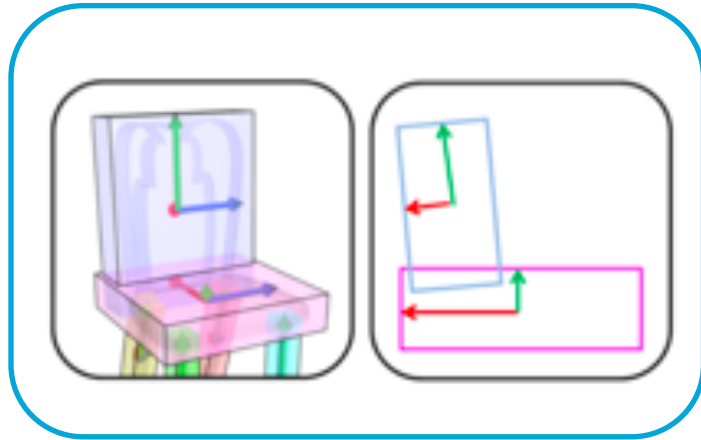


(e) Part

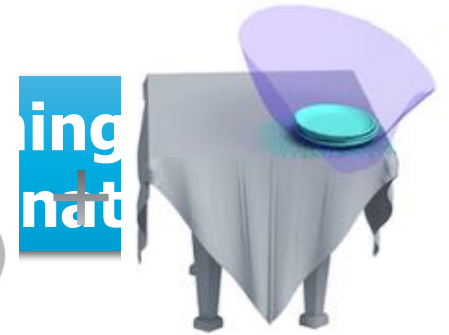
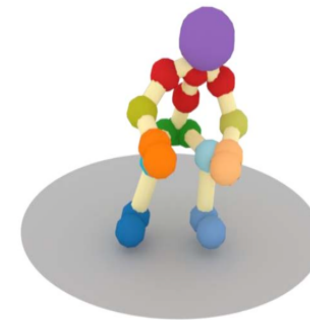
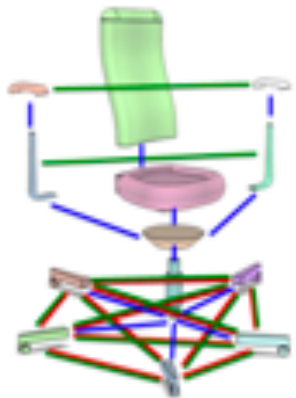
Multi-level treatment?

Hierarchical representation?

Interaction representation



More informative representation?



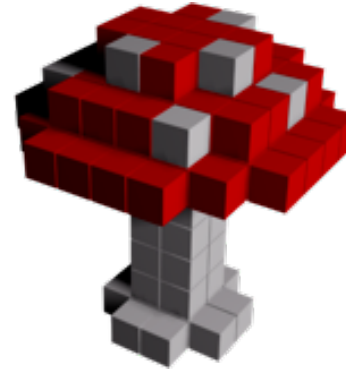
Input data type



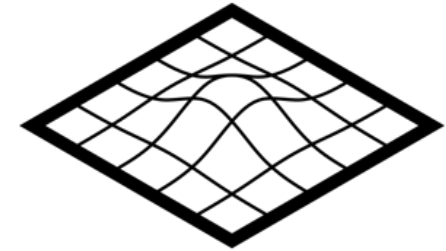
Mesh [HLK*17]



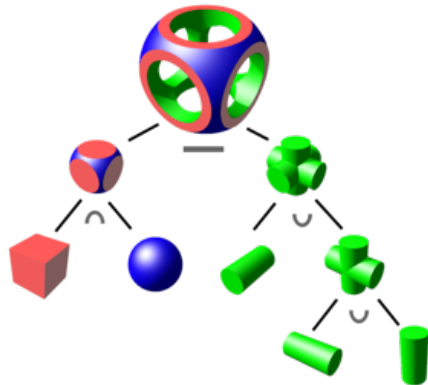
Point cloud [ZWK14]



Volumetric data



Parametric surface



Constructive solid geometry



Raw scan [FSL*15]

incomplete / partially regions

presence
of noise

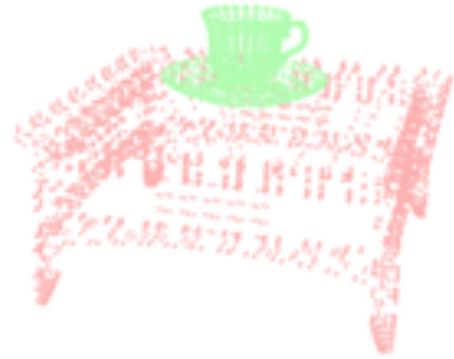
imperfect
registration

...

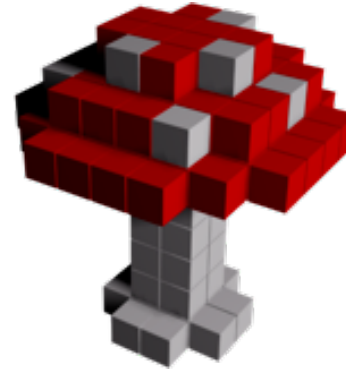
Input data type



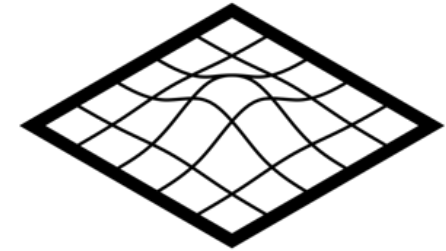
Mesh [HLK*17]



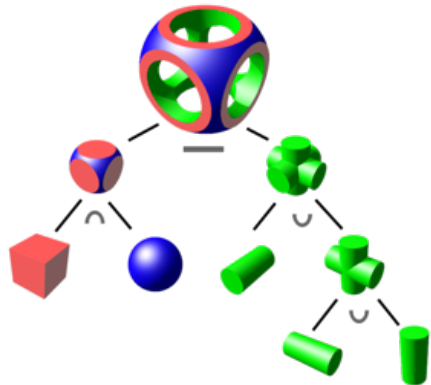
Point cloud [ZWK14]



Volumetric data



Parametric surface



Constructive solid geometry

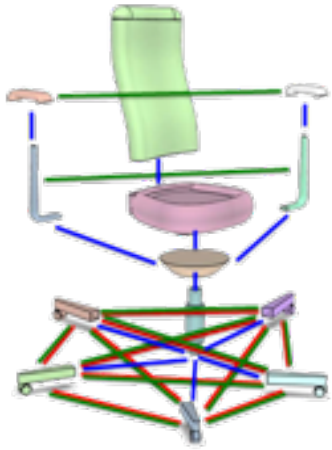


Raw scan [FSL*15]



RGB image
[ZFFF14]

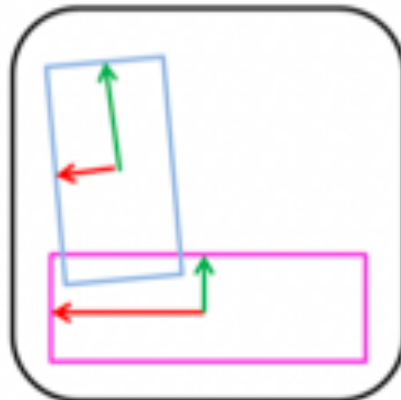
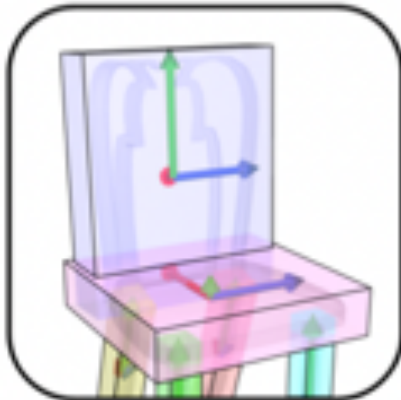
Static vs. dynamic



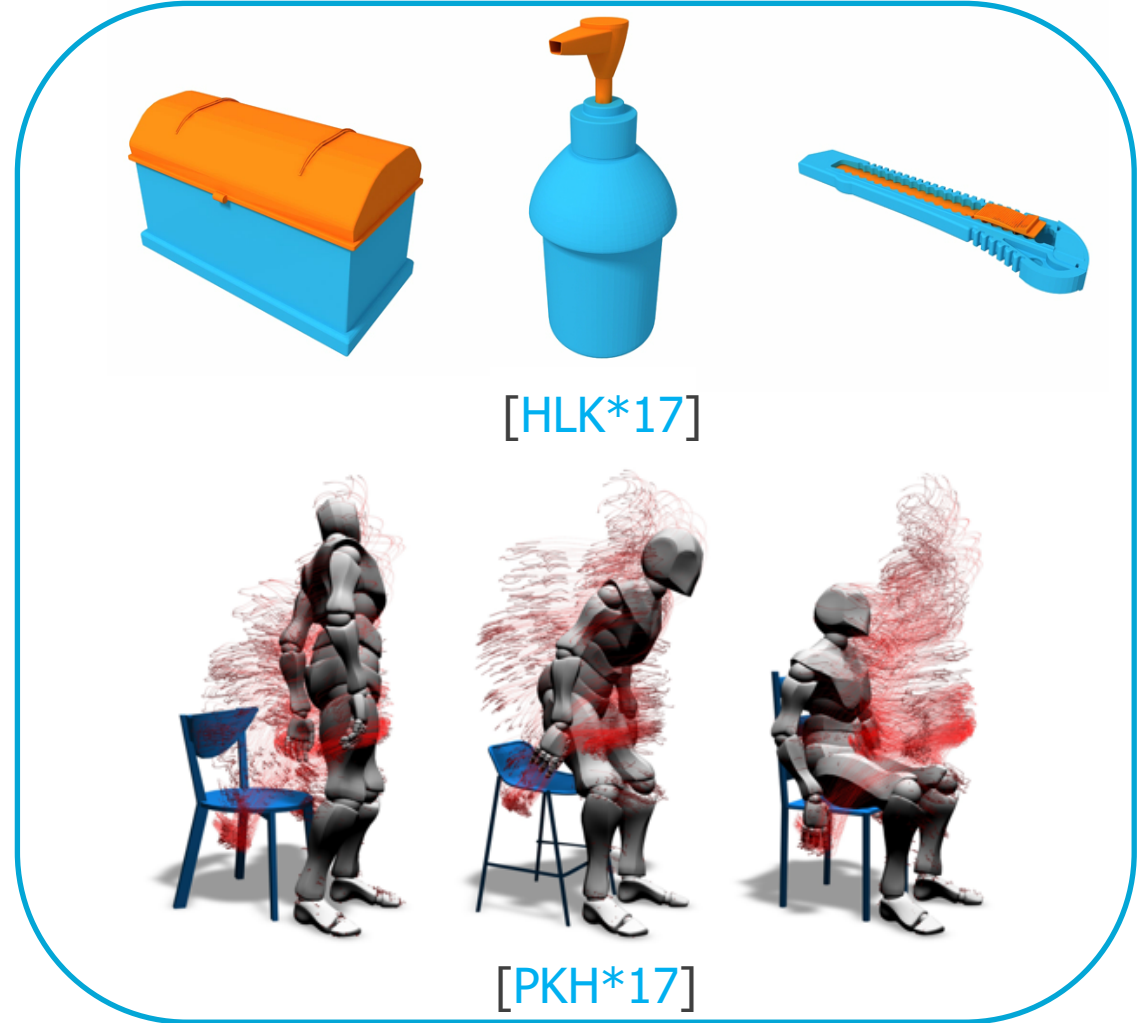
[WXL*11]



[FSL*15]



[FAvK*14]

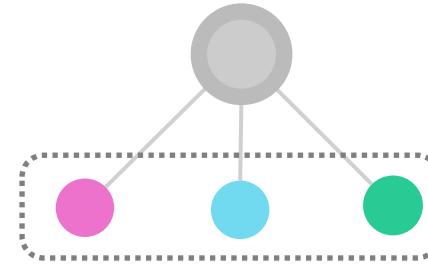


[HLK*17]

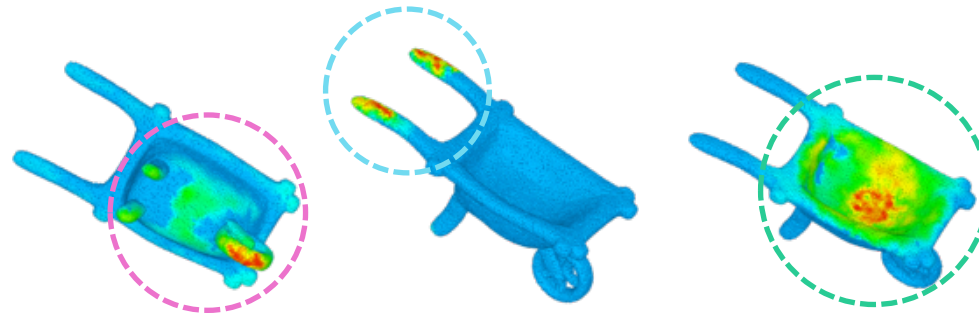
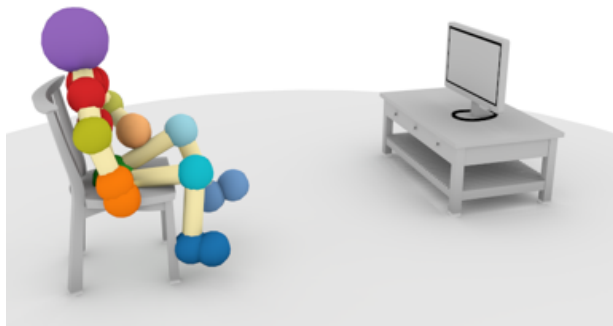
[PKH*17]

Real data collection?

Handcrafted vs. data-driven

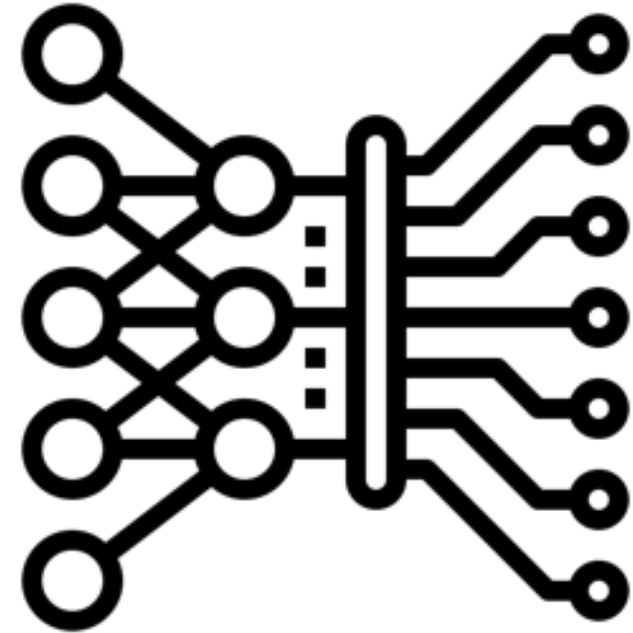
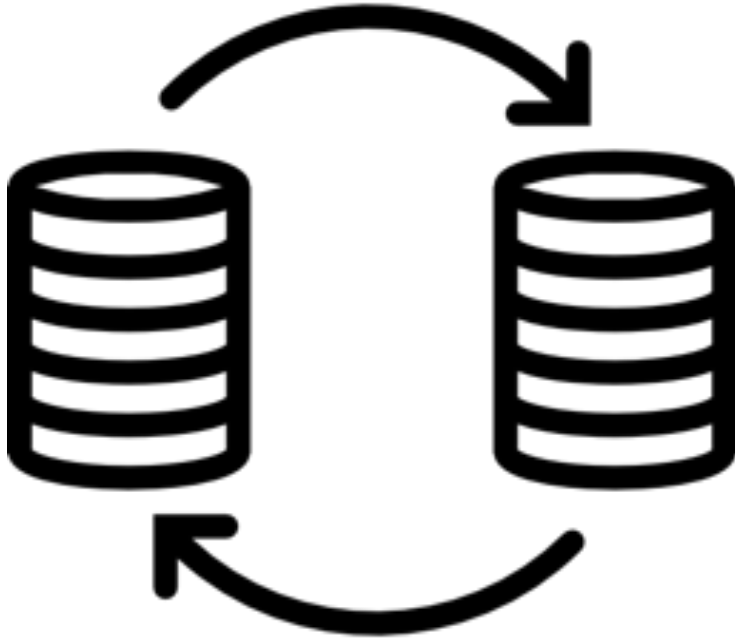


**prior
knowledge**



**handcrafted
features**

Handcrafted vs. data-driven



Large-scale 3D functionality dataset

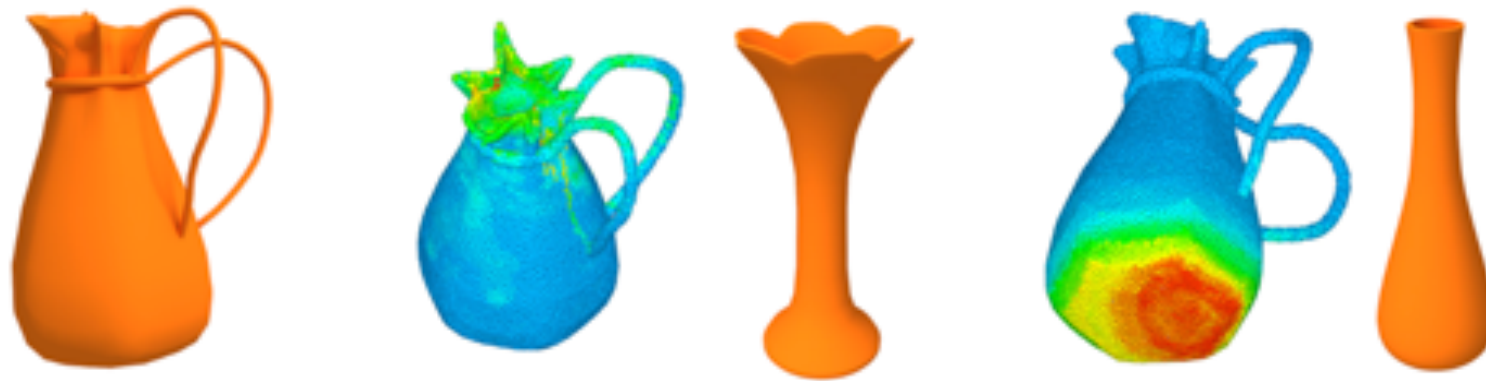
[Image source: Icons made by Pause08 www.flaticon.com]

Machine learning advances

[Image source: Icons made by Becris www.flaticon.com]

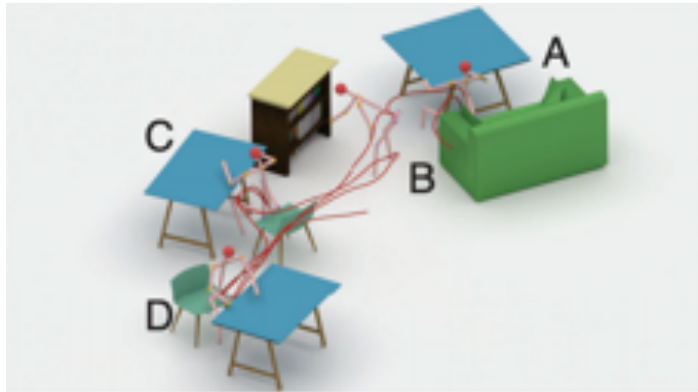
Beyond geometry

- Materials for physical reasoning
- Acoustic properties for sound-based functions



Emerging applications

- Functionality-guided scene synthesis
- Functionality-driven AR/VR
- Functionality-driven interactive 3D simulation



[MGC*19]

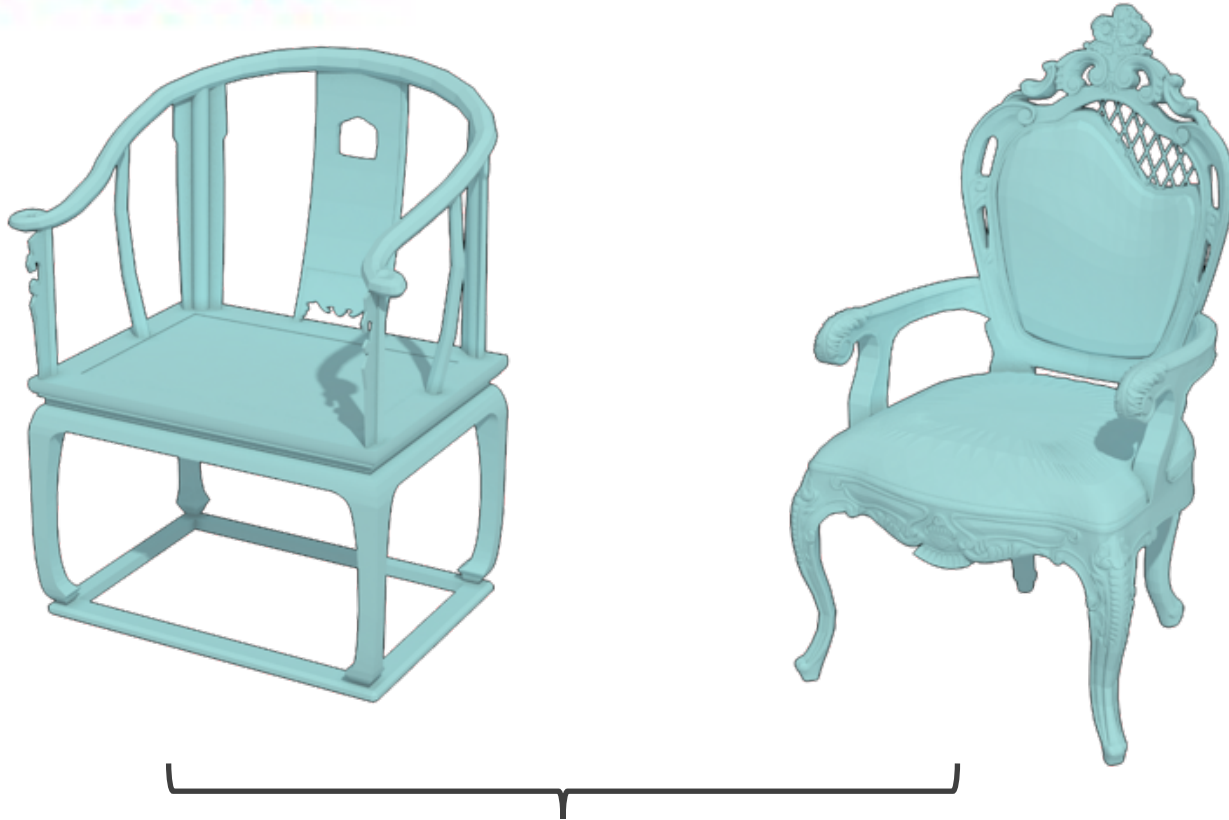


[image source:
<https://commons.wikimedia.org/wiki/File:Augmented-reality.jpg>]



[XQM*20]

Full understanding of 3D shape



Same functionality

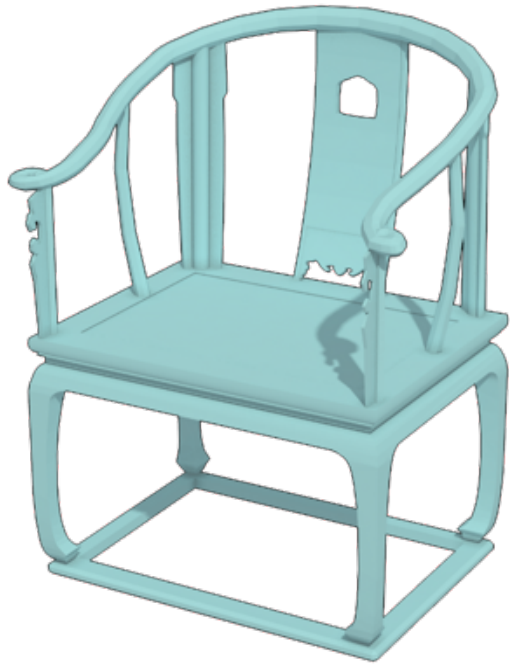
Material

Weight

Size

⋮

Full understanding of 3D shape



Same functionality

Same style

“Grand challenge”

- Model covering a range of functionality aspects
 - Human-object
 - Object-object
 - Dynamic settings
 - Physical properties
 - ...
- Use the model for analysis and synthesis
- E.g., realistic shape and scene synthesis

Conclusion



Summary

- Comprehensive survey of work on functionality
- Definition of functionality: geometry + interaction
- Three classes of methods:
geometry-only, geometry + interaction, geometry + agent
- Factorization into intrinsic and extrinsic properties

Limitations

- Functionality definition is not complete or perfect
- What are other ways of encoding functionality?
- What are the fundamental properties of parts, objects, scenes?
- Key question: form from function or function from form?

Thank you!

- Reasoning about functionality is ubiquitous
- Emerging connections between applications in graphics, vision, robotics, and AI
- Check out the course website for more information and for our contact details!

<https://learn3dfunc.github.io/>